



Automated Derivation of Polyhedral Process Networks

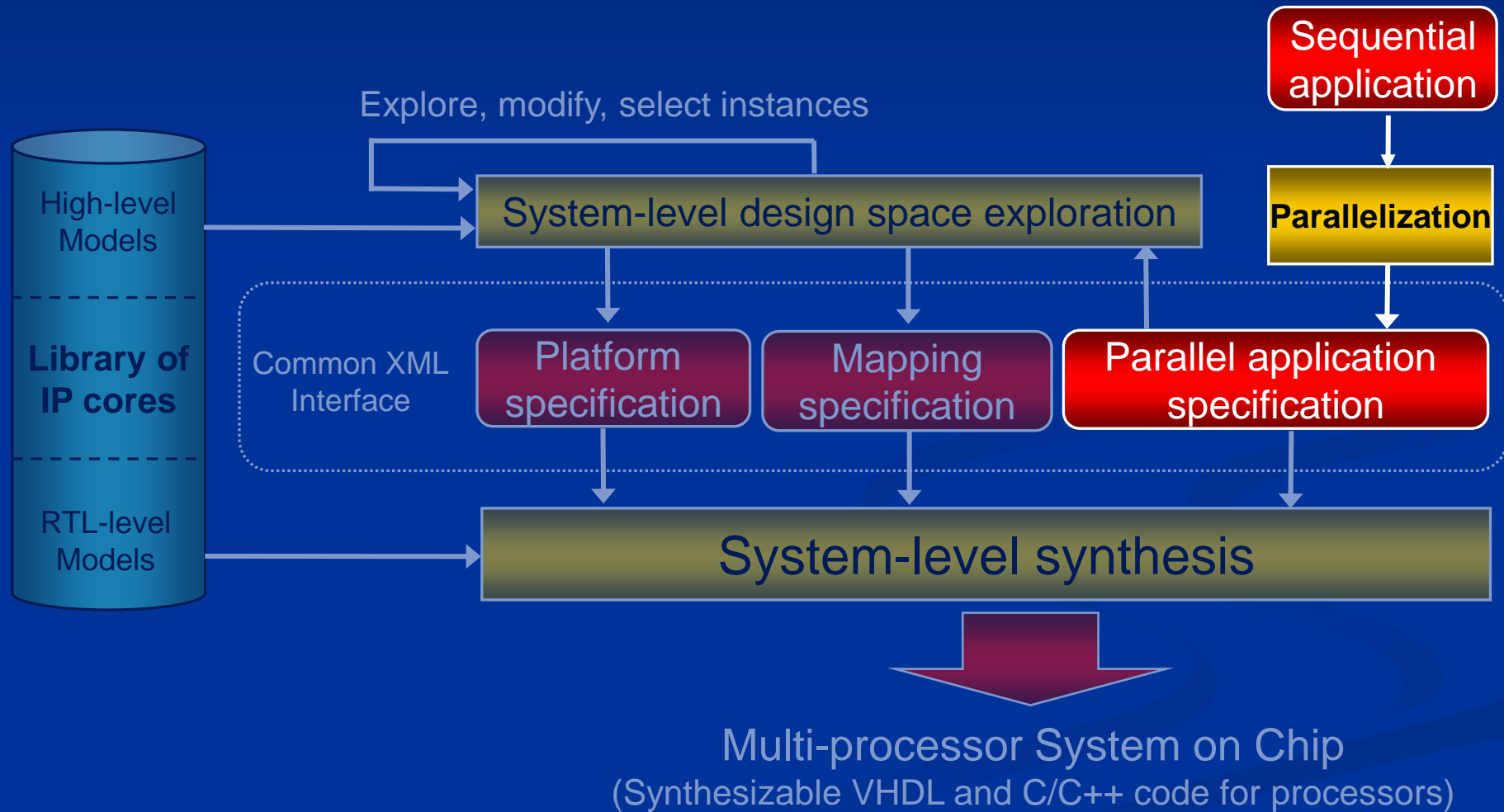
Todor Stefanov

Leiden Embedded Research Center,
Leiden Institute of Advanced Computer Science
Leiden University, The Netherlands



Universiteit Leiden

Automated Parallelization: PNgen tool



Programming problem

EASY to specify

Static Affine
Nested Loop Programs

```
for j = 1:1:N,  
  [x(j)] = Source1();  
end  
for i = 1:1:K,  
  [y(i)] = Source2();  
end  
for j = 1:1:N,  
  for i = 1:1:K,  
    [y(i), x(j)] = F(y(i), x(j));  
  end  
end  
for i = 1:1:K,  
  [Out(i)] = Sink(y(i));  
end
```

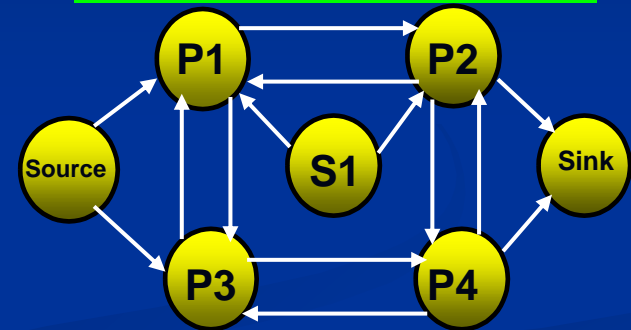
DIFFICULT to map

Application

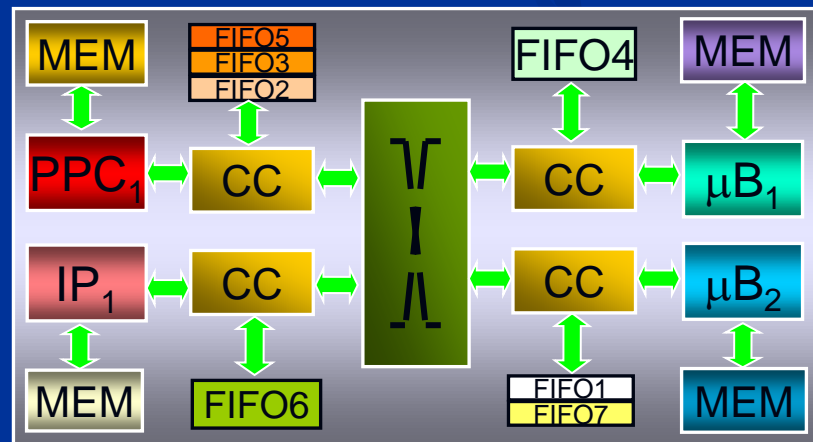
PNgen tool

DIFFICULT to specify

Polyhedral
Process Networks



EASY to map



ESPAM tool

Static Affine Nested Loop Programs

- Restrictions to top-level program code
 - Parameters are **symbolic constants**, i.e., do not change at run-time
 - **Only FOR-loops** with **bounds that are affine functions** of other loops' indices and parameters
 - **Only If-statements** with **conditions that are affine functions** of loops' indices and parameters
 - **Only Explicit data exchange** via arrays or scalars (*NO pointers*)
 - **Arrays are indexed with affine functions** of loops' indices and parameters
- NO restrictions for code in function calls

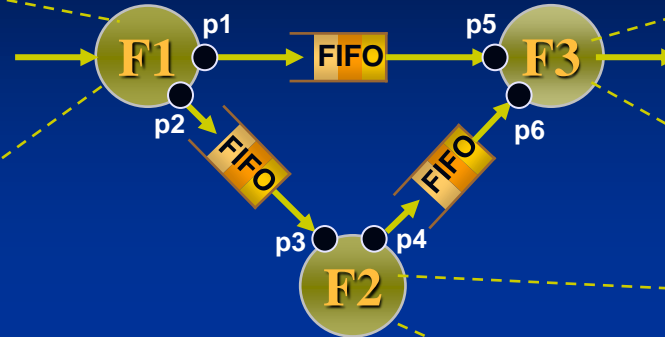
```
int N = 10;
#pragma parameter N 5 100
int main(void) {
    int i, j, k;
    MyType A[600];

    for ( k = 1; k <= 6*N-3; k++ ) {
        A[k] = Func1( );
    }

    for ( j = 1; j <= N; j++ ) {
        for ( i = j; i <= 3*j - 2; i++ ) {
            if ( i + j <= 4*N - 6 ) {
                A[i] = Func2( A[2*i-1], A[2*i+1]);
            }
            Func3( A[i] );
        }
    }
}
```

Polyhedral Process Networks (1)

```
int M = 10, P = 3;  
for( i=1; i <= M; i++) {  
  out = F1( );  
  if( i <= P)  
    write( p2, out );  
  else  
    write( p1, out );  
}
```



```
int N = 10, P = 3;  
for( j=1; j <= N; j++) {  
  if( j <= P)  
    in = read( p6 );  
  else  
    in = read( p5 );  
  F3( in );  
}
```

```
int P = 3;  
for( j=1; j <= P; j++) {  
  in = read( p3 );  
  out = F2( in );  
  write( p4, out );  
}
```

- Simple formalism to express concurrency
 - Autonomously running processes
 - Communicating via bounded FIFOs
 - Synchronization via blocking read/write
- Deterministic
 - For one and the same input, one and the same output is produced, irrespective of the execution order of processes
- Distributed Control
 - no global schedule needed

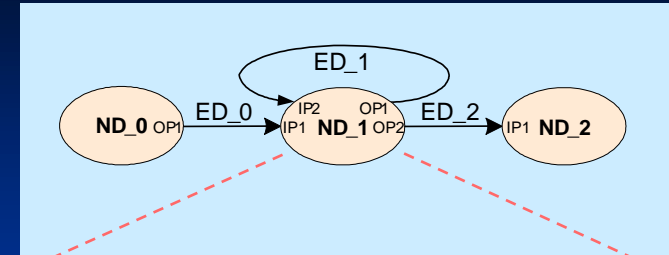
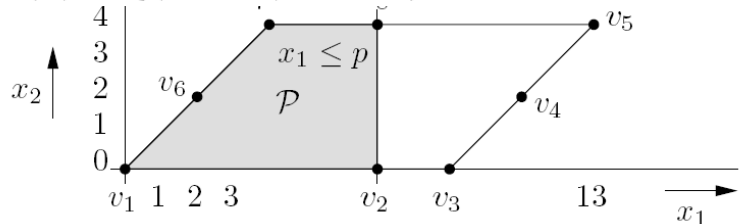
Polyhedral Process Networks (2)

- Well defined structure of a process
 - Separate READ - EXECUTE - WRITE code sections
 - CONTROL – determines the number of iterations/firings of a process
- Every Process, Input and Output Port can be represented as Parameterized Polyhedrons
- Parameterized Polyhedron

$$\mathcal{P}(\mathbf{p}) = \{ \mathbf{x} \in \mathbb{Q}^n \mid \mathbf{A}\mathbf{x} = \mathbf{B}\mathbf{p} + \mathbf{b} \wedge \mathbf{C}\mathbf{x} \geq \mathbf{D}\mathbf{p} + \mathbf{d} \}$$

- Set of points \mathbf{x} in the n -dimensional space satisfying some affine constraints
- $\mathbf{p} \in \mathbb{Q}^m$ is a vector of parameters

$$\mathcal{P}(p) = \{ (x_1, x_2) \in \mathbb{Q}^2 \mid 0 \leq x_2 \leq 4 \wedge x_2 \leq x_1 \leq x_2 + 9 \wedge x_1 \leq p \wedge p \leq 40 \}$$

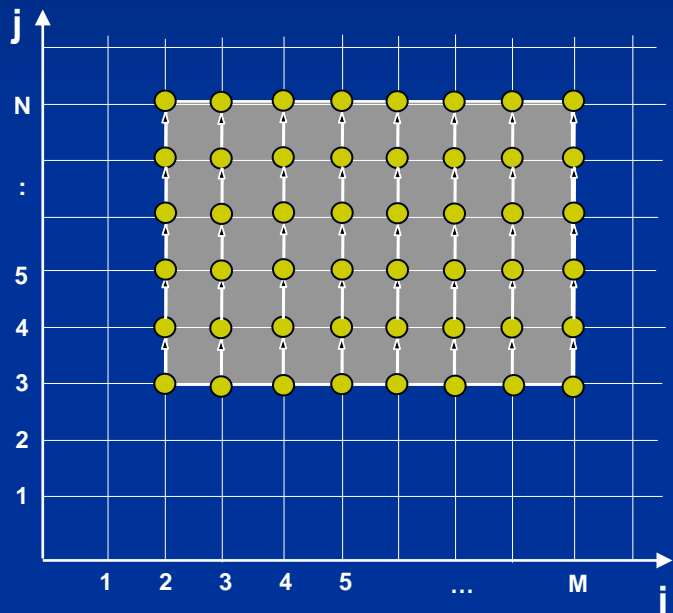


```

1 // process ND_1
2 void main() {
3   for( int i=2; i<=M; i++ )           CONTROL
4     for( int j=2; j<=N; j++ ) {
5       if( j-2 == 0 )
6         read( IP1, in_0 );           READ
7       if( j-3 >= 0 )
8         read( IP2, in_0 );
9       Transformer( in_0, out_0 );    EXECUTE
10      if( -j+N-1 >= 0 )
11        write( OP1, out_0 );         WRITE
12      if( j-N == 0 ) {
13        write( OP2, out_0 );
14      } // for j
15 } // main
    
```

Polyhedral Process Networks (3)

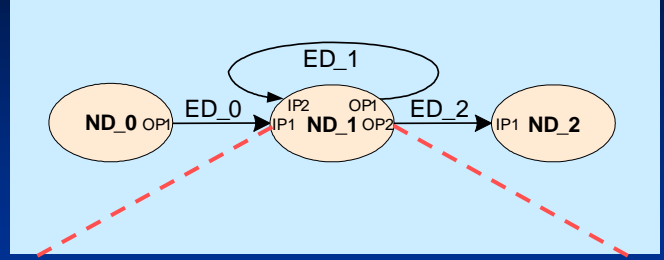
- Example: Input port IP2 as parameterized polyhedron



$$\begin{aligned} 2 \leq i \leq M, \\ 2 \leq j \leq N, \\ j - 3 \geq 0 \end{aligned}$$

$$\begin{aligned} 2 \leq i \leq M, \\ 3 \leq j \leq N, \end{aligned}$$

$$P(M, N) = \left\{ (i, j) \in \mathbb{Z}^2 \mid \begin{bmatrix} 1 & 0 \\ -1 & 0 \\ 0 & 1 \\ 0 & -1 \end{bmatrix} * \begin{pmatrix} i \\ j \end{pmatrix} \geq \begin{bmatrix} 0 & 0 \\ -1 & 0 \\ 0 & 0 \\ 0 & -1 \end{bmatrix} * \begin{pmatrix} M \\ N \end{pmatrix} + \begin{pmatrix} 2 \\ 0 \\ 3 \\ 0 \end{pmatrix} \right\}$$



```

1 // process ND_1
2 void main() {
3   for( int i=2; i<=M; i++ )
4     for( int j=2; j<=N; j++ ) {
5
6       if( j-2 == 0 )
7         read( IP1, in_0 );
8         read( IP2, in_0 );
9
10      Transformer( in_0, out_0 );
11
12      if( -j+N-1 >= 0 )
13        write( OP1, out_0 );
14      } // for j
15 } // main

```

Deriving Polyhedral Process Network

Sequential Program

Dependence Analysis

```
int N = 5;
#pragma parameter N 4 16;
Int K = 100;
#pragma parameter K 100 1000;
...
for( k=1; k<=K; k++ )
  for( j=1; j<=N; j++ ) {
    t = C( r[j][j], x[k][j], &r[j][j], &x[k][j] );
    for( i = j+1; i<=N; i++ ) {
      t = D( t, r[j][i], x[k][i], &r[j][i], &x[k][i] );
    }
  }
...

```

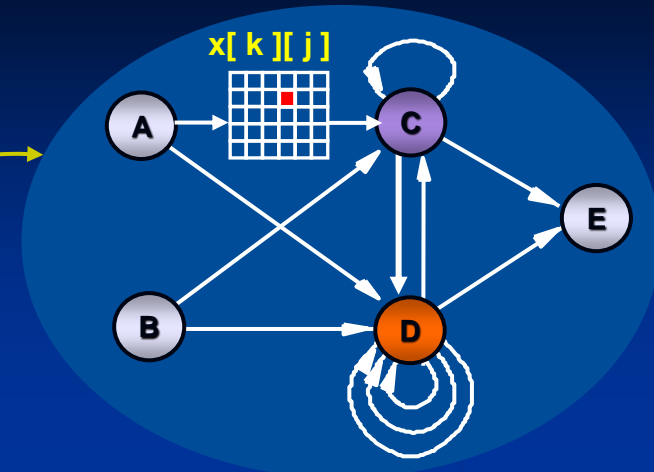
SAC or PDG

Linearization

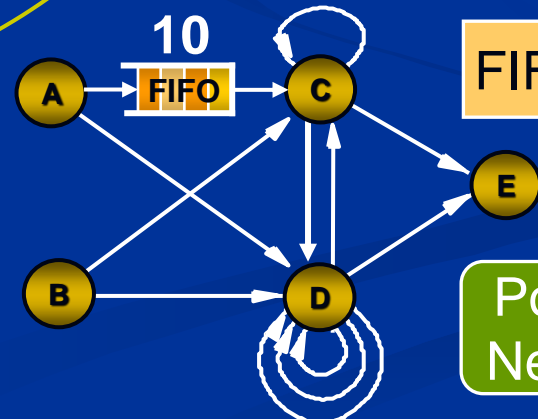
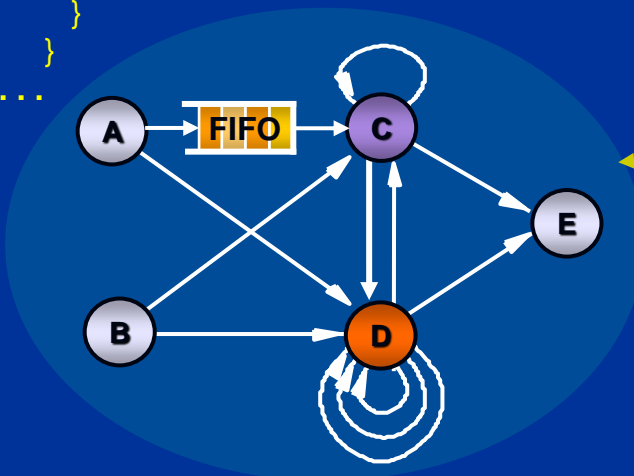
Polyhedral Process Network

FIFO size calculation

Polyhedral Process Network (optimized)



Polyhedral Dependence Graph

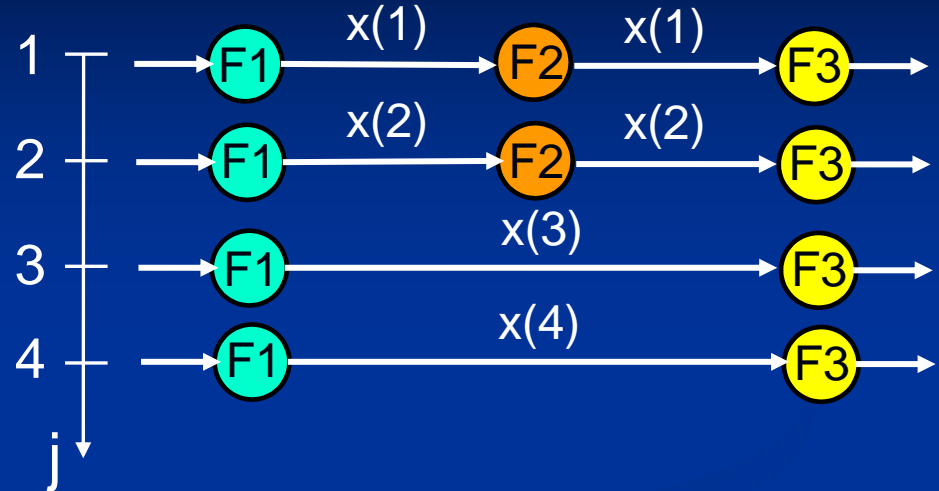


Dependence Analysis (1)

Static affine program

```
for j = 1:1:4,  
    [x(j)] = F1( ... );  
end  
for j = 1:1:4,  
    if j <= 2,  
        [x(j)] = F2( x(j) );  
    end  
    [...] = F3( x(j) );  
end
```

Dependence Graph (DG)



Exact Array Dataflow Analysis

Q: Given a read from an array element, what was the last write to that array element?

Example: given a read $\langle F3 @ j=2 \rangle$ from $x(2)$ what was the last write $\langle F? @ j=? \rangle$ to $x(2)$

A: Can be computed using Parametric Integer Programming (PIP)

\Rightarrow finds parametric lexicographically maximal element of a set bounded by linear constraints

Dependence Analysis (2)

Static affine program

```
for j = 1:1:4,  
  [x(j)] = F1( ... );  
end  
for j = 1:1:4,  
  if j <= 2,  
    [x(j)] = F2( x(j) );  
  end  
  [...] = F3( x(j) );  
end
```



Dependence analysis for $F3 \leftarrow F2$

subject to: $1 \leq j_W \leq 4$

$j_W \leq 2$

$j_W = j_R$

$1 \leq j_R \leq 4$

objective: $j_W^{\max} = \max_{lex} \{ j_W(j_R) \}$



PIP Solution:

```
if (  $j_R \leq 2$  ) then  $j_W = j_R$   
  else no solution;
```

Meaning of the Solution:

```
if (  $j_R \leq 2$  ) then  
  <F3 @  $j_R$ > depends on <F2 @  $j_W = j_R$ > via variable  $X(j_W = j_R)$   
else  
  <F3 @  $j_R$ > depends on other functions
```

Dependencies expressed as SSAC

Static affine program

```
for j = 1:1:4,  
    [x(j)] = F1( ... );  
end  
for j = 1:1:4,  
    if j <= 2,  
        [x(j)] = F2( x(j) );  
    end  
    [...] = F3( x(j) );  
end
```

Static Single Assignment Code

```
for j = 1:1:4,  
    [x_1(j)] = F1( ... );  
end  
for j = 1:1:4,  
    if j <= 2,  
        [x_2(j)] = F2( x_1(j) );  
    end  
    if j <= 2,  
        in_0 = x_2(j);  
    else  
        in_0 = x_1(j);  
    end  
    [...] = F3( in_0 );  
end
```

Properties of SSAC:

- every variable is written only once
- expose all dependencies

Exact Array
Dataflow Analysis

Meaning of the Solution:

```
if (  $j_R \leq 2$  ) then  
    <F3 @  $j_R$ > depends on <F2 @  $j_W = j_R$ > via variable  $X(j_W = j_R)$   
else  
    <F3 @  $j_R$ > depends on other functions
```

Dependencies expressed as PDG

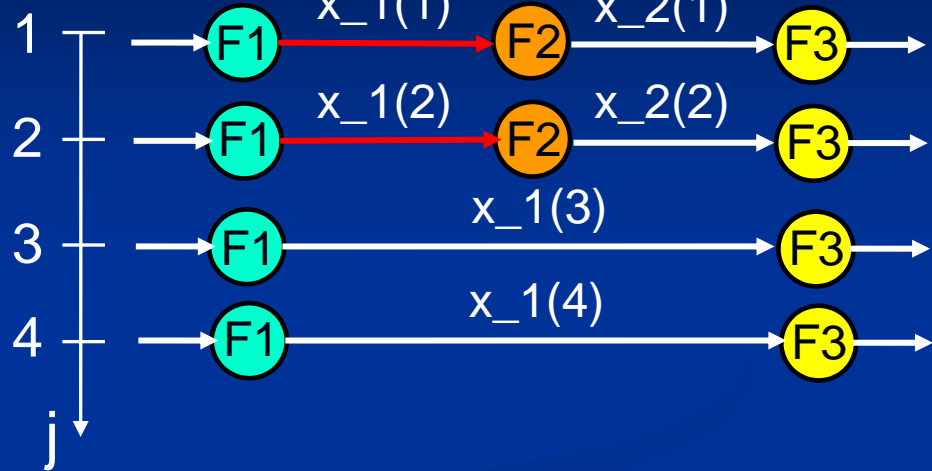
Static Single Assignment Code

```

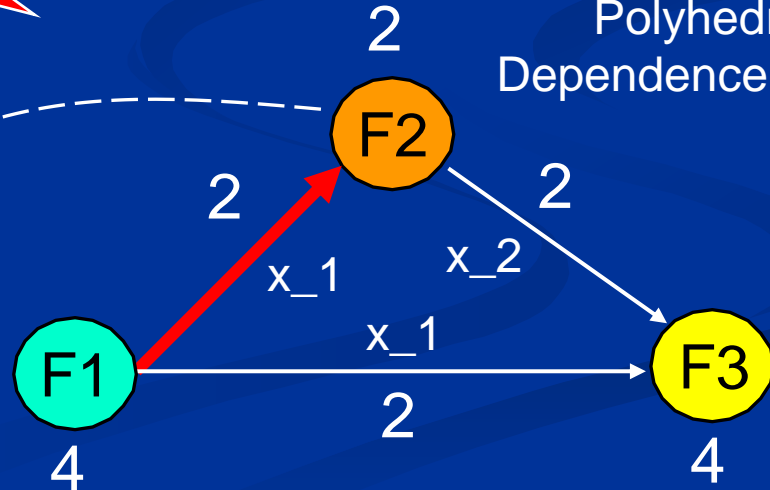
for j = 1:1:4,
  [x_1(j)] = F1( ... );
end
for j = 1:1:4,
  if j <= 2,
    [x_2(j)] = F2( x_1(j) );
  end
  if j <= 2,
    in_0 = x_2(j);
  else
    in_0 = x_1(j);
  end
  [...] = F3( in_0 );
end
    
```

unroll

Dependence Graph (DG)



Polyhedral Dependence Graph



Polyhedral annotation:
 $P_{F2} = \{j \in Z \mid 1 \leq j \leq 2\} = \{1,2\}$

Deriving Polyhedral Process Networks

Sequential Program

Dependence Analysis

```
int N = 5;  
#pragma parameter N 4 16;  
Int K = 100;  
#pragma parameter K 100 1000;
```

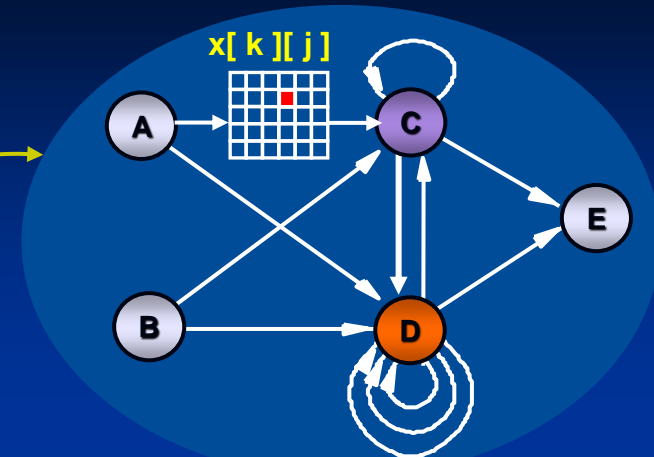
...

```
for( k=1; k<=K; k++ )  
  for ( j=1; j<=N; j++ ) {  
    t = C( r[j][j], x[k][j], &r[j][j], &x[k][j] );  
    for( i = j+1; i<=N; i++ ) {  
      t = D( t, r[j][i], x[k][i], &r[j][i], &x[k][i] );  
    }  
  }  
...
```

SAC or PDG

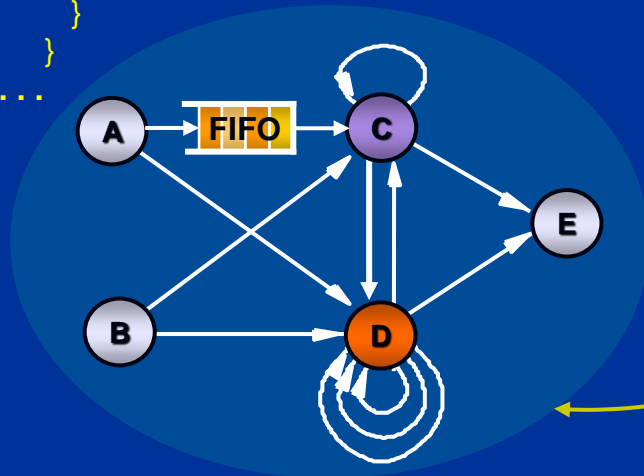
Linearization

Polyhedral Process Network



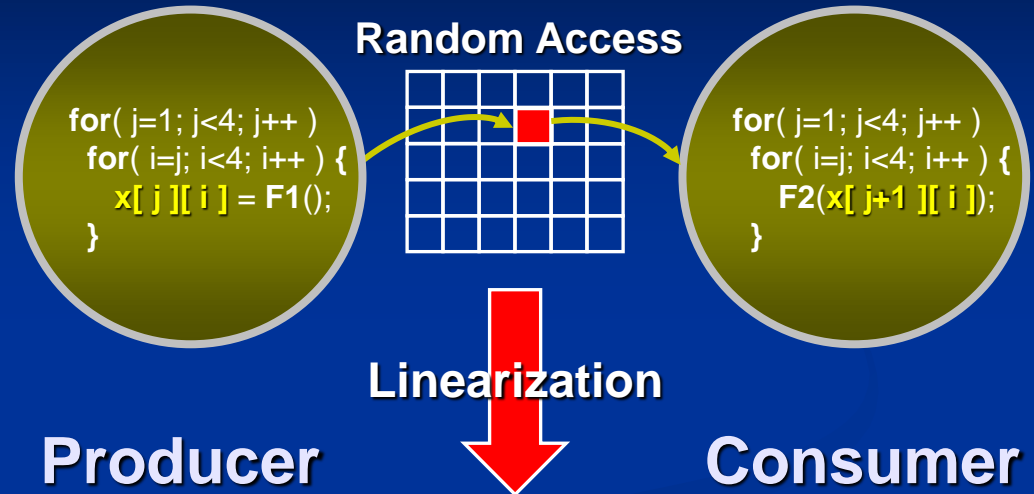
Polyhedral Dependence Graph

Dependencies via n-dimensional arrays with random access!!!

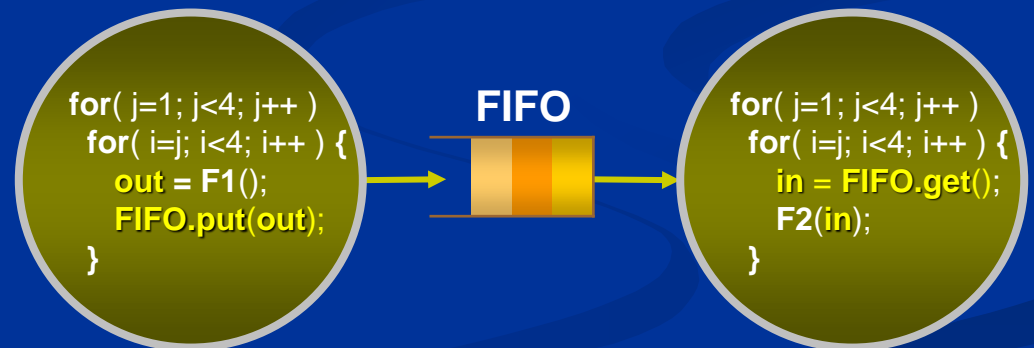


Linearization

- **Linearization:** mapping high-order data-structures, e.g., N-dimensional array onto 1-dimensional stream



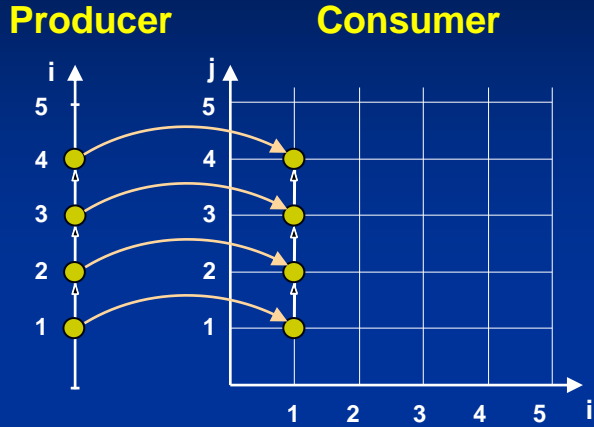
- Indexing of $x(j,i)$ and $x(j+1,i)$ is replaced by relative **put** and **get** operation on a FIFO buffer



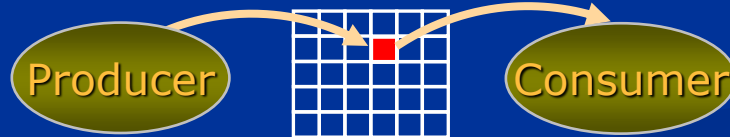
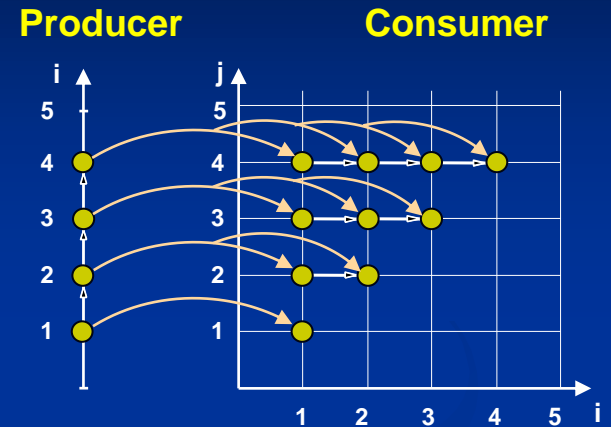
What is actually the problem? Is Linearization always possible?

Possible Communication Scenarios

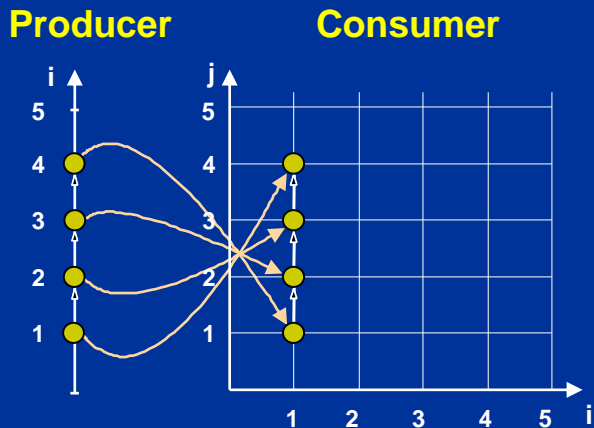
In-order



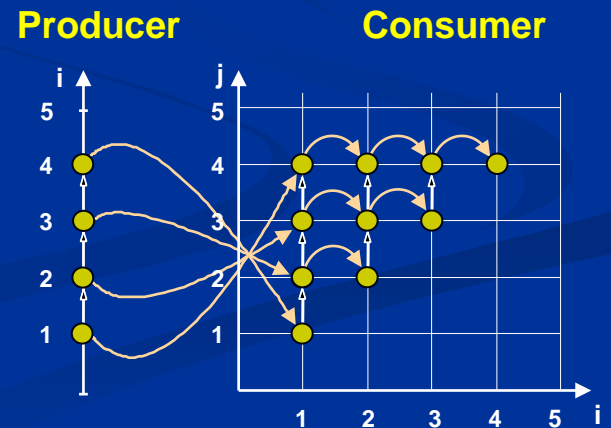
In-order with multiplicity



Out-of-order



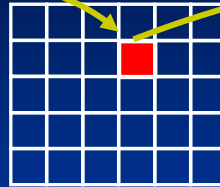
Out-of-order with multiplicity



In-order Communication

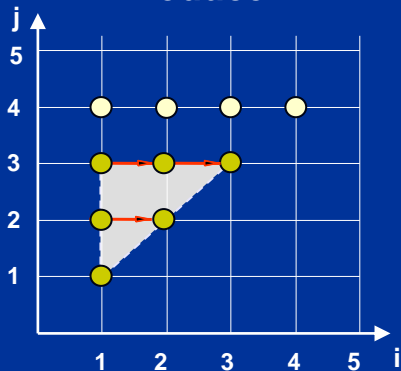
```
for( j=1; j<4; j++ )
  for( i=1; i<=j; i++ ) {
    x[j][i] = F1();
  }
```

$X[j][i]$



```
for( j=2; j<5; j++ )
  for( i=1; i<j; i++ ) {
    F2(x[j-1][i]);
  }
```

Producer

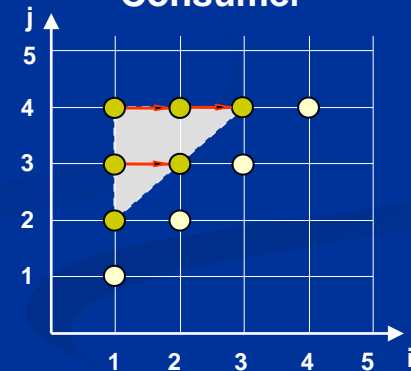


The sequence in which the data is produced

(1,1) (2,1) (2,2) (3,1) (3,2) (3,3)
 $X[1][1]$ $X[2][1]$ $X[2][2]$ $X[3][1]$ $X[3][2]$ $X[3][3]$
 (2,1) (3,1) (3,2) (4,1) (4,2) (4,3)

The sequence in which the data is consumed

Consumer



```
for( j=1; j<4; j++ )
  for( i=1; i<=j; i++ ) {
    out = F1();
    FIFO.put(out);
  }
```



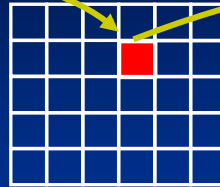
```
for( j=2; j<5; j++ )
  for( i=1; i<j; i++ ) {
    in = FIFO.get();
    F2(in);
  }
```

If data is consumed in the same order as it was produced, N-dimensional array CAN be safely replaced by FIFO

Out-of-order Communication

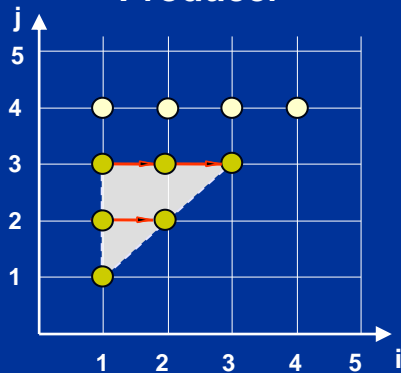
```
for( j=1; j<4; j++ )
  for( i=1; i<=j; i++ ) {
    x[j][i] = F1();
  }
```

$X[j][i]$



```
for( i=1; i<4; i++ )
  for( j=i+1; j<5; j++ ) {
    F2(x[j-1][i]);
  }
```

Producer



The sequence in which the data is produced

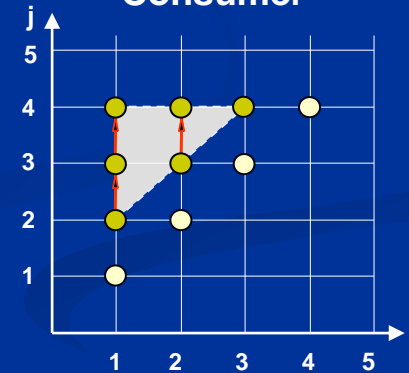
(1,1) (2,1) (2,2) (3,1) (3,2) (3,3)

$X[1][1]$ $X[2][1]$ $X[2][2]$ $X[3][1]$ $X[3][2]$ $X[3][3]$

(2,1) (3,1) (4,1) (3,2) (4,2) (4,3)

The sequence in which the data is consumed:

Consumer



Observation: Data $X[3][1]$ is produced *after* data $X[2][2]$
BUT

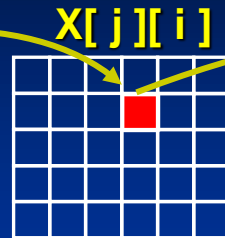
Data $X[3][1]$ is consumed *before* data $X[2][2]$

If data is consumed in different order than it was produced,
N-dimensional array CAN NOT be replaced by a simple FIFO

Implementing Out-of-Order

```
for( j=1; j<4; j++ )  
  for( i=1; i<=j; i++ ) {  
    x[j][i] = F1();  
  }
```

Producer

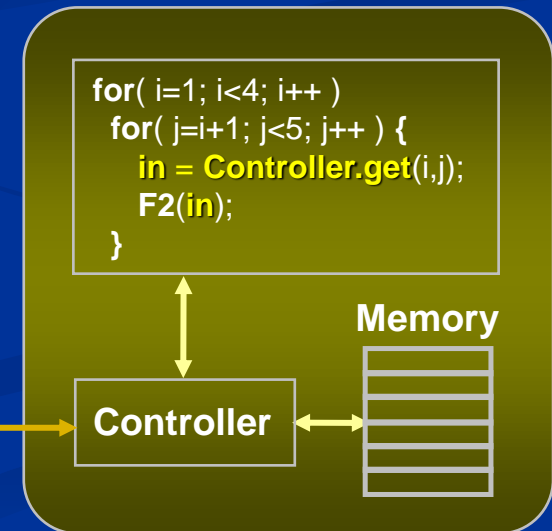


```
for( i=1; i<4; i++ )  
  for( j=i+1; j<5; j++ ) {  
    F2(x[j-1][i]);  
  }
```

Consumer

- The data is reordered at the consumer
 - Option1:
 - Simple FIFO
 - Reordering Controller
 - Reordering Memory
 - Option2:
 - Window FIFO
 - Reordering Controller

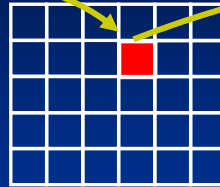
```
for( j=1; j<4; j++ )  
  for( i=1; i<=j; i++ ) {  
    out = F1();  
    FIFO.put(out);  
  }
```



Identifying Out-of-Order (1)

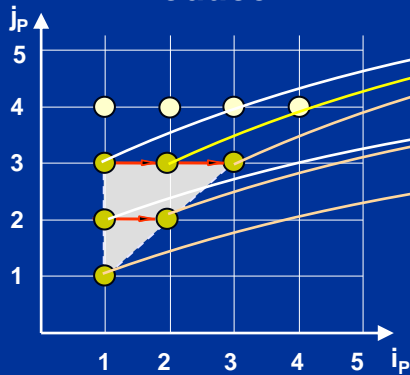
```
for( j=1; j<4; j++ )
  for( i=1; i<=j; i++ ) {
    x[j][i] = F1();
  }
```

$x[j][i]$

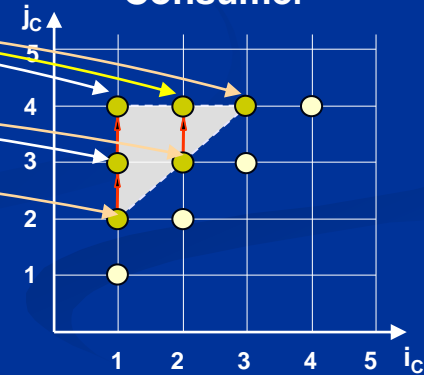


```
for( i=1; i<4; i++ )
  for( j=i+1; j<5; j++ ) {
    F2(x[j-1][i]);
  }
```

Producer



Consumer

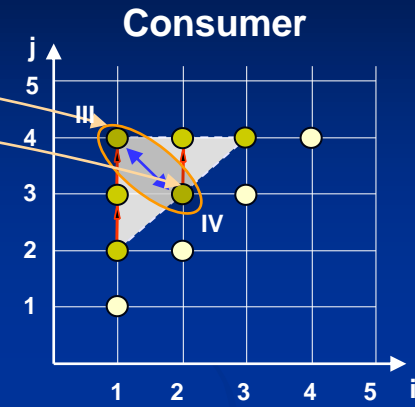
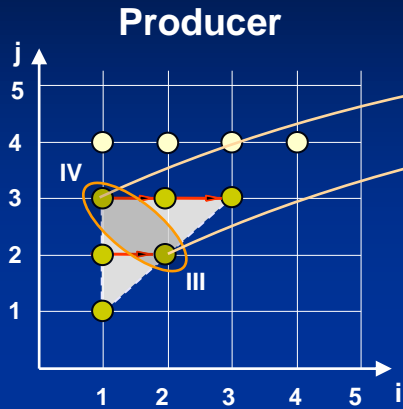


Observation: $j_p = j_c - 1$
 $i_p = i_c$

$$(j_p, i_p) = M(j_c, i_c)$$

In general, mapping function M exists for any producer-consumer pair

Identifying Out-of-Order (2)



$$(j_p, i_p) = M(j_c, i_c)$$



Reordering Integer Linear Problem

$$\begin{aligned}
 & i_c^1 < j_c^1 \leq 4 \\
 & 1 \leq i_c^1 \leq 3 \\
 & i_c^2 < j_c^2 \leq 4 \\
 & 1 \leq i_c^2 \leq 3 \\
 & (j_c^1, i_c^1) <_{\text{lex}} (j_c^2, i_c^2) \\
 & M(j_c^1, i_c^1)_{\text{lex}} > M(j_c^2, i_c^2)
 \end{aligned}$$

Mapped 2 points in Producer:

$$(j_p^1, i_p^1) = M(j_c^1, i_c^1)$$

$$(j_p^2, i_p^2) = M(j_c^2, i_c^2)$$

Any 2 points in Consumer:

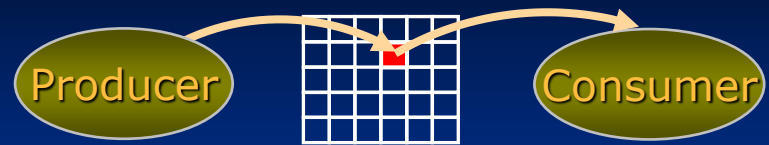
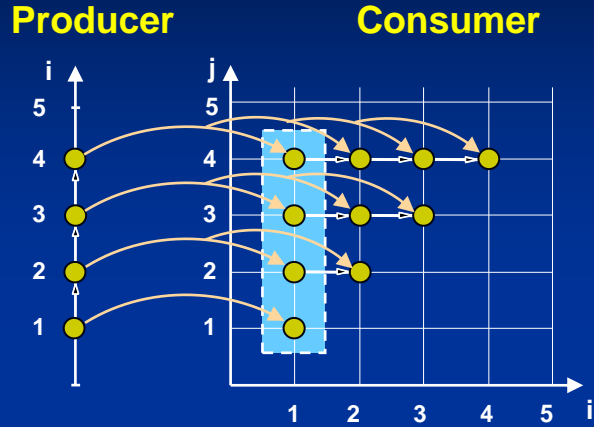
$$(j_c^1, i_c^1)$$

$$(j_c^2, i_c^2)$$

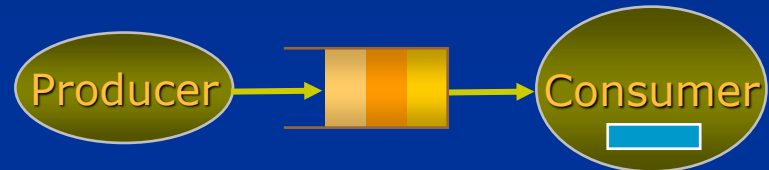
IF *Reordering Problem has a solution* THEN *Out-of-Order communication*
 ELSE *In-Order communication*

Multiplicity

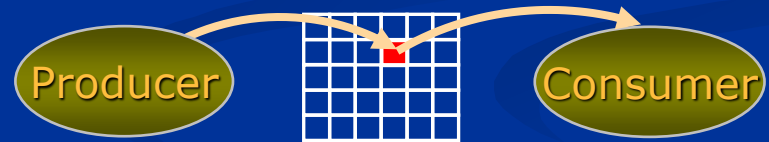
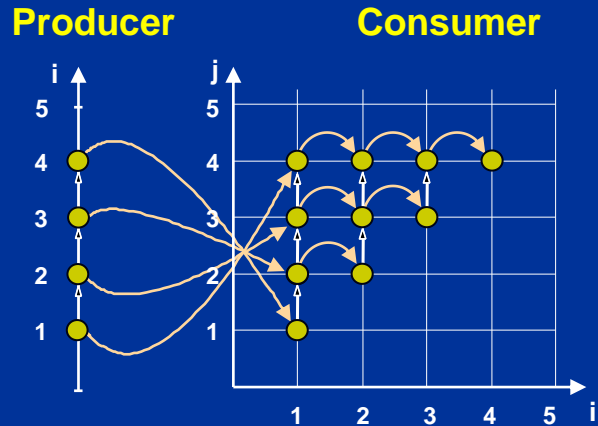
In-order with multiplicity



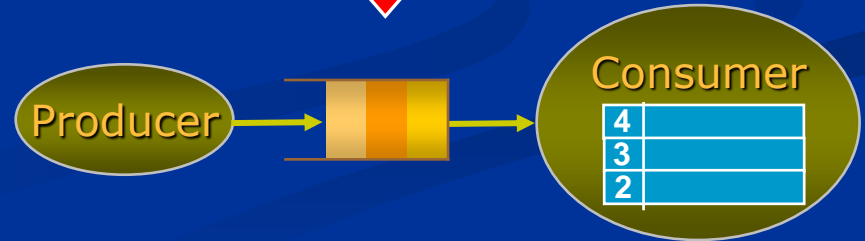
Linearization



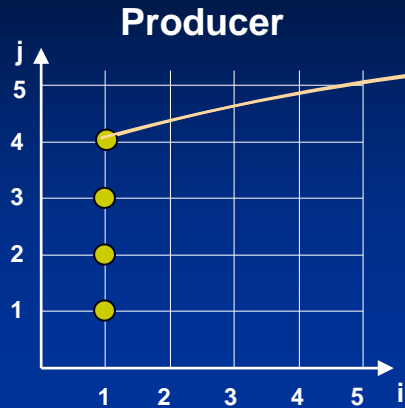
Out-of-order with multiplicity



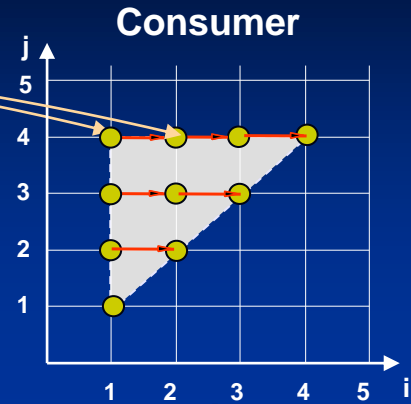
Linearization



Identifying Multiplicity



$$(j_p, i_p) = M(j_c, i_c)$$



Multiplicity Integer Linear Problem

$$1 \leq j_c^1 \leq 4$$

$$1 \leq i_c^1 \leq j_c^1$$

$$1 \leq j_c^2 \leq 4$$

$$1 \leq i_c^2 \leq j_c^2$$

$$(j_c^1, i_c^1) \neq (j_c^2, i_c^2)$$

$$M(j_c^1, i_c^1) = M(j_c^2, i_c^2)$$

Any 2 points in
Consumer:

$$(j_c^1, i_c^1)$$

$$(j_c^2, i_c^2)$$

Mapped 2 points in
Producer:

$$(j_p^1, i_p^1) = M(j_c^1, i_c^1)$$

$$(j_p^2, i_p^2) = M(j_c^2, i_c^2)$$

IF Multiplicity Problem has a solution **THEN** there is **Multiplicity**

Deriving Polyhedral Process Networks

Sequential Program

Dependence Analysis

```
int N = 5;
#pragma parameter N 4 16;
Int K = 100;
#pragma parameter K 100 1000;
...
for( k=1; k<=K; k++)
  for( j=1; j<=N; j++) {
    t = C( r[j][j], x[k][j], &r[j][j], &x[k][j] );
    for( i=j+1; i<=N; i++) {
      t = D( t, r[j][i], x[k][i], &r[j][i], &x[k][i] );
    }
  }
...

```

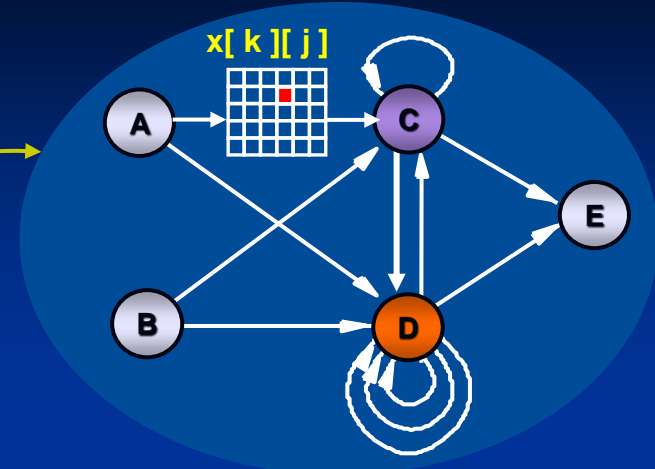
SAC or PDG

Linearization

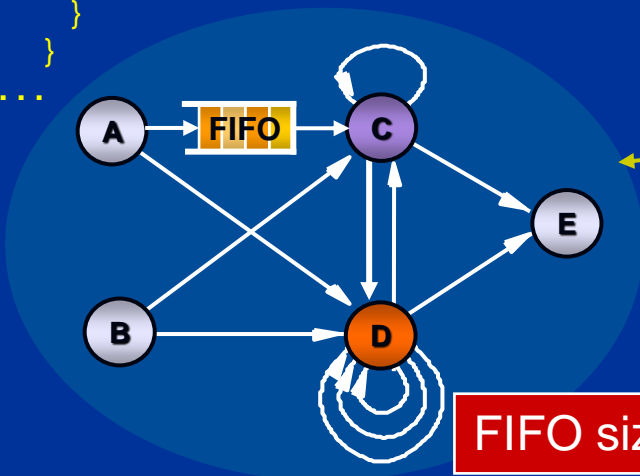
Polyhedral Process Network

FIFO size calculation

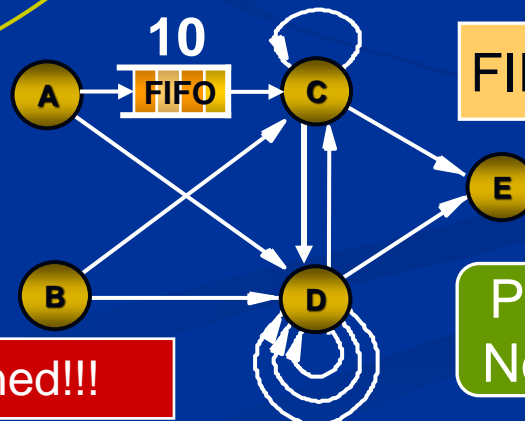
Polyhedral Process Network (optimized)



Polyhedral Dependence Graph

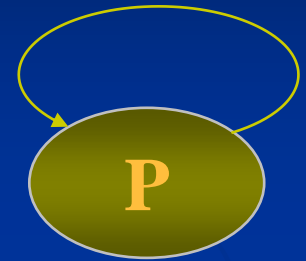


FIFO sizes undefined!!!



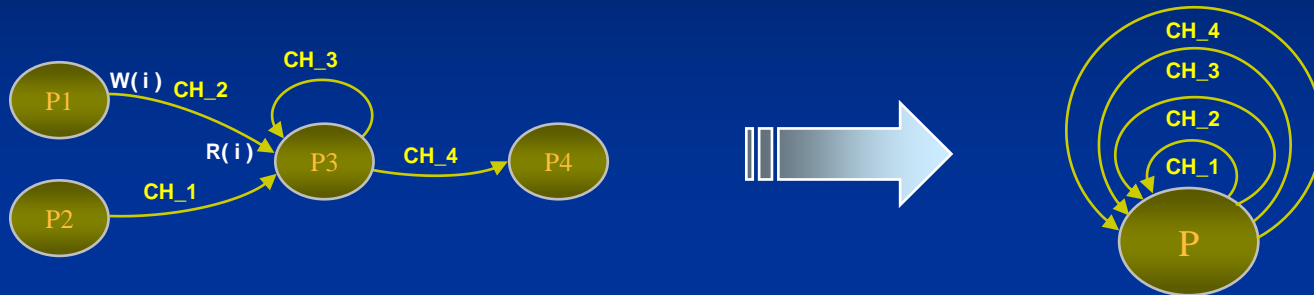
FIFO sizes calculation (1)

- What is the maximum amount of data in a **self-loop FIFO** channel?
- For every given process firing i :
 - number of elements written before i : $W(i)$
 - number of elements read before i : $R(i)$
 - number of elements in FIFO at i : $W(i) - R(i)$
- Find $\max(W(i) - R(i))$ over all firings i
- How to compute $\max(W(i) - R(i))$?
 - parametric PPNs: symbolically, using *Barvinok* library
 - $W(i)$ and $R(i)$ are *Ehrhart polynomials*
 - The maximum is found by Bernstein expansions
 - non-parametric PPNs: symbolically or simulate the channels – code generation, using *CLoog*



FIFO sizes calculation (2)

- What is the maximum amount of data in a **FIFO** channel?



Relative execution order of different processes not known a priori

- Schedule is needed:
 - Put all processes in a common iteration space i
 - Offset the processes such that the dependences are respected
 - Try to find minimum offsets \rightarrow helps to minimize the FIFO sizes!
- All channels are **self-loop FIFO** channels
- Use the techniques for the self-loop FIFOs



Making system-level design take off

<http://daedalus.liacs.nl>