

complexiteit en spellen

complexiteit 2024

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Gastcollege bij Complexiteit
(2024, J.de Graaf en L.Edixhoven).
Geen tentamenstof.

Thema: **Complexiteitsklassen** die ‘horen’ bij
puzzels en spellen.
Naar het boek van Hearn en Demaine over
“**Constraint Logic**”.

Eerder ook in [Seminar Combinatorial Algorithms](#) (W.Kosters en HJ.Hoogeboom).

'game theory' fields

combinatorial game theory

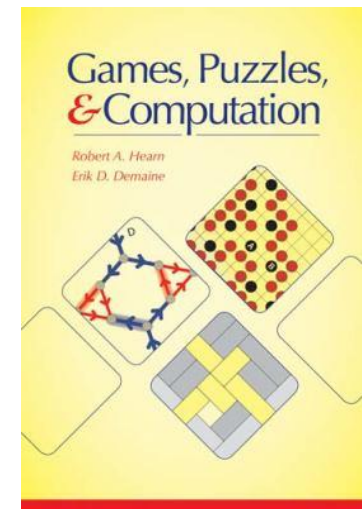
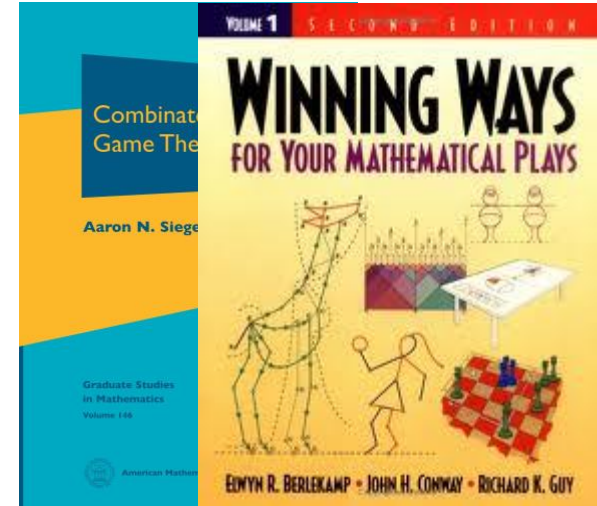
algorithms
mathematical theory

economic game theory

von Neumann, Nash
strategy, optimization expected profit

computational complexity

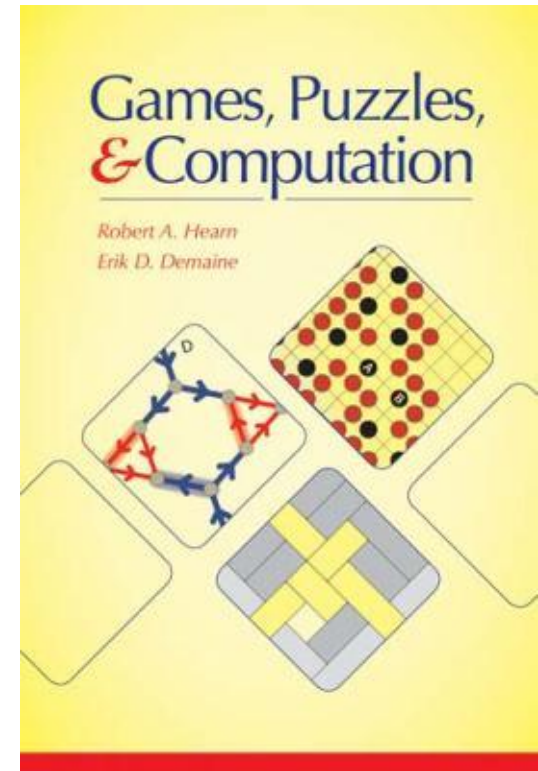
models of computation: *games*
turing machine



Games, Puzzles, & Computation

Robert A. Hearn
Erik D. Demaine

(2009, AKPeters)



E. Demaine and R.A. Hearn. Constraint Logic:
A Uniform Framework for Modeling Computation as
Games. In: Proceedings of the 23rd Annual IEEE
Conference on Computational Complexity, June 2008.

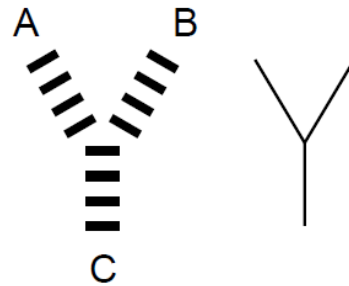
R.A. Hearn. Games, Puzzles, and Computation
PhD thesis, MIT, 2006.

domino computing



Computing with Planar Toppling Domino Arrangements

William M. Stevens



fork

challenge:
(no) timing & (no) bridges

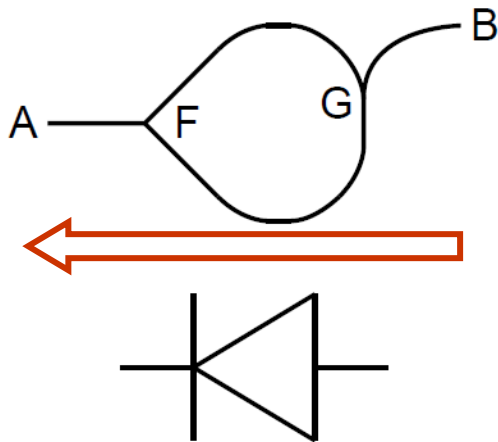


Fig. 3. A one way line

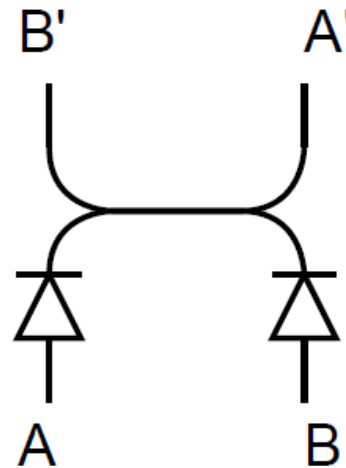


Fig. 4. A single line crossover

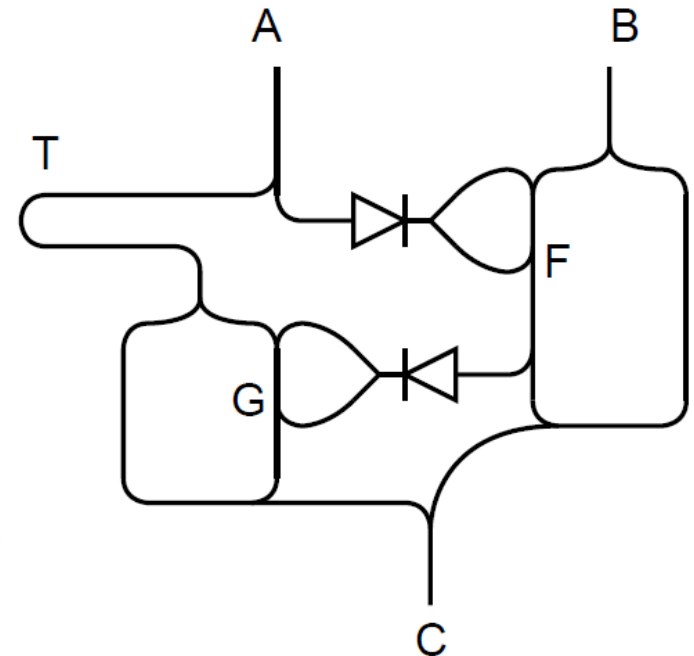


Fig. 5. A both mechanism

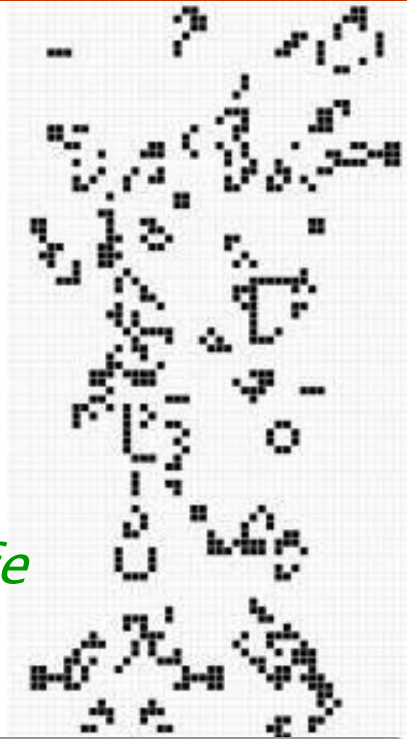
what is a game?

characteristics

- bounded state
- moves, repetition
- players
- goal

study the complexity of

- **simulation** (0p) *domino, game of life*
- **puzzles** (1p) *rush hour*
- **board games** (2p) 'generalized' *chess*
- teams



We gaan uit van een eindig aantal toestanden.
We onderscheiden het aantal spelers

- nul: simulaties
- één: puzzels
- twee: spellen

en ook of zetten wel/niet herhaald mogen worden

- bounded / unbounded

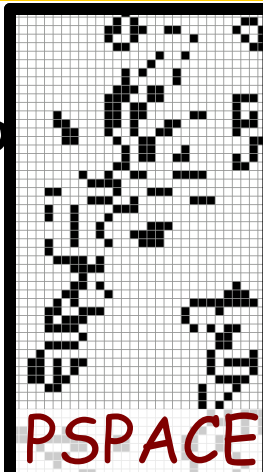
Daarbij horen zes klassen spellen en passende complexiteitsklassen.

Voor elke klasse is een **Constraint Logic** die deze complexiteit heeft, en gebruikt kan worden om naar concrete spellen te reduceren. Constraint Logic is een spel/puzzel waarin takken in een graaf kunnen worden omgedraaid (volgens simpele regels)

Complexity of Games & Puzzles

[Demaine, Hearn & many others]

unbounded



PSPACE



PSPACE



EXPTIME



Undecidable

bounded



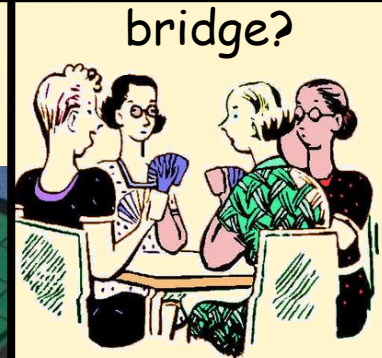
P



NP



PSPACE



NEXPTIME

0 players
(simulation)

1 player
(puzzle)

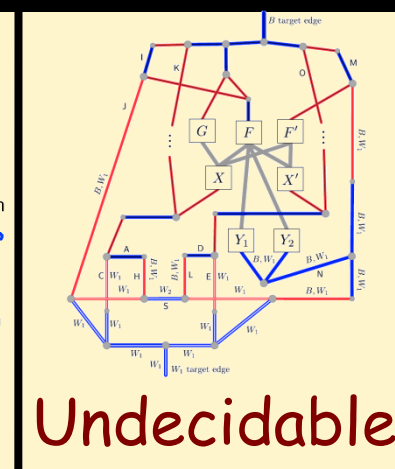
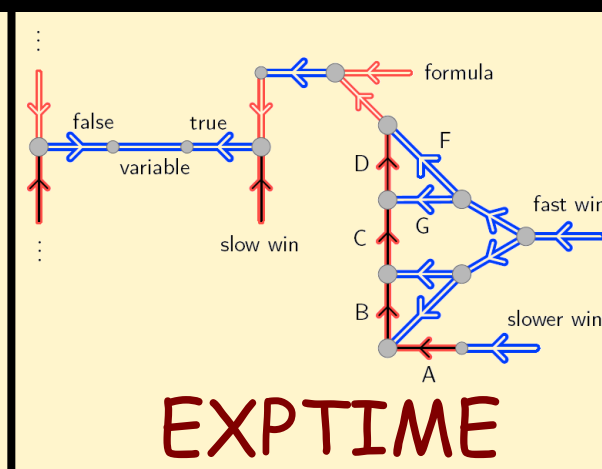
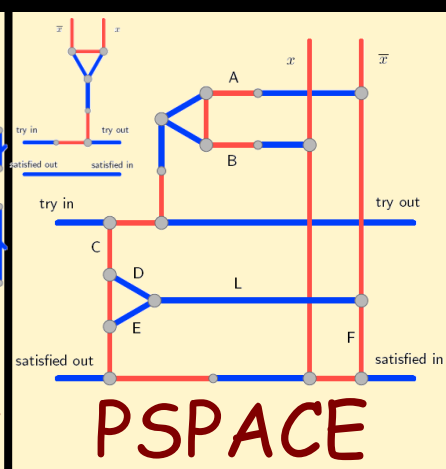
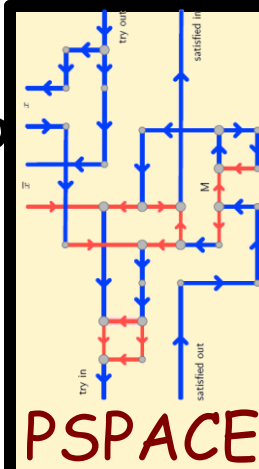
2 players
(game)

team,
imperfect info

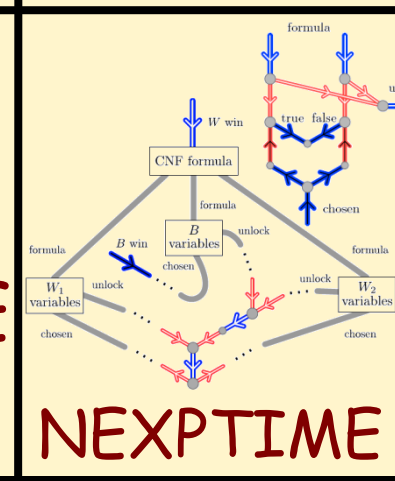
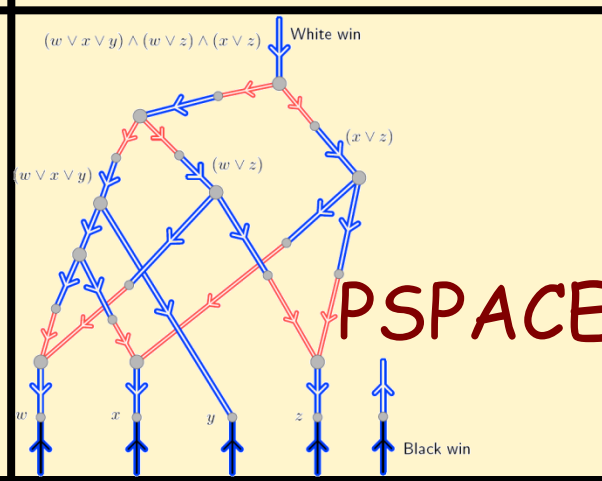
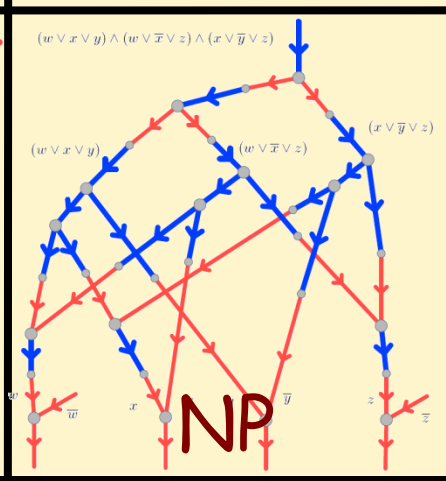
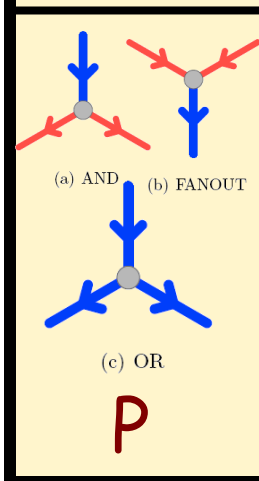
Constraint Logic

[Hearn & Demaine 2009]

unbounded



bounded



0 players
(simulation)

1 player
(puzzle)

2 players
(game)

team,
imperfect info

We gaan eerst kijken naar

- tijdscomplexiteit (voor bounded)
- ruimtecomplexiteit (unbounded)

en

- deterministische,
- niet-deterministische en
- alternerende(!) TuringMachine berekeningen.

De bijbehorende complexiteitsklassen passen precies op de zes klassen van spellen.

deel 1: tijd- en ruimtecomplexiteit

algemeen leerboek (ook talen en automaten):
Michael Sipser, Introduction to the Theory
of Computation.

Ch.7&8 Time & Space complexity.

Ch.10.3 beschrijft Alternation.

gevorderd:

Arora and Barak, Computational Complexity A
modern approach. Cambridge University
Press. 2009

► Complexiteit (dit vak)

- hoeveel werk kost deze oplossing? (tijd)complexiteit
- hoeveel geheugen? ruimtcomplexiteit

basic complexity classes

game complexity classes

VS.

TM resources: *space & time*

Cook/Levin NP completeness SAT

Savitch PSPACE = NPSPACE

Er zijn verschillende TM modellen mogelijk.
Invoer tape, meerdere werktapes, eenzijdig,
dubbelzijdig.

Voor ruimte complexiteit onderscheiden we een
werktape naast de invoertape. Dit maakt
logaritmische complexiteit mogelijk: véél
minder schrijfruimte dan de invoer lang is.

Polynomiale ruimte complexiteit

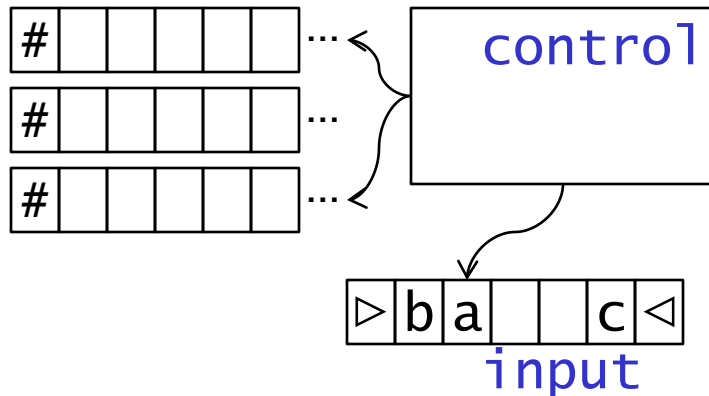
- PSPACE
- NPSPACE niet deterministische berekeningen

Savitch: ruimte kan hergebruikt worden, we
kunnen nauwkeurig alle berekeningen
'recursief' nagaan.

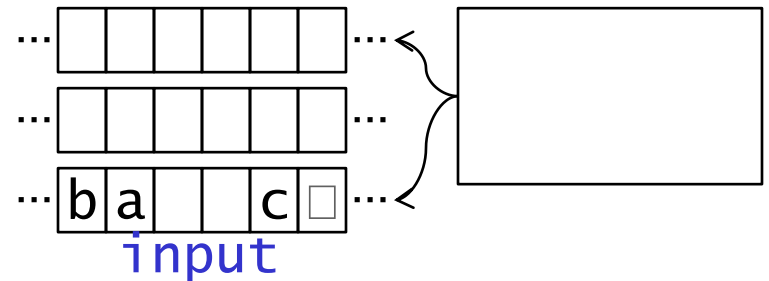
PSPACE = NPSPACE (!)

TM models (H&U)

working tapes



working tapes



space complexity

DSPACE(f) NSPACE(f)

offline

multiple working tapes

single side infinite

for every input word of length n , ...

*M scans at most $f(n)$ cells
on any storage tape ...*

time complexity

DTIME(f) NTIME(f)

input on tape

multiple working tapes

double sided

*M makes at most $f(n)$
moves before halting ...*

$$\text{NSPACE}(s(n)) \subseteq \text{SPACE}(s^2(n))$$

can we reach a halting configuration?
 at most exponentially many steps $s(n)|\Sigma|^{s(n)}$

solve recursively “re-use space”

$\text{reach}(ini, fin, 1) = \text{step}(ini, fin)$

$\text{reach}(ini, fin, 2^k)$

foreach configuration mid

test $\text{reach}(ini, mid, 2^{k-1}) \wedge \text{reach}(mid, fin, 2^{k-1})$

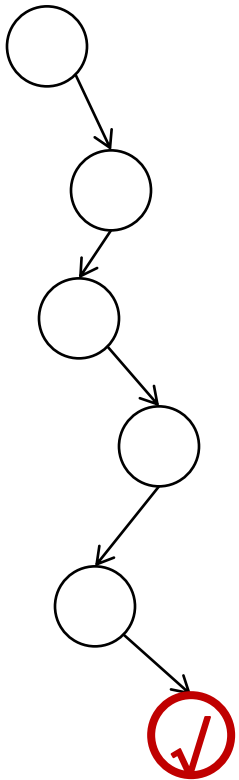
stack depth $s(n)$ of configs, each size $s(n)$

$$\text{NPSPACE} = \text{PSPACE}$$

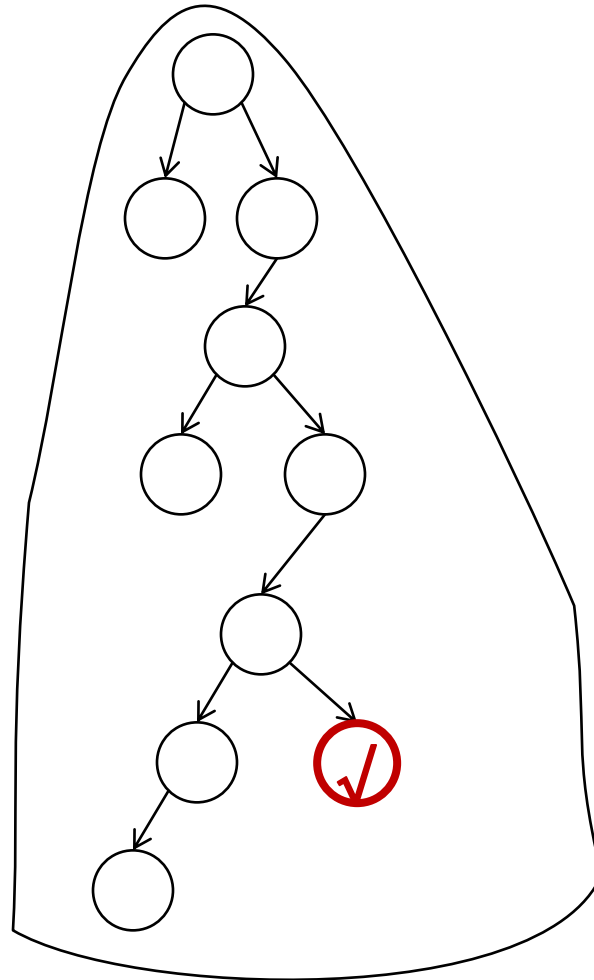
$$\text{NSPACE}(s(n)) \subseteq \text{ATIME}(s^2(n)) \quad \text{“parallel in time”}$$

computation tree

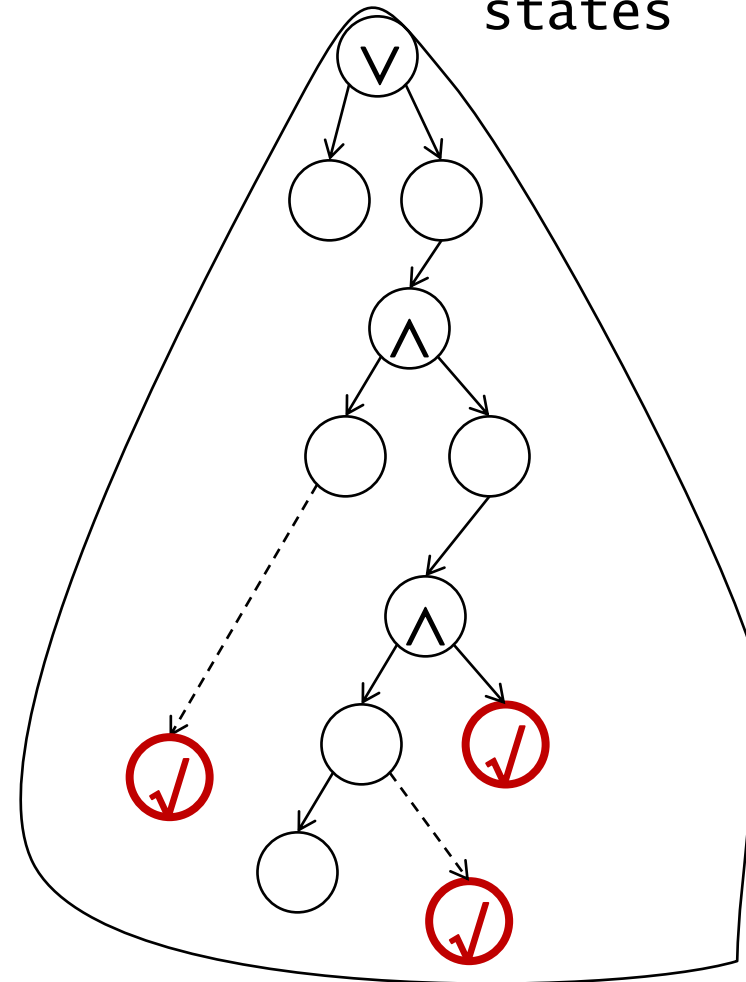
existential and *universal* states



determinism



nondeterminism



alternation

niet-det TM: existentieel: kan er een accepterende berekening gevonden worden.

Alternierend: ook universeel: elke volgende stap heeft een accepterende berekening.

P, NP, **AP**

PSPACE=NPSPACE, **APSPACE**

Oók LOGSPACE=L, NL, AL

Alterneren is krachtig, stapt een nivo omhoog

AL=P, AP=PSPACE, APSPACE=EXPTIME

Gelijkheid, wonderlijk in complexiteitsland.

Constructie door de hele berekeningsboom na te rekenen.

$\text{NSPACE}(s(n)) \subseteq \text{ATIME}(s^2(n))$ “parallel in time”

$\text{reach}_{2k}(c_1, c_2)$

exists configuration c

write in time $s(n)$

$\text{reach}_k(c_1, c) \wedge \text{reach}_k(c, c_2)$

parallel in time

(!!) technisch is correct: $\bigcup_c \text{ATIME}(c \cdot s^2(n))$

$\text{ATIME}(s(n)) \subseteq \text{DSPACE}(s(n))$

simulate computation tree

dimensions

existential and *universal* states
 computation = tree

	<i>log.</i> space	<i>polynomial</i> time	space	<i>exp.</i> time
determinism	L	P	PSPACE	EXPTIME
nondeterminism	NL	NP	NPSPACE	NEXPTIME
alternation	AL	AP	APSPACE	AEXPTIME

AL

AP

APSPACE

AEXPTIME

$P \subseteq NP \subseteq PSPACE \subseteq EXPTIME \subseteq NEXPTIME \subseteq EXPSPACE$

NPSPACE

NEXPSPACE

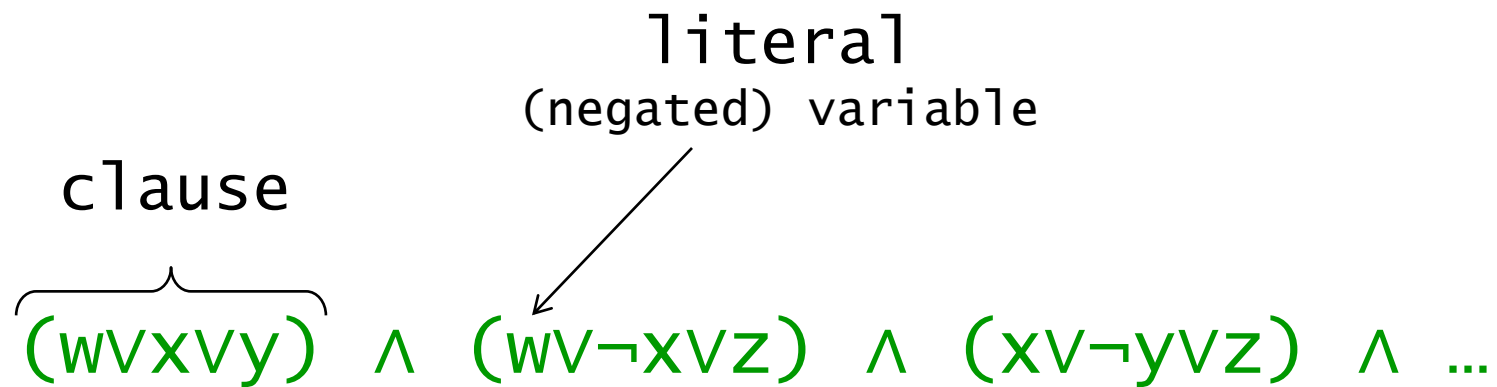
Cook-Levin: SAT is NP-compleet probleem.

deterministische TM: HORNSAT is P-compleet.
HORN clause: max één positieve literal.

Let op: P-compleet maakt gebruik van (bv) *log-space reducties*. Met pol-time reducties zijn (bijna) alle P-problemen equivalent. 😊

NC = Nick's class is gemotiveerd door
logaritmische tijd polynomiale grootte
parallele circuits, zie bijvoorbeeld de
lezing van Demaine

Demaine MIT Complexity: P-complete



3 conjunctive normalform

3SAT

given: given formula ϕ in 3CNF

question: is ϕ satisfiable?

(can we find a variable assignment making formula true)

Cook/Levin

3SAT is NP-complete

$$T_{iak} \rightarrow \neg T_{ibk} \quad T_{iak} \wedge T_{ib.k+1} \rightarrow H_{ik}$$

$$H_{ik} \wedge Q_{pk} \wedge T_{iak} \rightarrow \bigvee_{(p,a,q,b,d)} H_{i+d.k+1} \wedge Q_{q.k+1} \wedge T_{ib.k+1}$$

CNF conjunctive normal form
clauses: disjunction literals

$$a \rightarrow \neg b \quad \text{iff} \quad \neg a \vee \neg b$$

$$a \wedge b \rightarrow c \quad \text{iff} \quad \neg a \vee \neg b \vee c$$

$$a \wedge b \wedge c \rightarrow \bigvee_I (d_I \wedge e_I \wedge f_I) \quad \text{sat-iff}^*$$

$$(\neg a \vee \neg b \vee \neg c \vee \bigvee_I z_I) \wedge$$

$$\bigwedge_I (\neg z_I \wedge d_I) \wedge \bigwedge_I (\neg z_I \wedge e_I) \wedge \bigwedge_I (\neg z_I \wedge f_I)$$

3SAT is NP hard

$$(a \vee b \vee c \vee d \vee e) \quad \text{sat-iff}^*$$

$$(a \vee b \vee x_1) \wedge (\neg x_1 \vee c \vee x_2) \wedge (\neg x_2 \vee d \vee e)$$

$$T_{iak} \rightarrow \neg T_{ibk} \quad T_{iak} \wedge T_{ib.k+1} \rightarrow H_{ik}$$

$$H_{ik} \wedge Q_{pk} \wedge T_{iak} \rightarrow \bigvee_{(p,a,q,b,d)} H_{i+d.k+1} \wedge Q_{q.k+1} \wedge T_{ib.k+1}$$

determinism

HORN-SAT is P hard

CNF conjunctive normal form

Horn clauses: at most one positive literal

$$a \rightarrow \neg b \quad \text{iff} \quad \neg a \vee \neg b$$

$$a \wedge b \rightarrow c \quad \text{iff} \quad \neg a \vee \neg b \vee c$$

$$a \wedge b \wedge c \rightarrow (d \wedge e \wedge f) \quad \text{iff}$$

$$(\neg a \vee \neg b \vee \neg c \vee d) \wedge \dots \wedge (\neg a \vee \neg b \vee \neg c \vee f)$$

HORN-SAT is in P

unit propagation

empty formula: formula True

empty clause: formula False

unit clause (l): set l True

remove clauses with l

remove $\neg l$ from clauses

all remaining variables negative

Quantified Boolean Formula.

Reeks quantoren gevolgd door formule
(conjunctie clausen)

Dit lijkt op spellen: Ik win als
er is een zet, zodat
voor alle zetten van de tegenstander,
er is een zet, zodat ...

QBF: is de formule waar?

Dit probleem is PSPACE compleet.

formula games – complete problems

NL

2SAT

$$(x_1 \vee x_3) \wedge (\neg x_5 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

P

HORN-SAT

$$(\neg x_3 \vee \neg x_2 \vee \neg x_5 \vee x_1) \quad \text{i.e.} \quad (x_3 \wedge x_2 \wedge x_5 \rightarrow x_1)$$

NP

SAT

satisfiability

$$\exists x_1 \exists x_3 \exists x_5 (x_1 \vee x_3 \vee \neg x_5) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

(N) PSPACE

QBF

aka QSAT

$$\exists x_1 \forall x_3 \exists x_5 (x_1 \vee x_3 \vee \neg x_5) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

true quantified boolean formula

SAT is NP hard

satisfiability

$$\exists x_1 \exists x_3 \exists x_5 (x_1 \vee x_3 \vee \neg x_5) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

QBF is PSPACE hard

aka QSAT

$$\exists x_1 \forall x_3 \exists x_5 (x_1 \vee x_3 \vee \neg x_5) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

input length $p(n)$ #steps $\leq c^{p(n)}$

configuration c sequence variables T_{iak} Q_{qk} H_{ik}

$\Phi_k(c_1, c_2)$ from c_1 to c_2 in $\leq k$ steps
 $k=1$ see SAT construction Cook/Levin

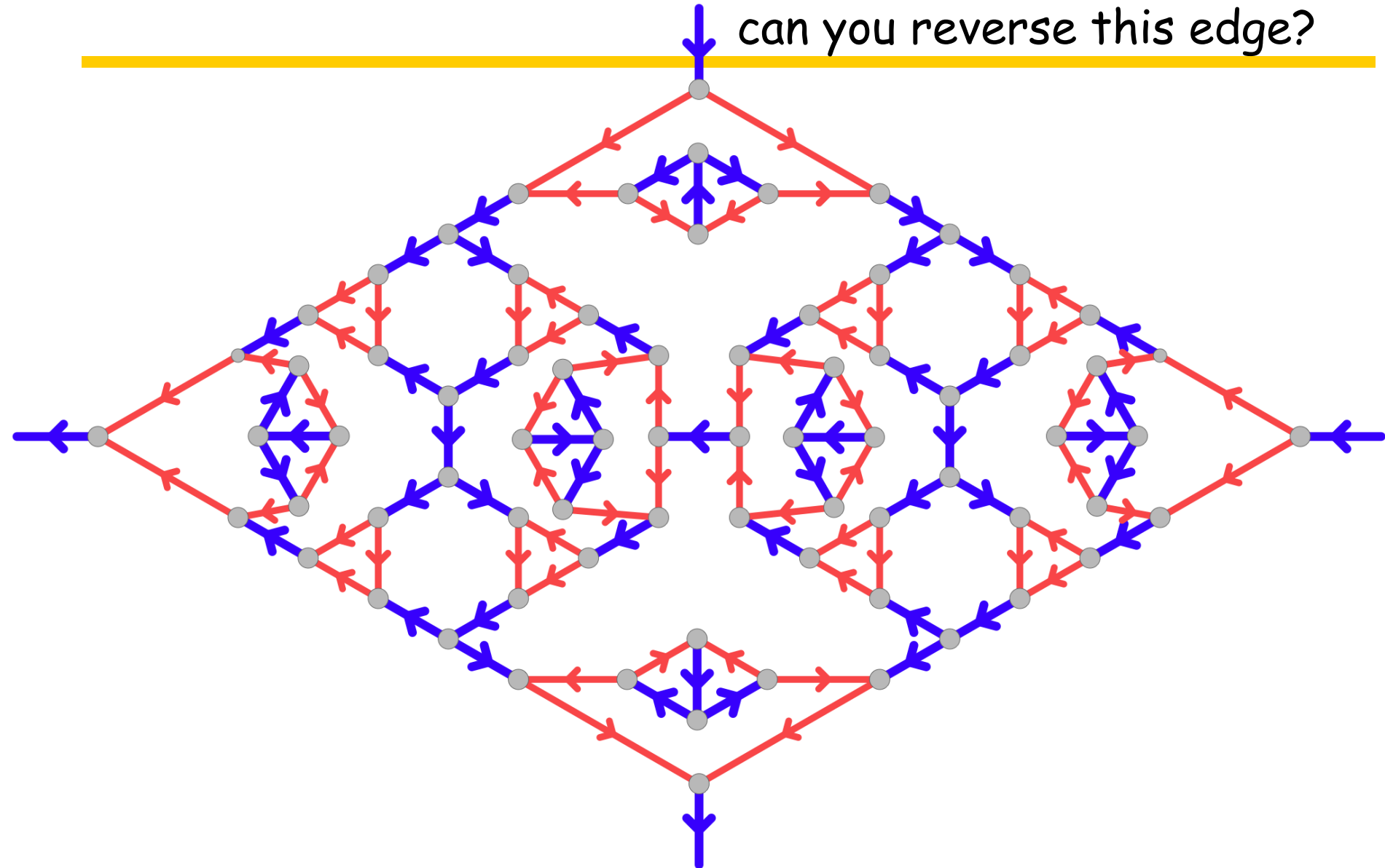
$\Phi_{2k}(c_1, c_2) = (\exists c) (\Phi_k(c_1, c) \wedge \Phi_k(c, c_2))$
close, but *doubles size*

$\Phi_{2k}(c_1, c_2) = (\exists c) (\forall c') (\forall c'')$
 $[(c', c'') = (c, c_1) \vee (c', c'') = (c_1, c)] \rightarrow \Phi_k(c', c'')$

deel 2: constraint logic

Decision Problem

can you reverse this edge?



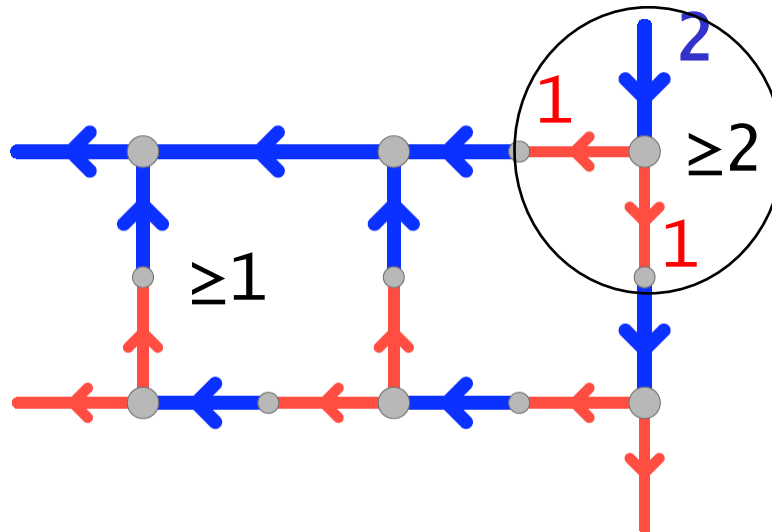
constraint Logic

NCL - nondet constraint Logic

instance: constraint graph G , edge e
question: sequence which reverses e

BOUNDED NCL

... reverses each edge *at most once*



Constraint Logic.

Gerichte graaf.

Gekleurde takken/aanhechtingen.

Waarde rood=1, blauw=2.

Elke knoop heeft tenminste waarde twee ingaande takken (dus twee rood of één blauw)

- NCL 'nondeterministic constraint logic'
past bij eenpersoons spellen=puzzels

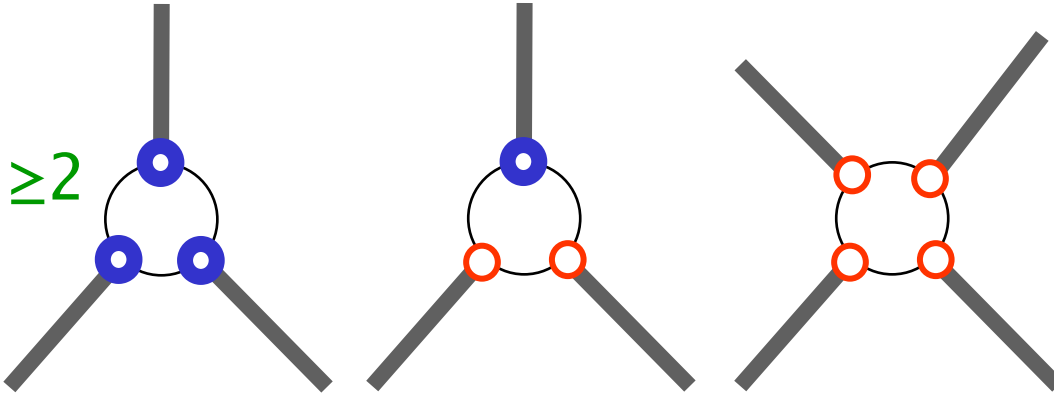
Zet: omkeren tak, als aan de eis voldaan blijft.

Doel: omkeren speciale tak.

- BNCL 'bounded' elke tak maximaal één keer omkeren

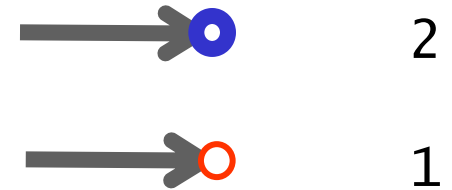
basic constraint logic

examples



edge connectors

incoming value



constraint graph

oriented/directed edges + connectors

vertex constraint

inflow value ≥ 2

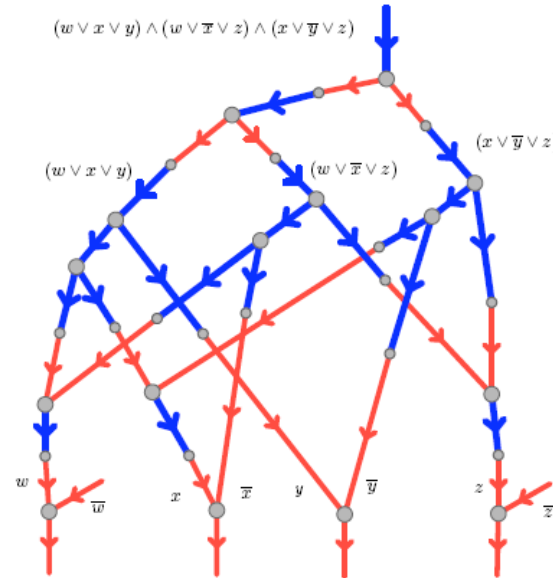
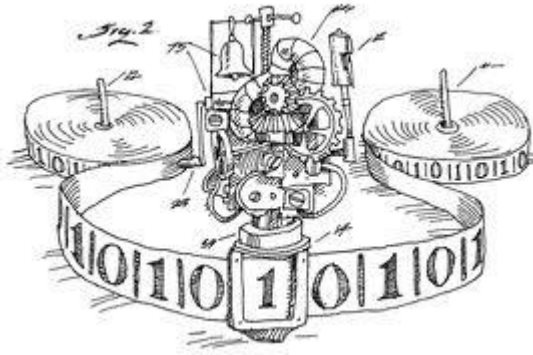
game: legal move

edge reversal satisfying constraint

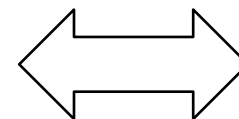
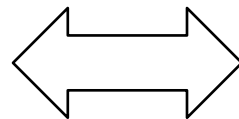
goal

reversal given edge

NP & TipOver



$$(w \vee x \vee y) \wedge (w \vee \bar{x} \vee z) \wedge (x \vee \bar{y} \vee z)$$



NP

3SAT

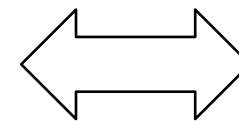
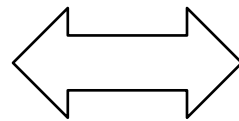
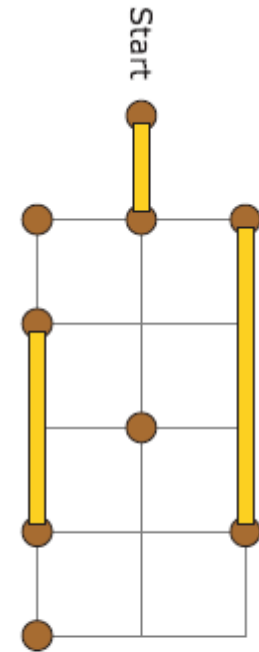
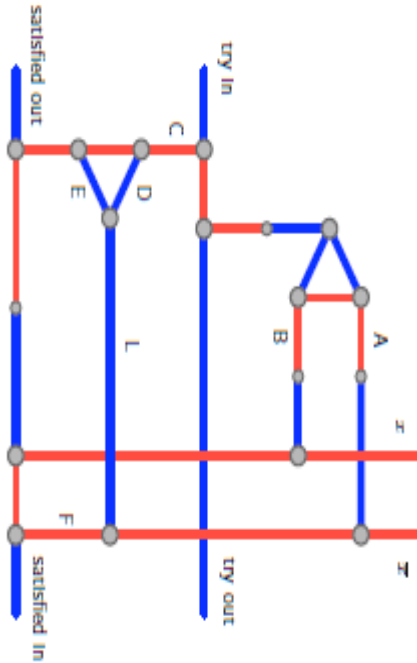
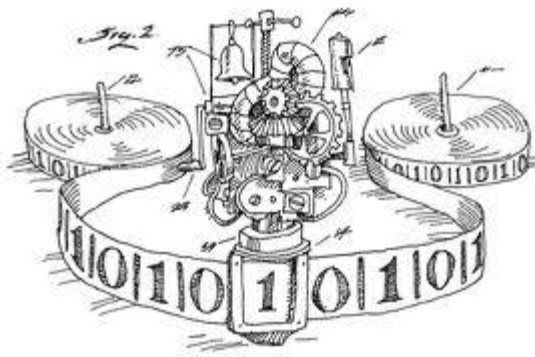
part I
constraint logic
'graph games'

Bounded NCL

part II
games in particular

TipOver

PSPACE & Plank Puzzle



PSPACE

part I
constraint logic
'graph games'

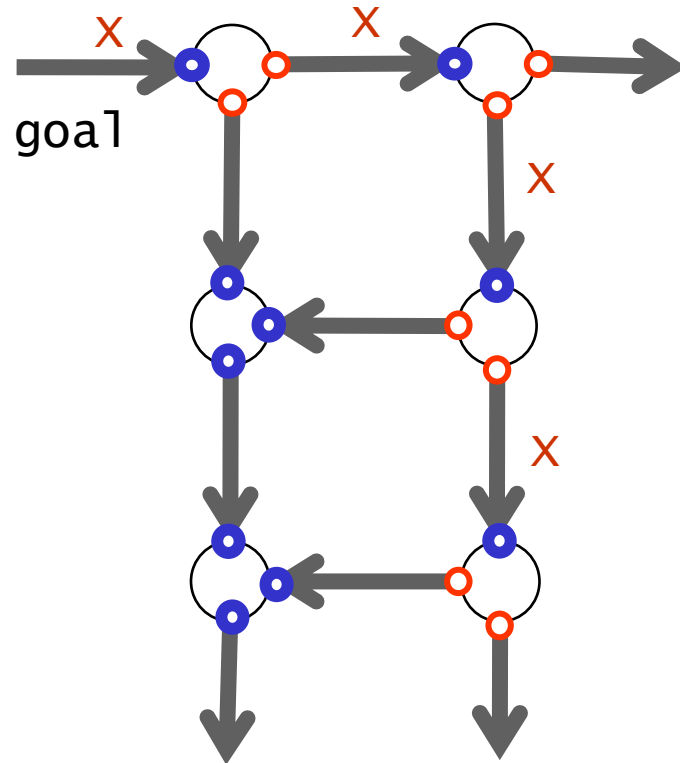
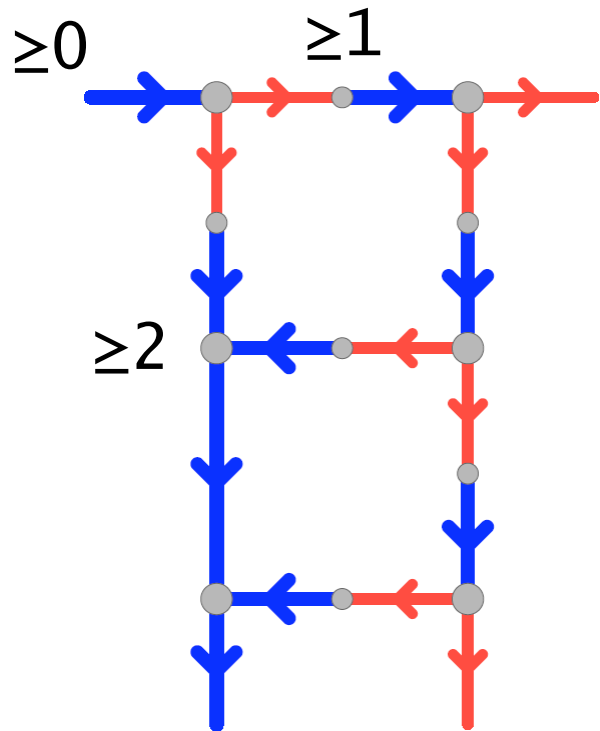
part II
games in particular

QBF

NCL

**plank puzzle
(river crossing)**

'special' vertex constraints?



colour conversion
dangling edges

edge terminators

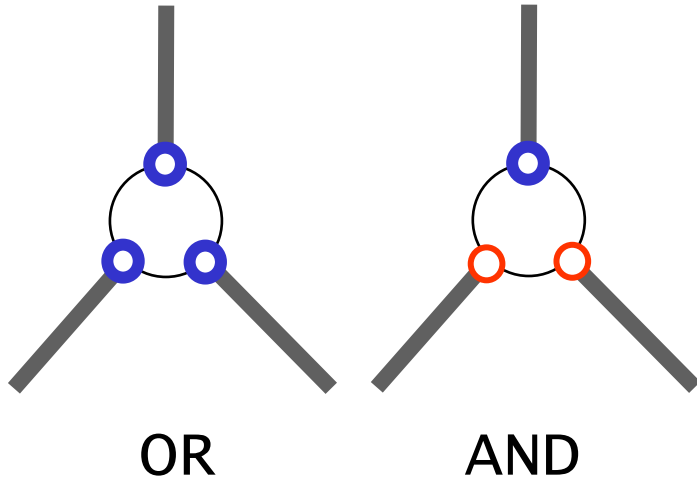
We kunnen een aantal soorten knopen onderscheiden, met een bepaalde intuïtie.
OR, AND, FANOUT, CHOICE.

De state space van zo'n knoop voldoet aan die intuïtie.

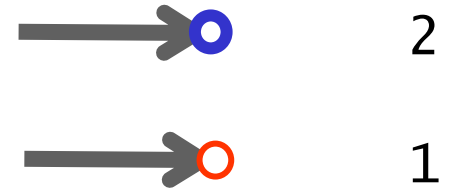
Bijvoorbeeld: om de tak boven de OR naar buiten te keren, moet tenminste één van de onderste twee naar binnen gekeerd worden.

normal form vertices

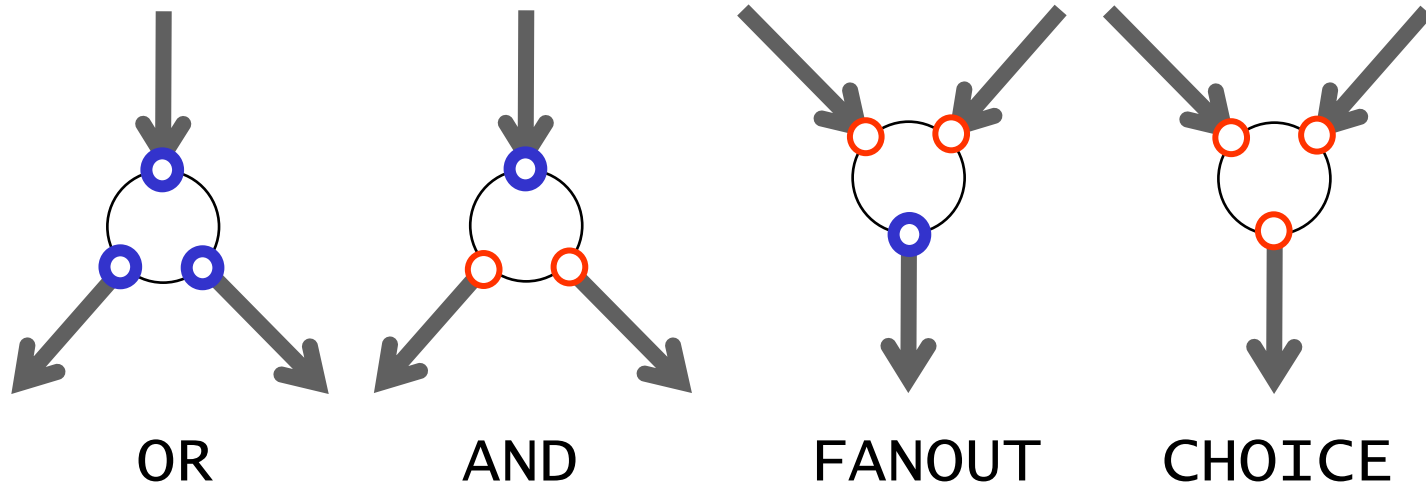
NCL



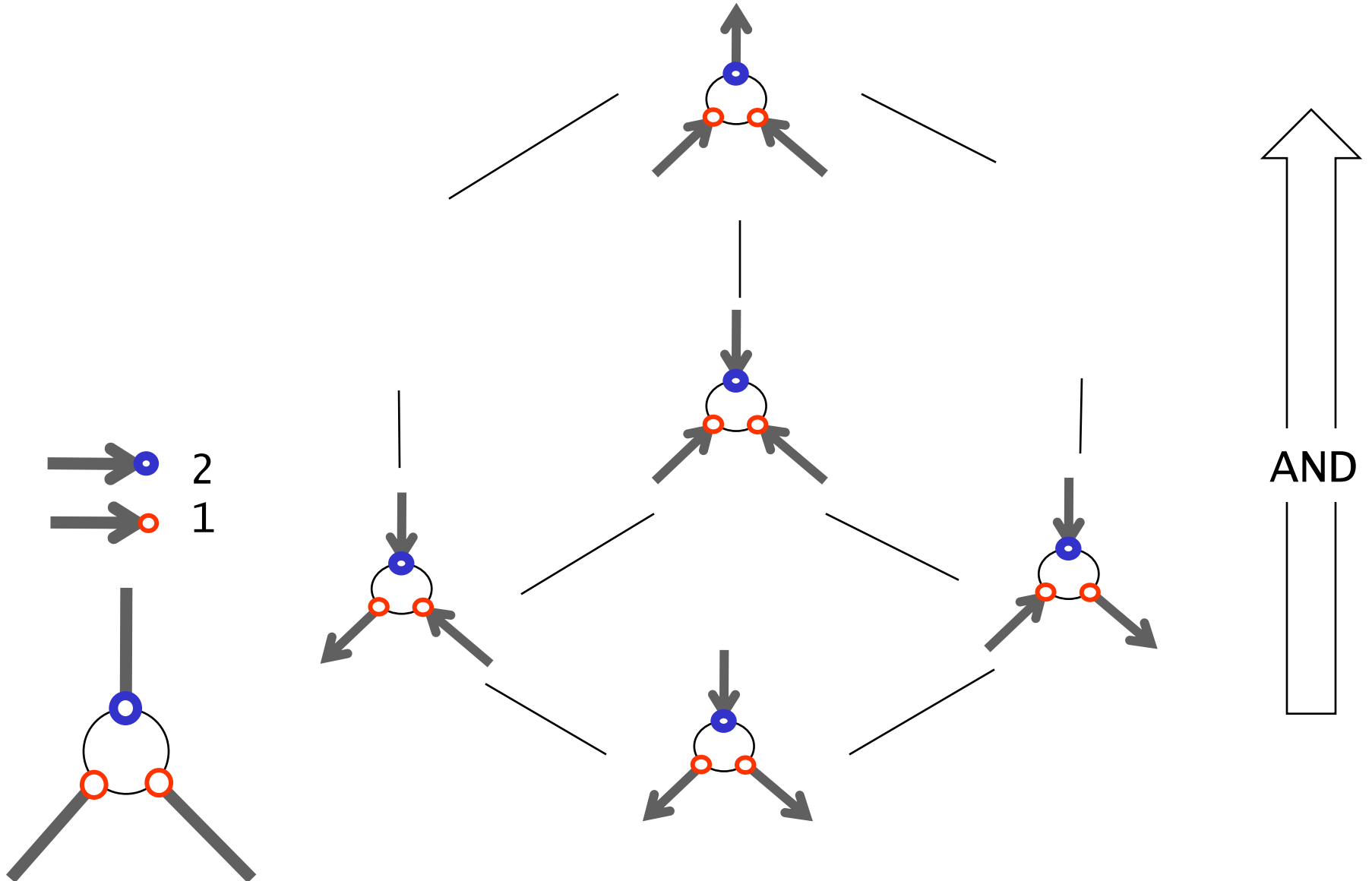
incoming value



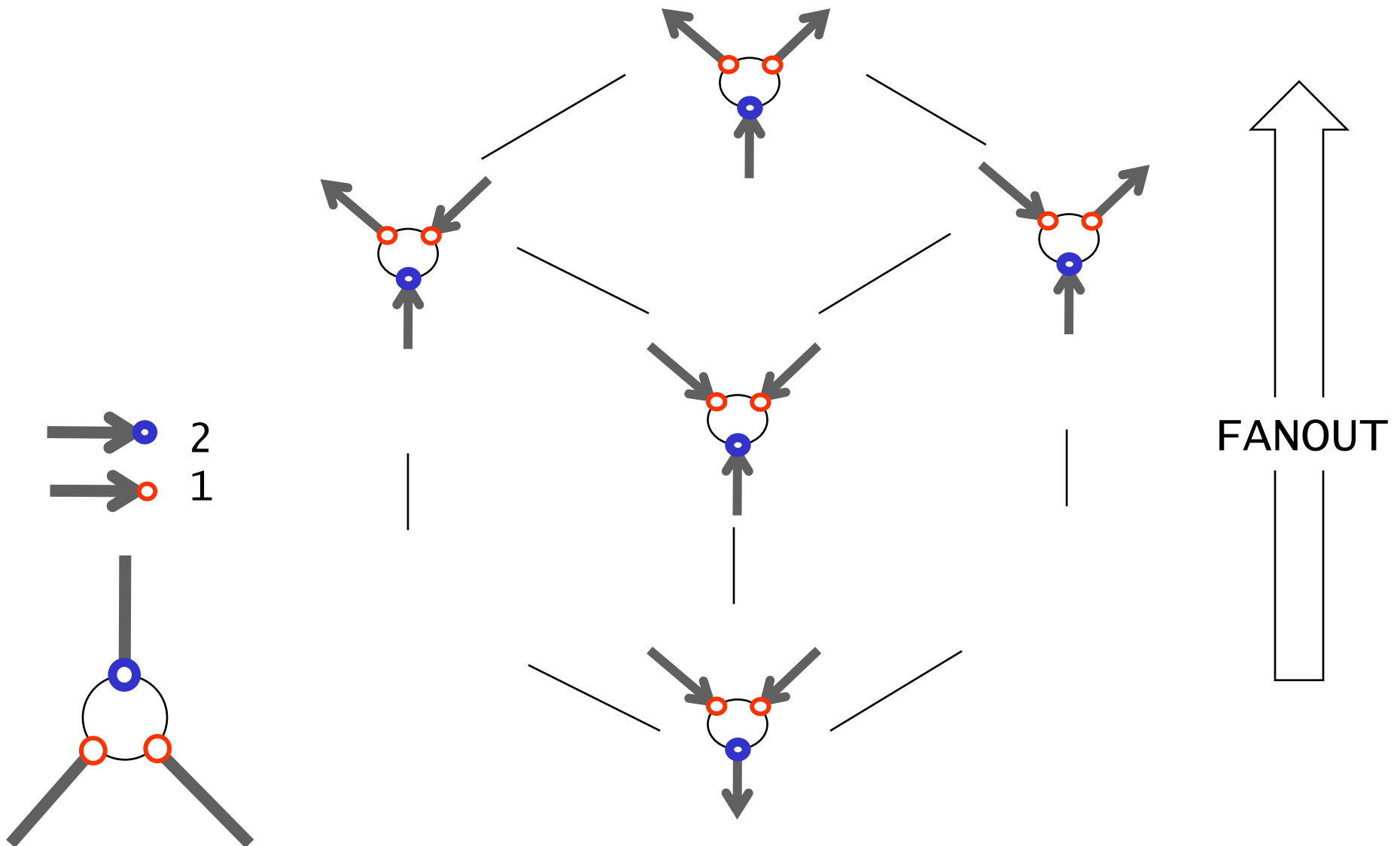
bounded NCL (reverse only once)



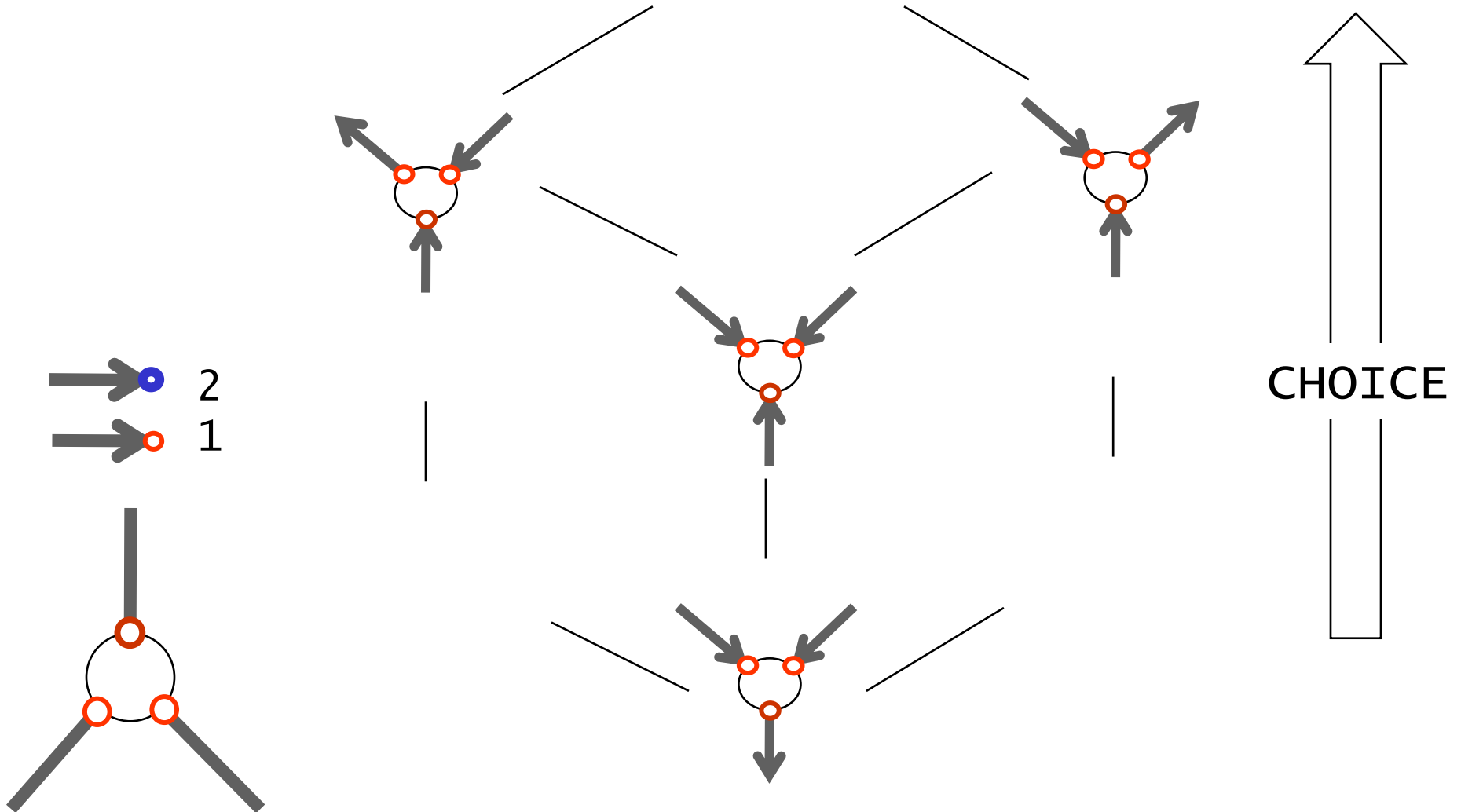
Legal configurations



Legal configurations



Legal configurations



Met de vier soorten knopen kan eenvoudig een graaf gemaakt worden die een formule representeert.

De bovenste tak kan omgekeerd worden als de formule waargemaakt kan worden.

Onderaan geven de takken de waardering van de variabelen weer.

Dus BNCL simuleert SAT en is NP complete

Als we meerdere keren takken mogen omdraaien kunnen we gadgets maken die kwantoren nadoen. (Niet erg snel in te zien.)

Dus NCL simuleert QBF/QSAT en is PSPACE complete

basic observation

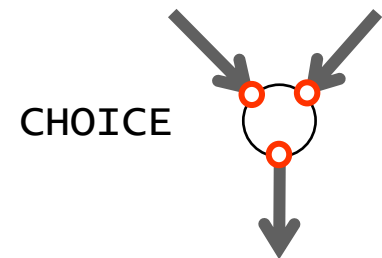
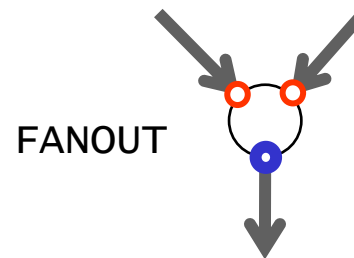
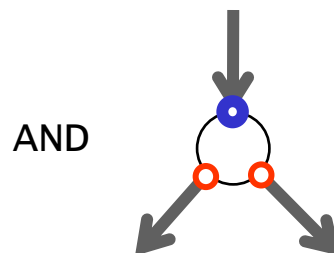
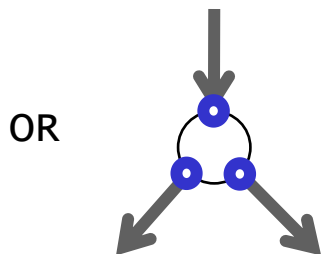
“emulate” a logical formula as graph game

goal:

flip a given edge *iff* formula satisfiable

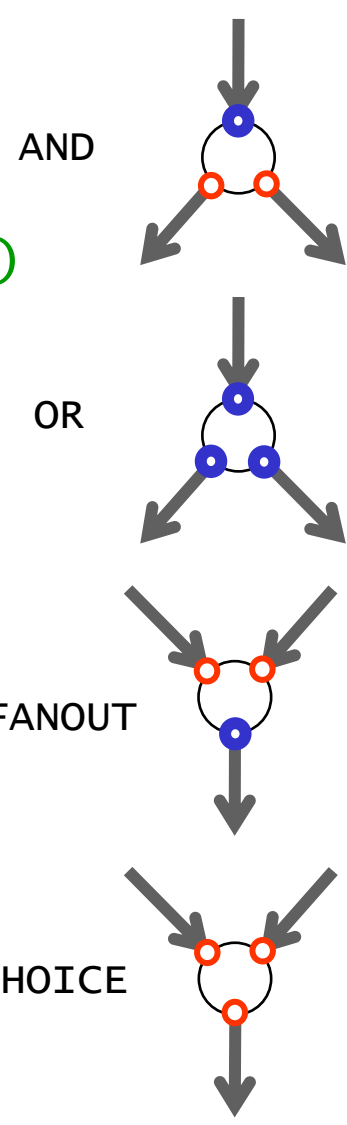
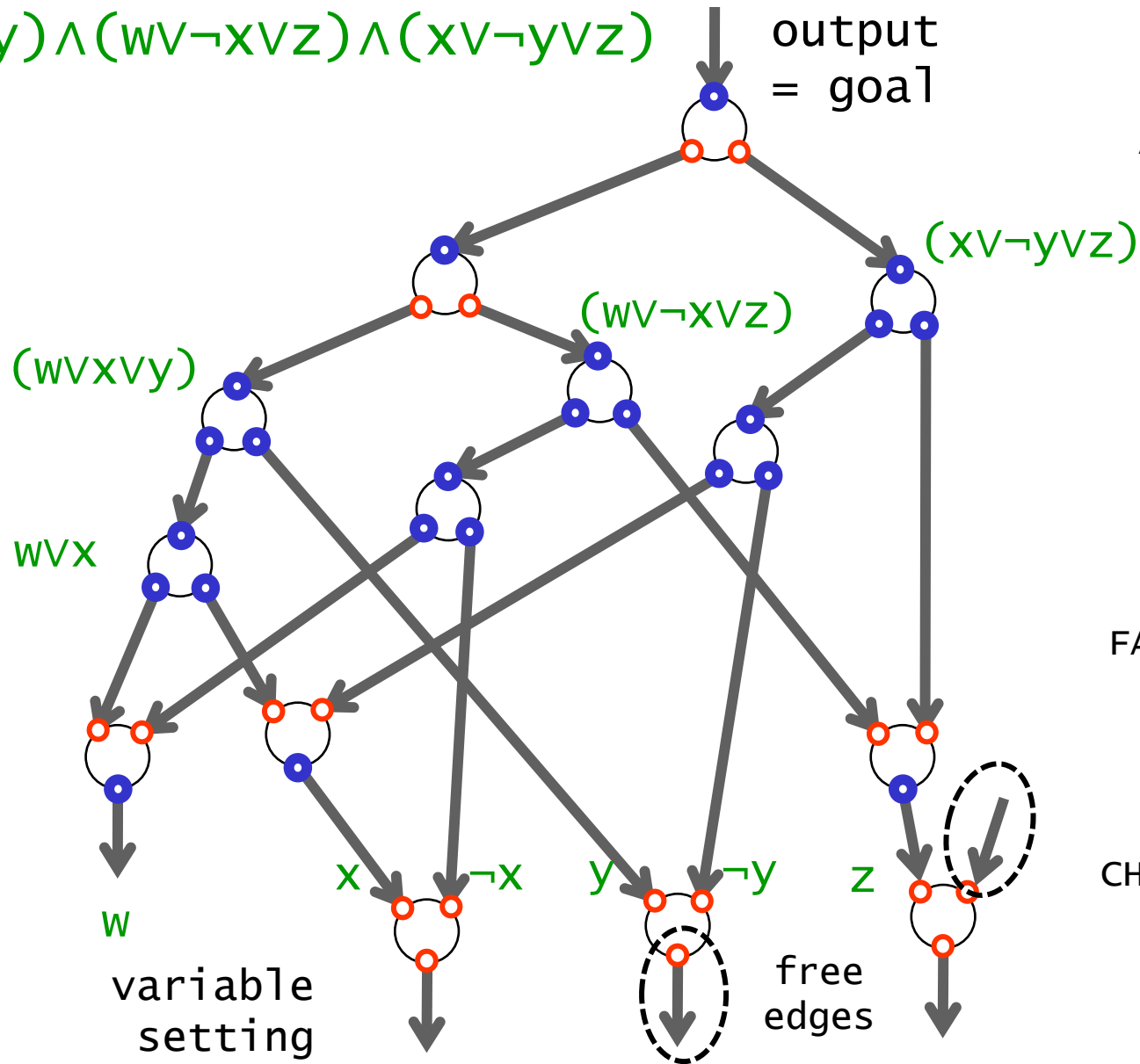
$$(wvxvy) \wedge (wv \neg xvz) \wedge (xv \neg yvz)$$

components



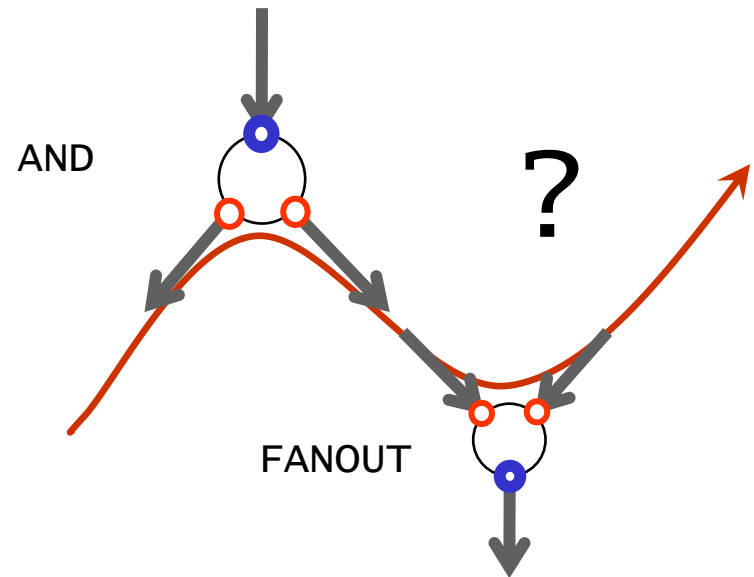
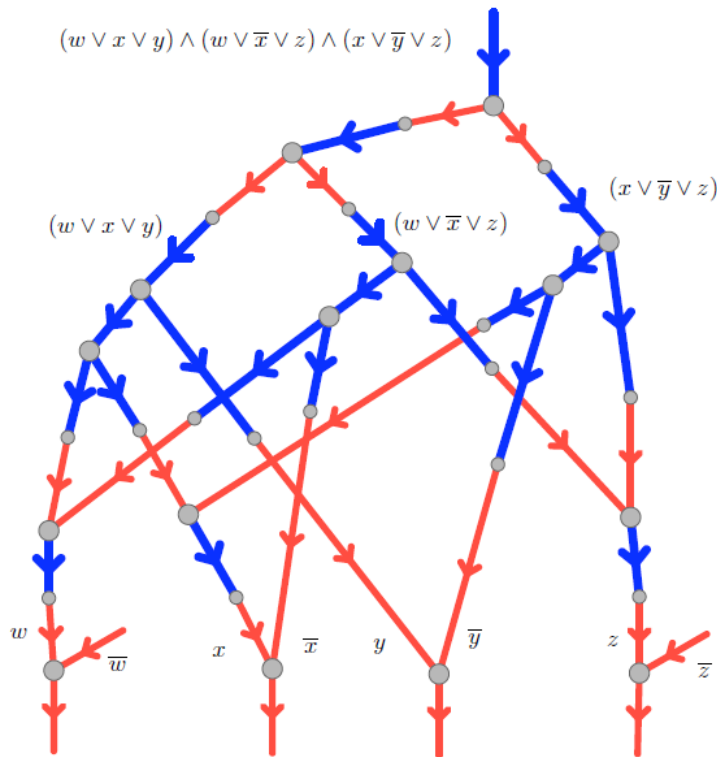
formula constraint graph

$$(wvxvy) \wedge (wv \rightarrow xvz) \wedge (xv \rightarrow yvz)$$



questions

- ‘can’ : not obliged to reverse edges upwards
ie, we do not always set variable
- can we reverse the ‘wrong way’?
- do we need restriction to reverse edge once?



game categories

game categories and their natural complexities

(polynomial)

TM
resources

Rush Hour
River Crossing

unbounded
SPACE

bounded
TIME

PSPACE	PSPACE NPSPACE	EXPTIME APSPACE	undecid
P	NP	PSPACE AP	NEXPTIME

#

zero
simulation
determ.

one
puzzle
nondeterm.

two
game
alternat.

team
imperfect
informat.

Tipover

$NL \subseteq P \subseteq NP \subseteq PSPACE \subseteq EXPTIME \subseteq NEXPTIME$
= NPSPACE = AP

formula games – complete problems

NP

$\exists x_1 \exists x_3 \exists x_5 (x_1 \vee x_3 \vee \neg x_5) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_5 \vee x_1)$

SAT

satisfiability

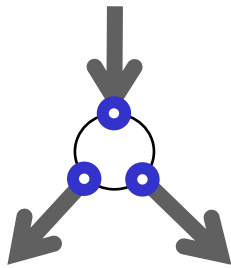
(N)PSPACE

$\exists x_1 \forall x_3 \exists x_5 (x_1 \vee x_3 \vee \neg x_5) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_5 \vee x_1)$

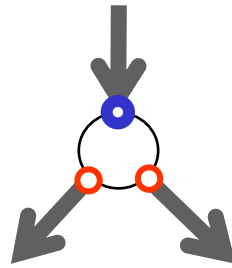
QBF

aka QSAT

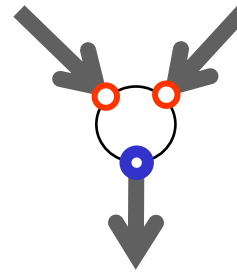
conclusion (B-NCL)



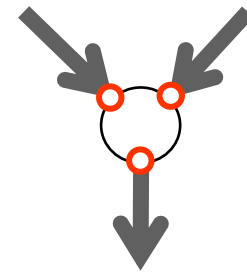
OR



AND



FANOUT



CHOICE

BOUNDED NCL - nondet constraint logic

instance: constraint graph G , edge e

question: sequence which reverses *each edge at most once*, ending with e

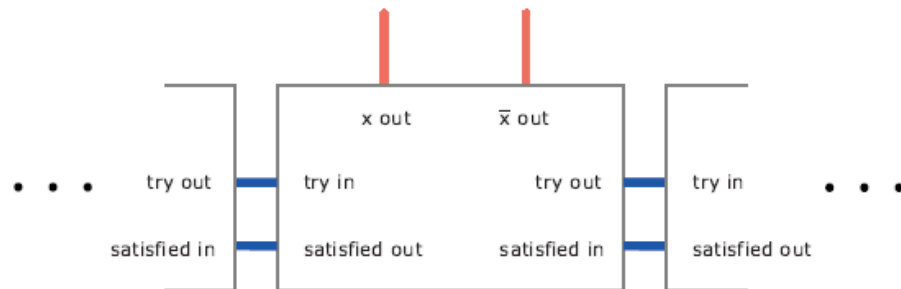
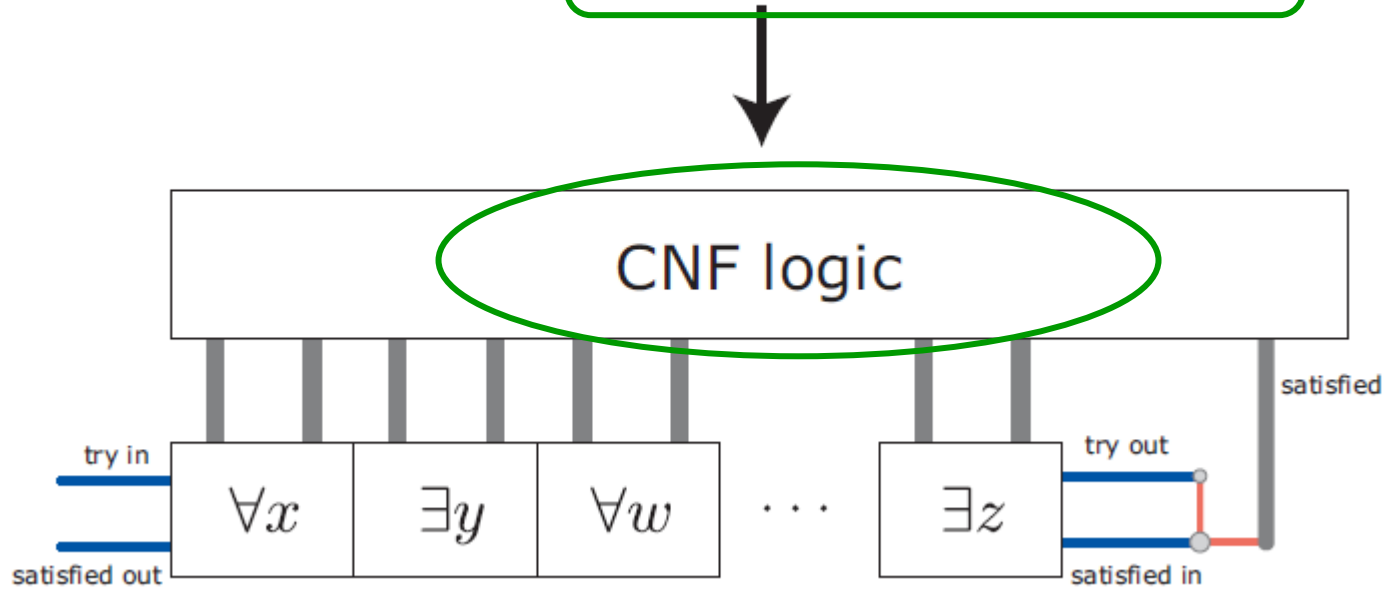
- reduction from 3SAT into Bounded NCL
- Bounded NCL is in NP

thm. Bounded NCL is NP-complete

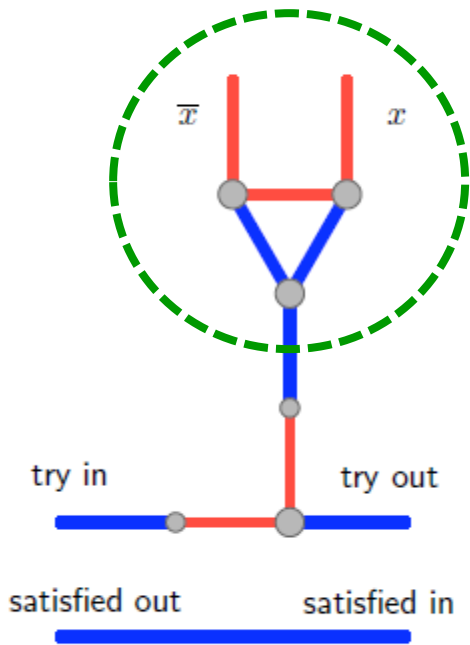
however: toppling domino's cannot cross

quantification

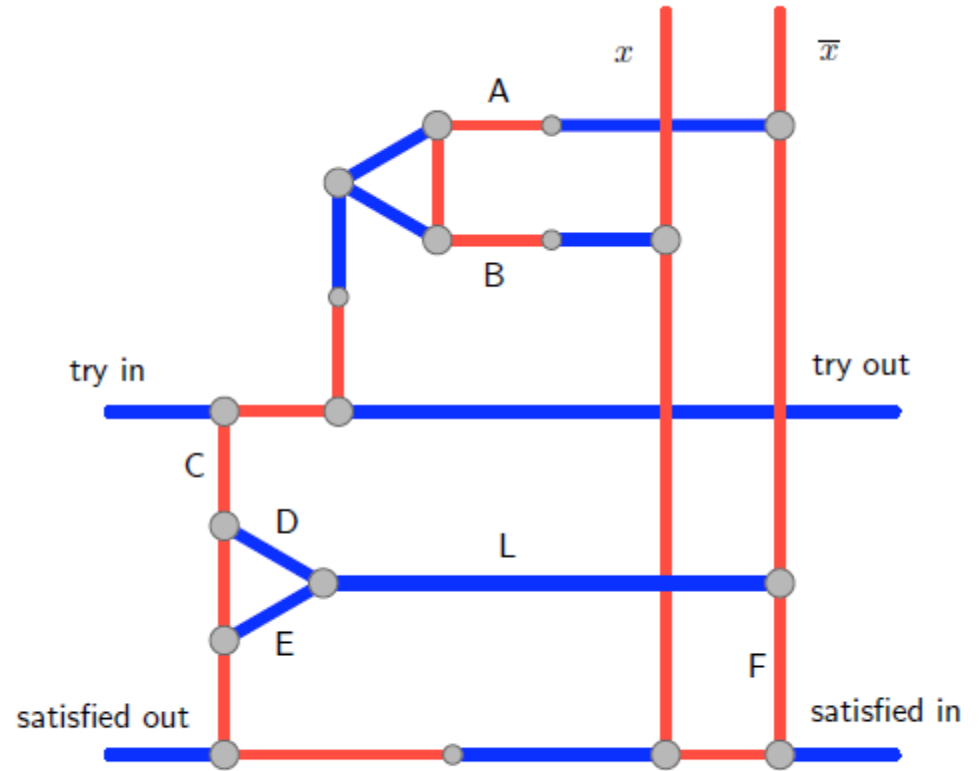
$$\forall x \exists y \forall w \dots \exists z [(x \vee y) \wedge \dots \wedge (\bar{z} \vee x \vee \bar{w})]$$



quantifier gadgets

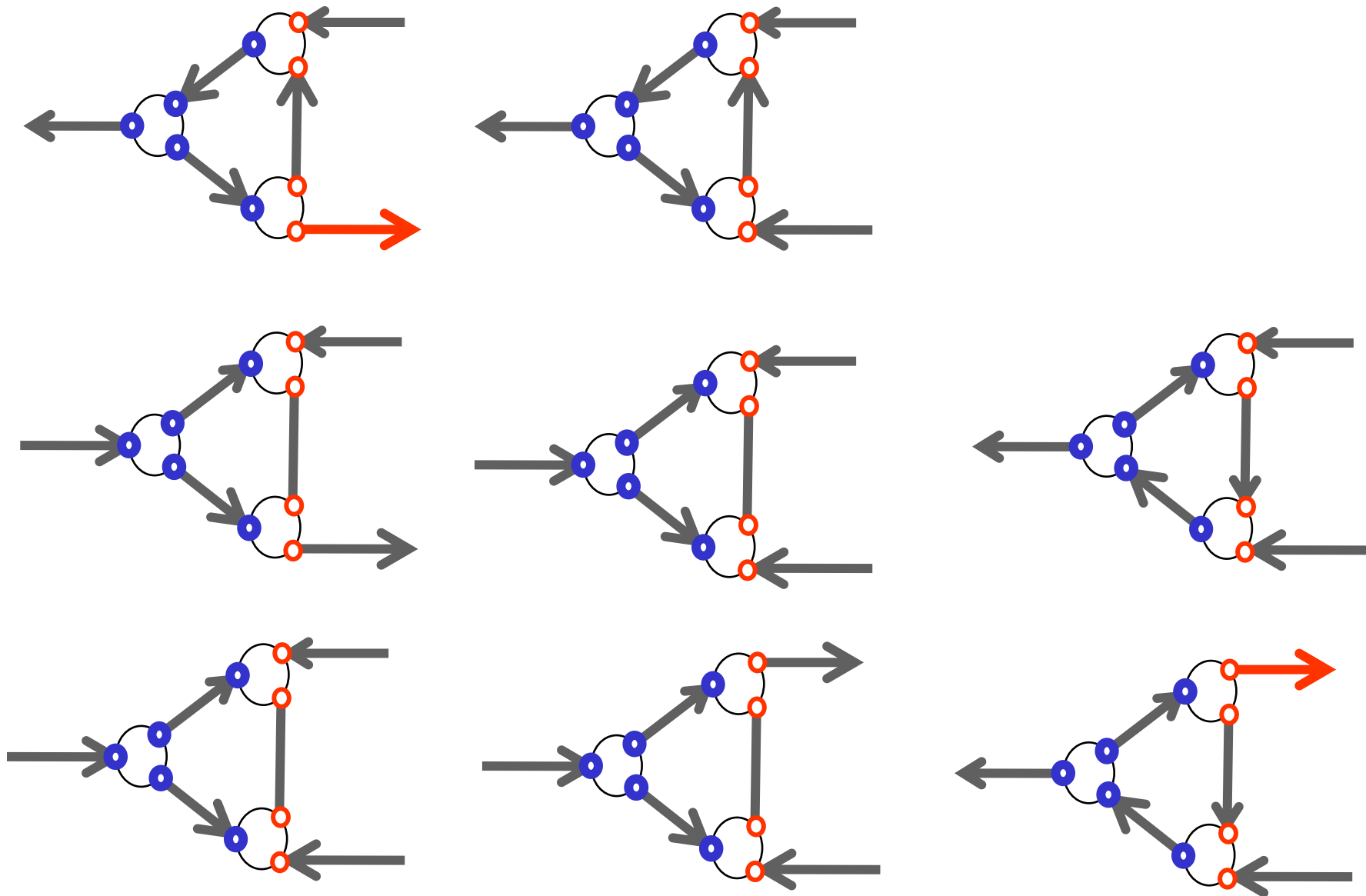


(a) Existential quantifier

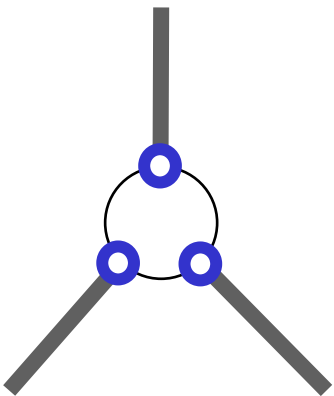
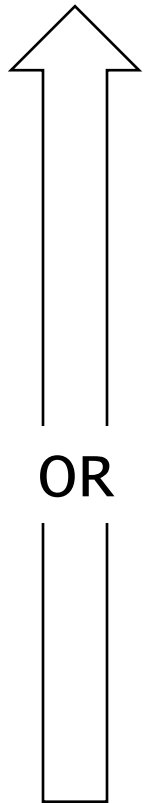
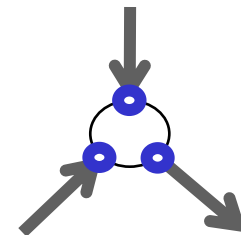
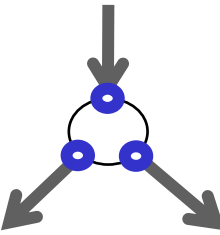
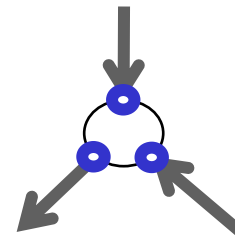
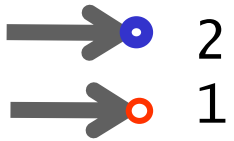
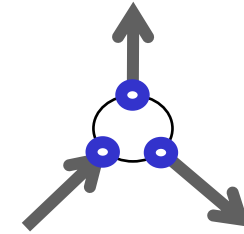
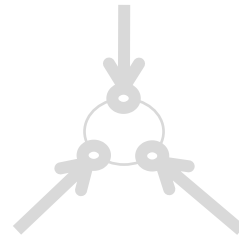
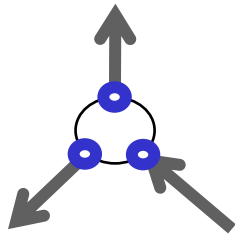
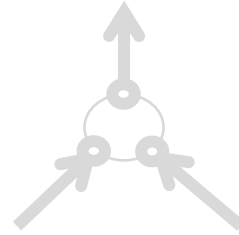
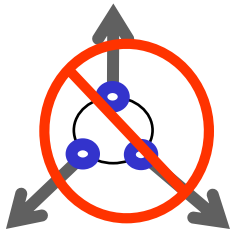


(b) Universal quantifier

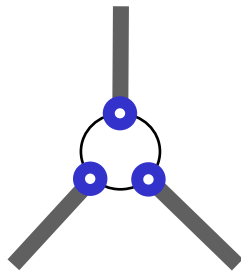
Tatch behaviour



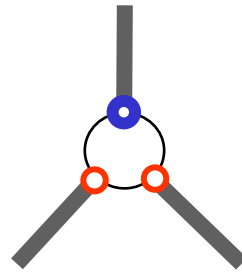
protected OR



conclusion (NCL)



OR



AND

initial orientation
arrows not specified

NCL - nondet constraint logic

instance: constraint graph G , edge e

question: sequence which reverses e

thm. NCL is PSPACE-complete

next: concrete games



bounded: NP



unbounded: PSPACE

games and complexity

Met NCL en BNCL als tussenstap kunnen we concrete spellen NP-compleet dan wel PSPACE-compleet bewijzen.

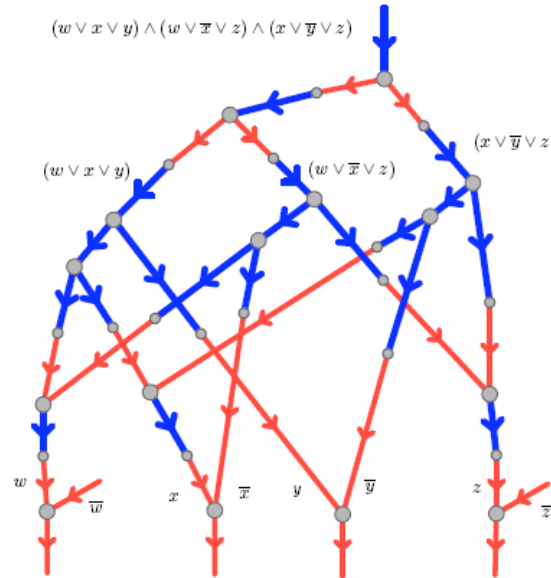
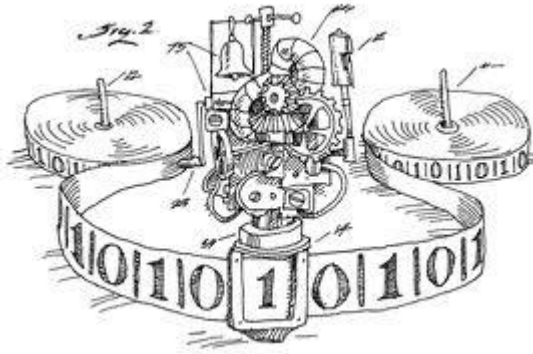
Het volstaat om 'gadgets' te bouwen die de diverse knopen kunnen simuleren.

Probleem: de grafen van NCL laten kruisende takken toe. Dat is in spellen vaak niet toegestaan. Oplossing een gadget dat signalen laat kruisen.

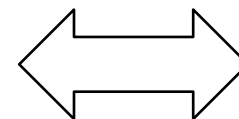
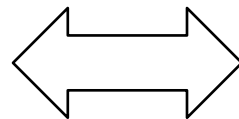
Tipover is een bounded spel. Als een krat gevallen is blijft deze liggen
Rush-hour is unbounded. Auto's mogen weer terug geschoven worden.

TipOver is NP-Complete

NP & TipOver



$$(w \vee x \vee y) \wedge (w \vee \bar{x} \vee z) \wedge (x \vee \bar{y} \vee z)$$



NP

3SAT

part I
constraint logic
'graph games'

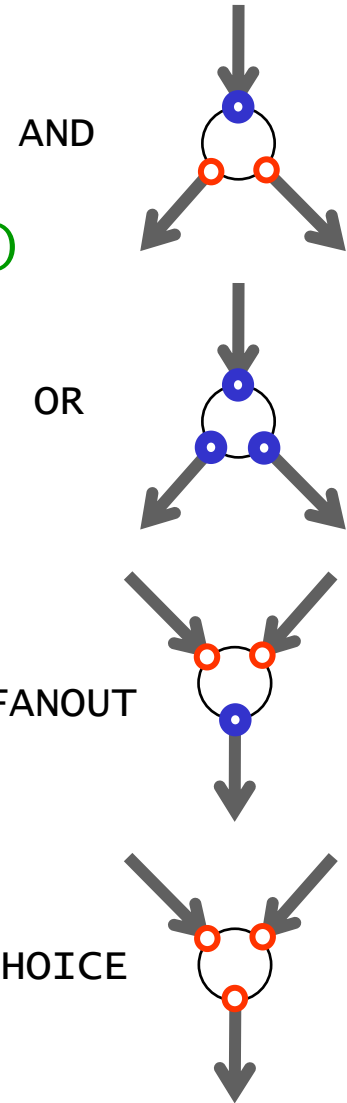
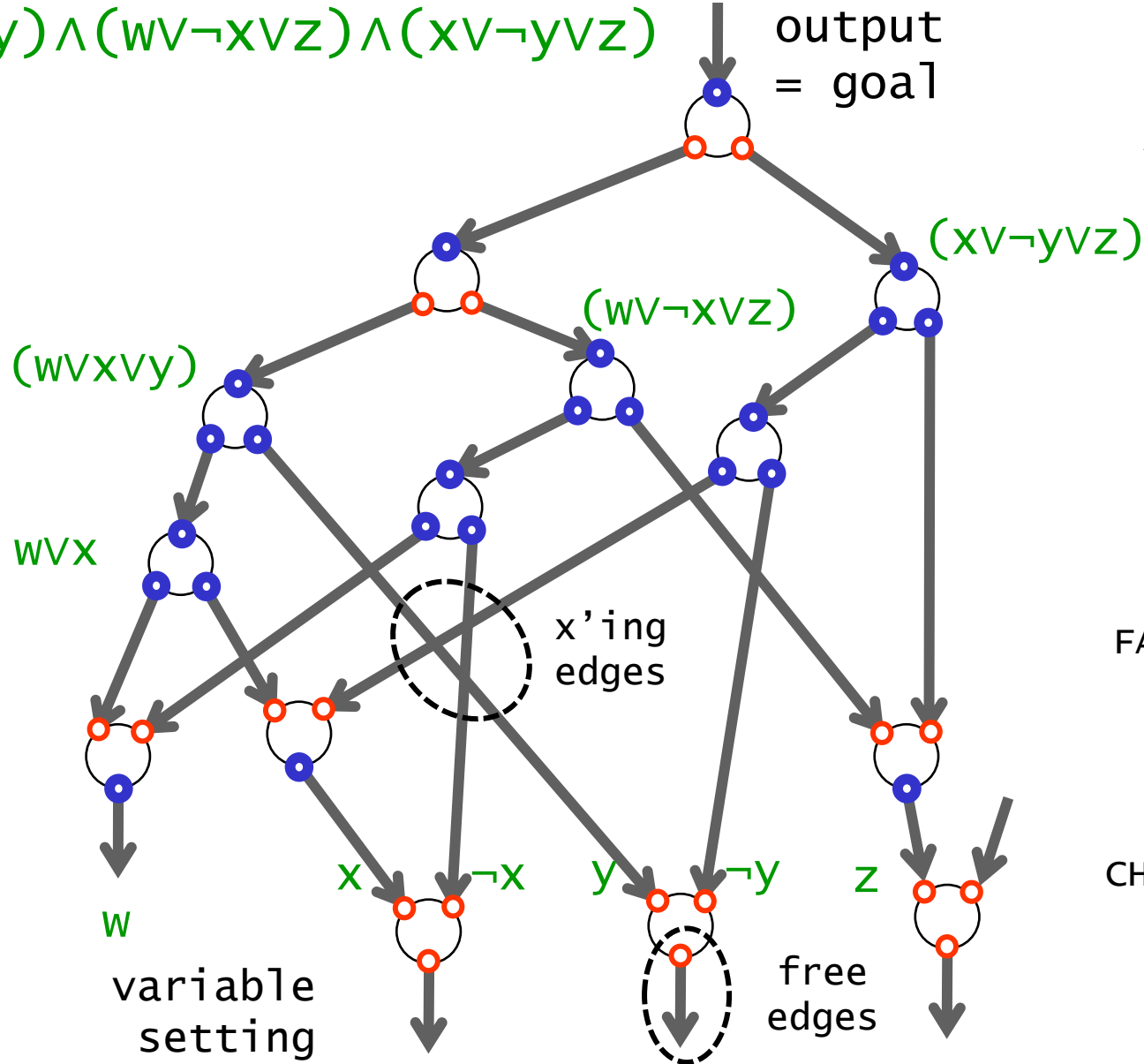
Bounded NCL

part II
games in particular

TipOver

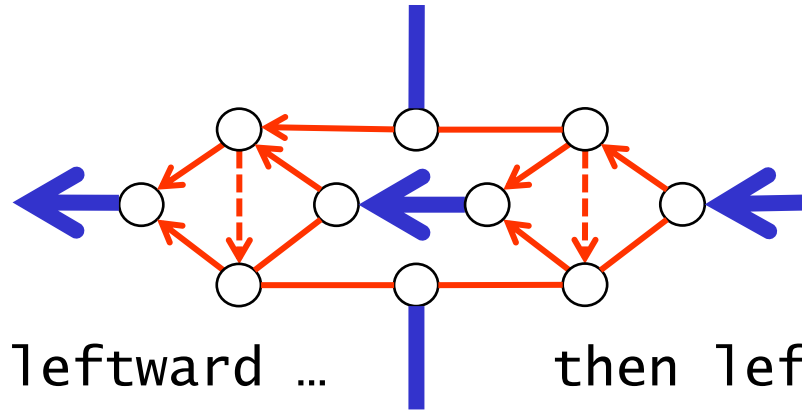
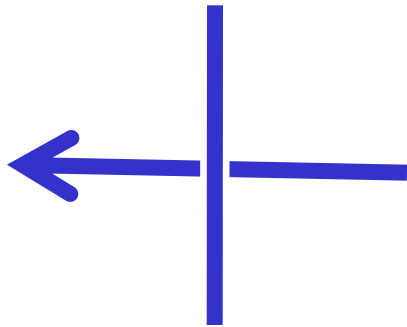
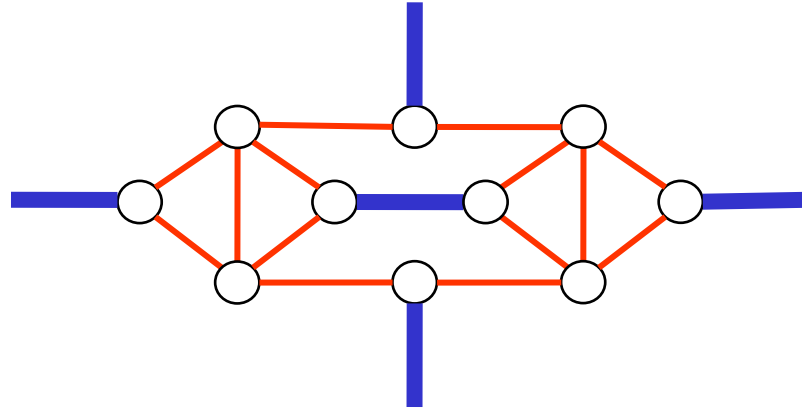
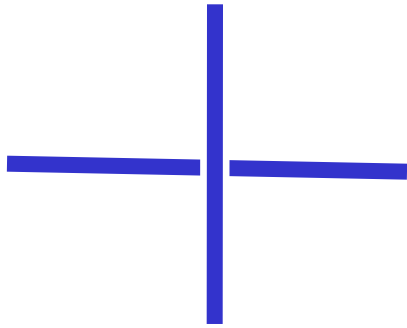
formula constraint graph

$$(wvxvy) \wedge (wv \rightarrow xvz) \wedge (xv \rightarrow yvz)$$



planar crossover gadget

formal proof Lemma 5.10

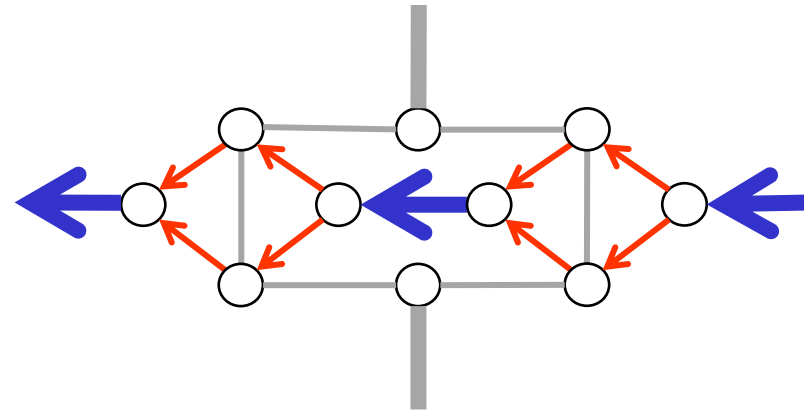
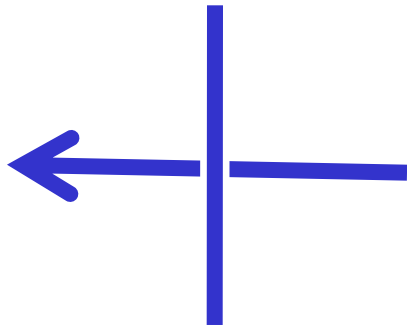
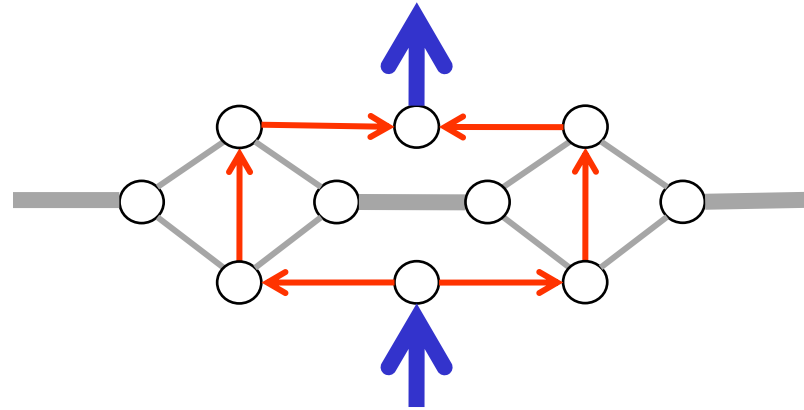
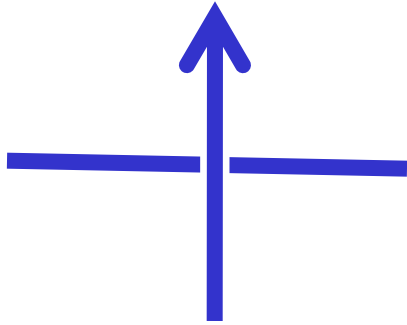


if leftward ...

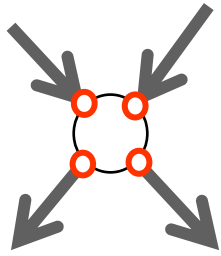
then leftward

planar crossover gadget

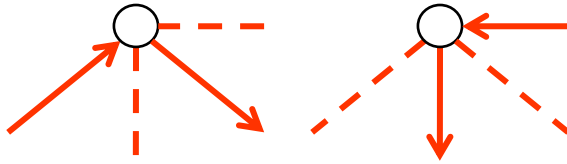
formal proof Lemma 5.10



bounded NCL half-crossover

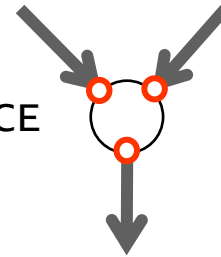


to be replaced

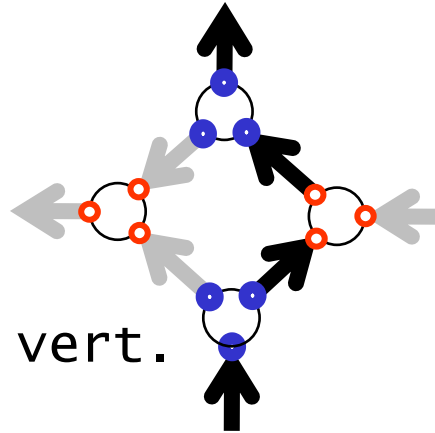
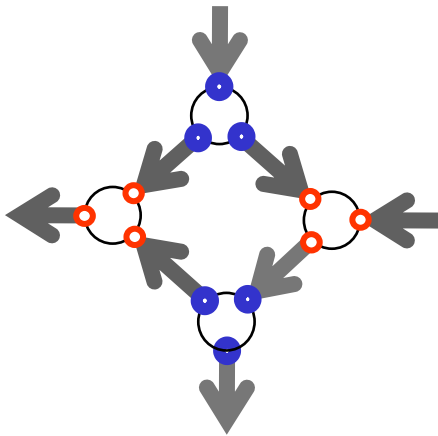
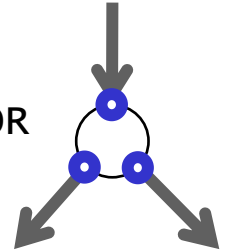


restricted behaviour

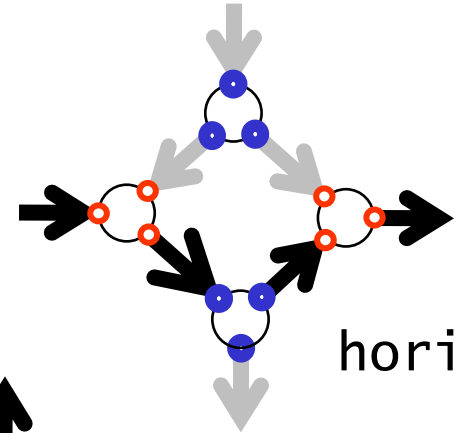
CHOICE



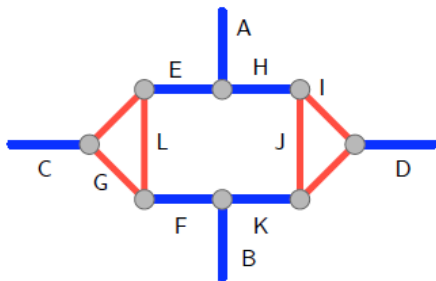
OR



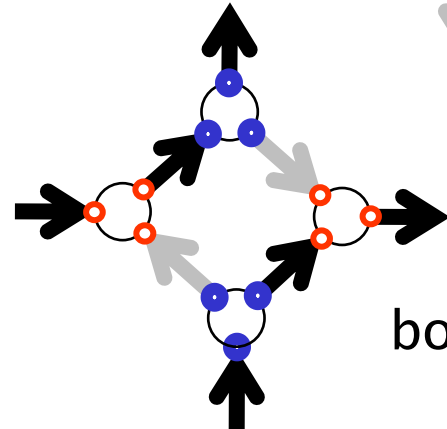
vert.



hori.



(b) Half-crossover

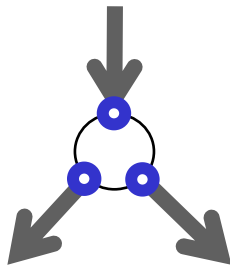


both

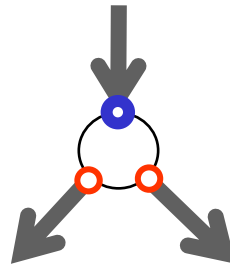
race condition

half-crossover *bounded ncl* type

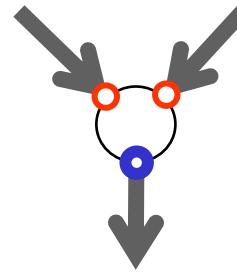
conclusion (planar BNCL)



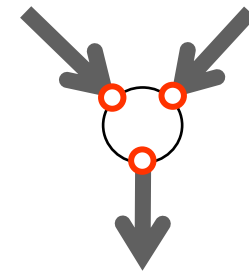
OR



AND



FANOUT



CHOICE

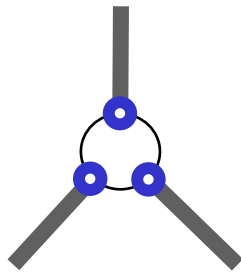
BOUNDED NCL - nondet constraint logic

instance: constraint graph G , edge e

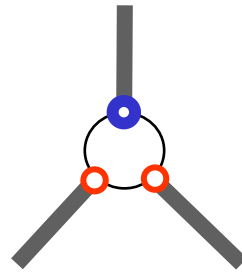
question: sequence which reverses *each edge at most once*, ending with e

Bounded NCL is NP-complete,
even for planar graphs,
with restricted vertices

conclusion (planar NCL)



OR



AND

NCL - nondet constraint logic

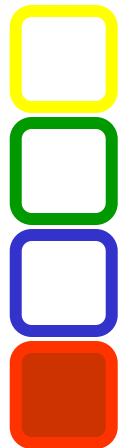
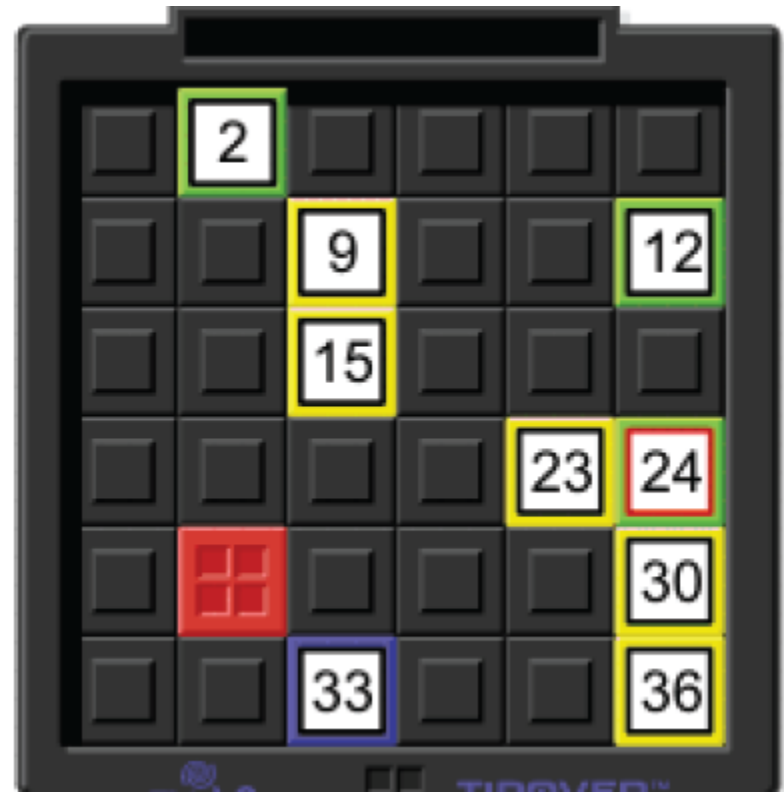
instance: constraint graph G , edge e

question: sequence which reverses e

NCL is PSPACE-complete,

*even for planar graphs,
with restricted vertices*

application: TipOver



2

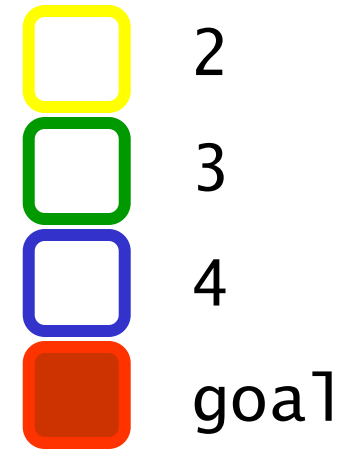
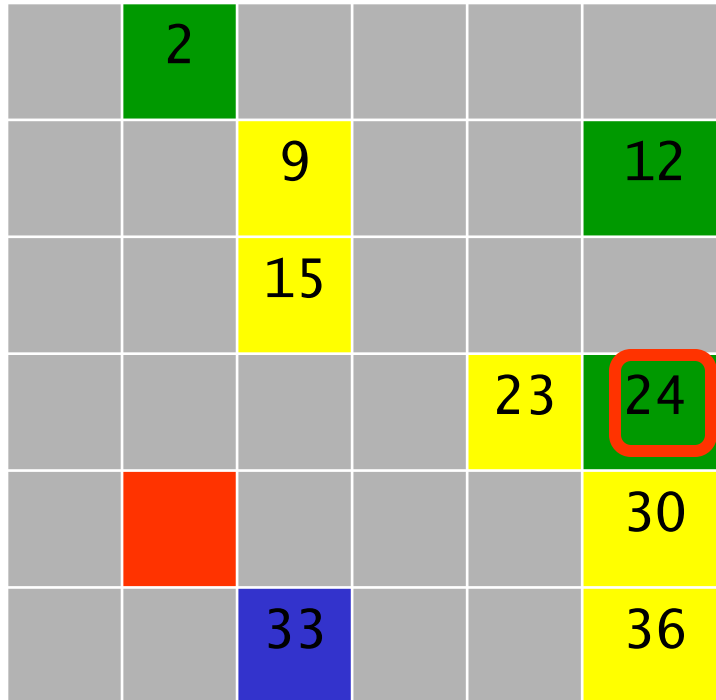
3

4

goal

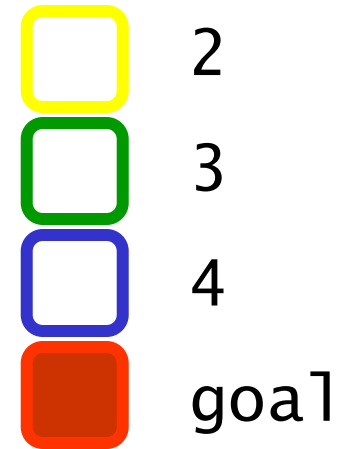
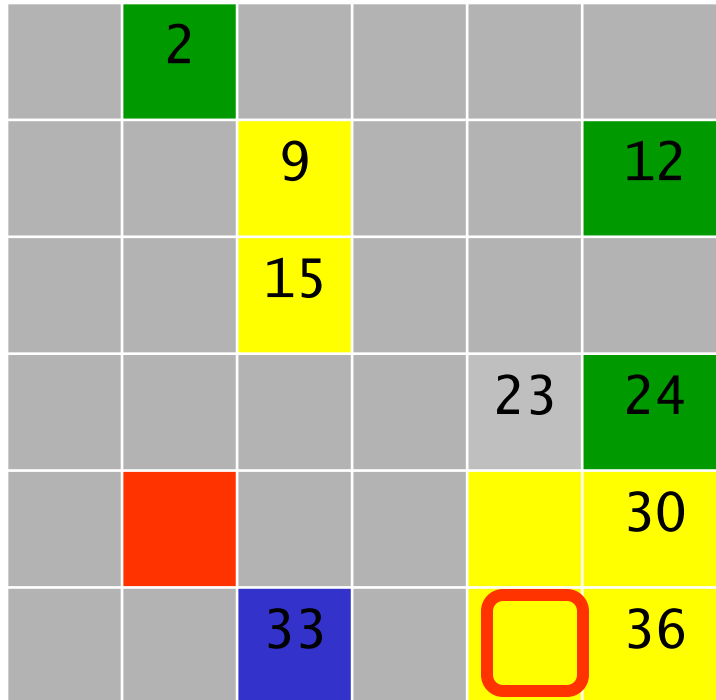
24 initial position

solution advanced



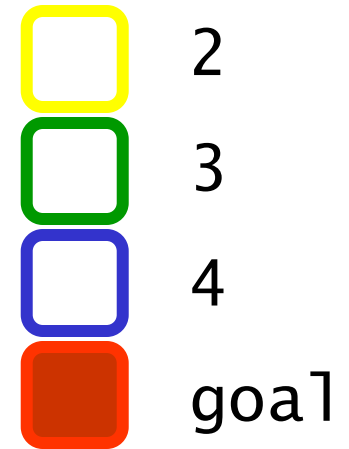
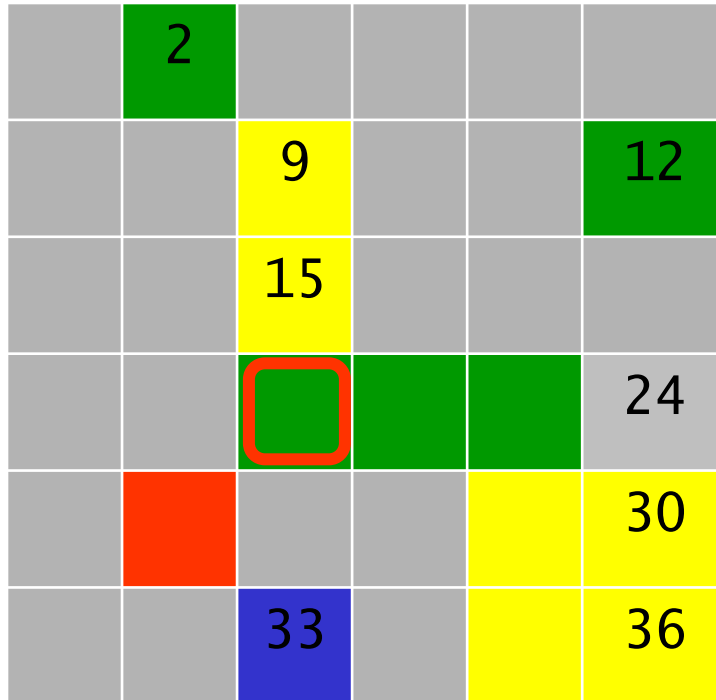
23D, 24L, 30U, 9R, 15U, 2D

solution advanced



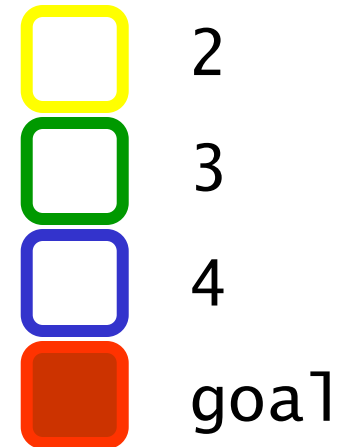
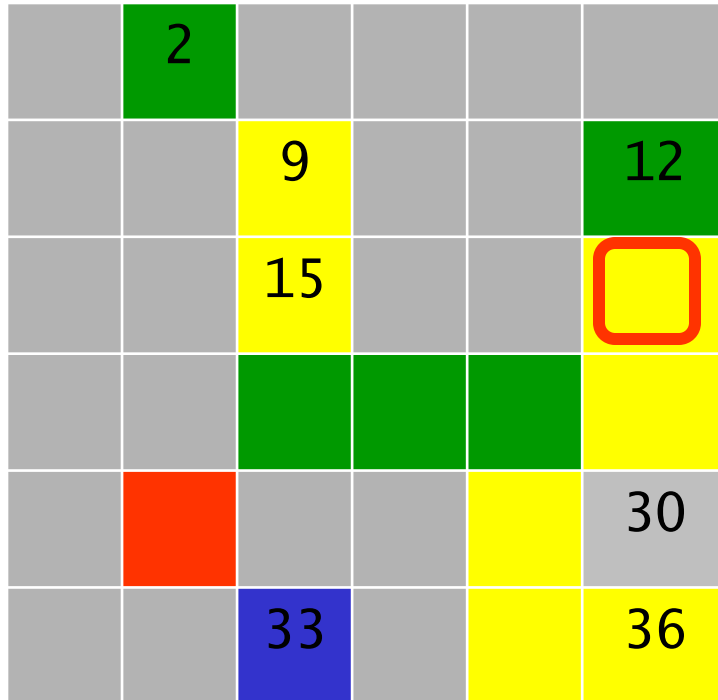
23D, 24L, 30U, 9R, 15U, 2D

solution advanced



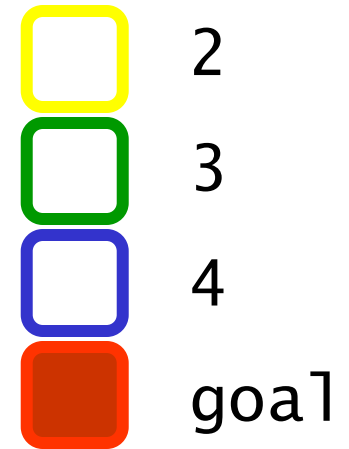
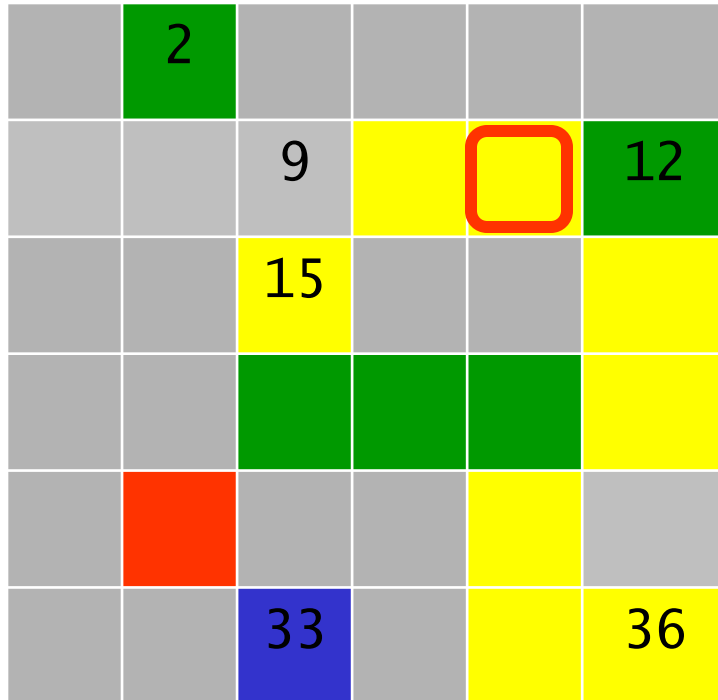
23D, 24L, 30U, 9R, 15U, 2D

solution advanced



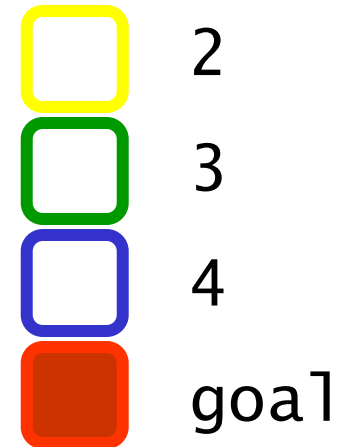
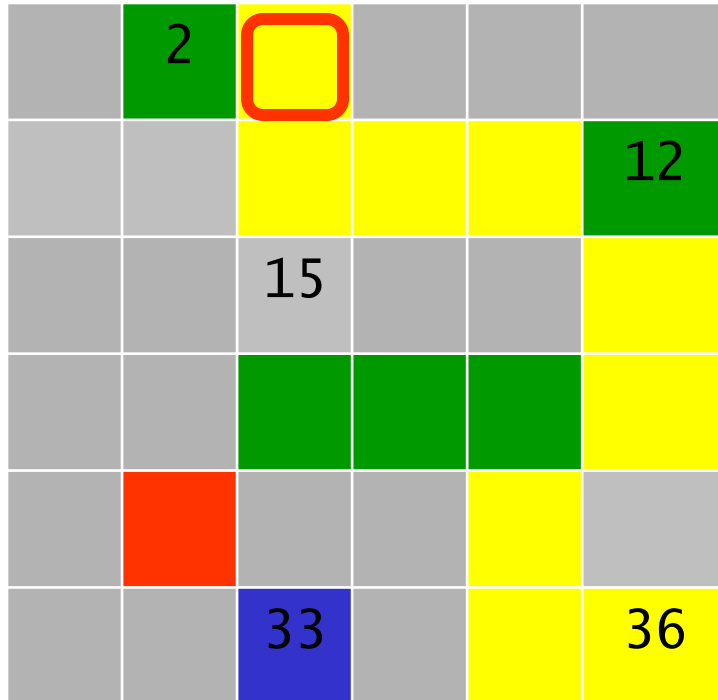
23D, 24L, 30U, 9R, 15U, 2D

solution advanced



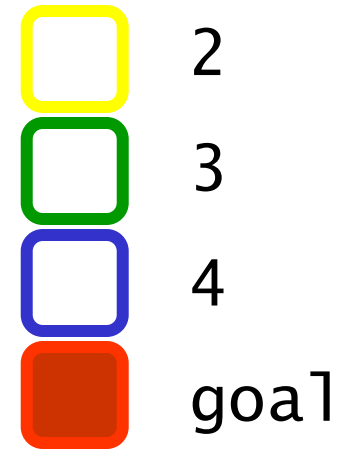
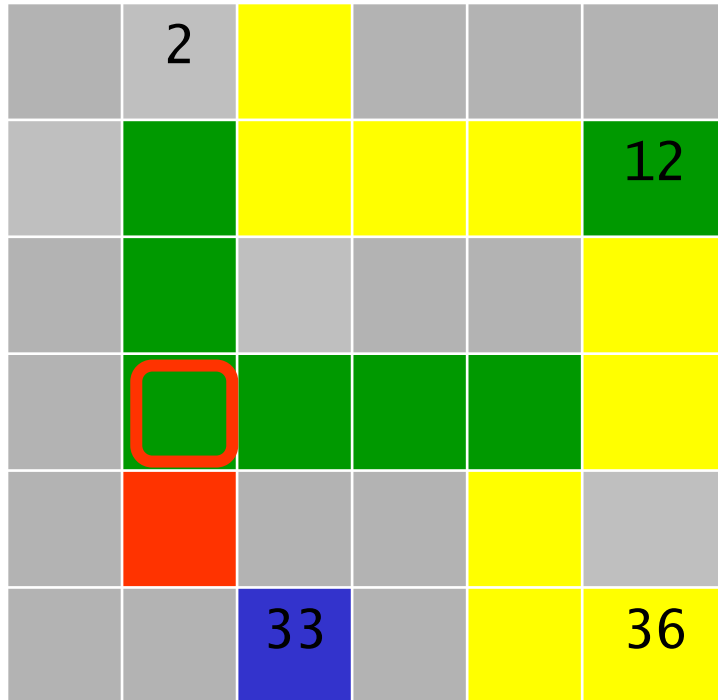
23D, 24L, 30U, 9R, 15U, 2D

solution advanced



23D, 24L, 30U, 9R, 15U, 2D

solution advanced



23D, 24L, 30U, 9R, 15U, 2D

□ 2

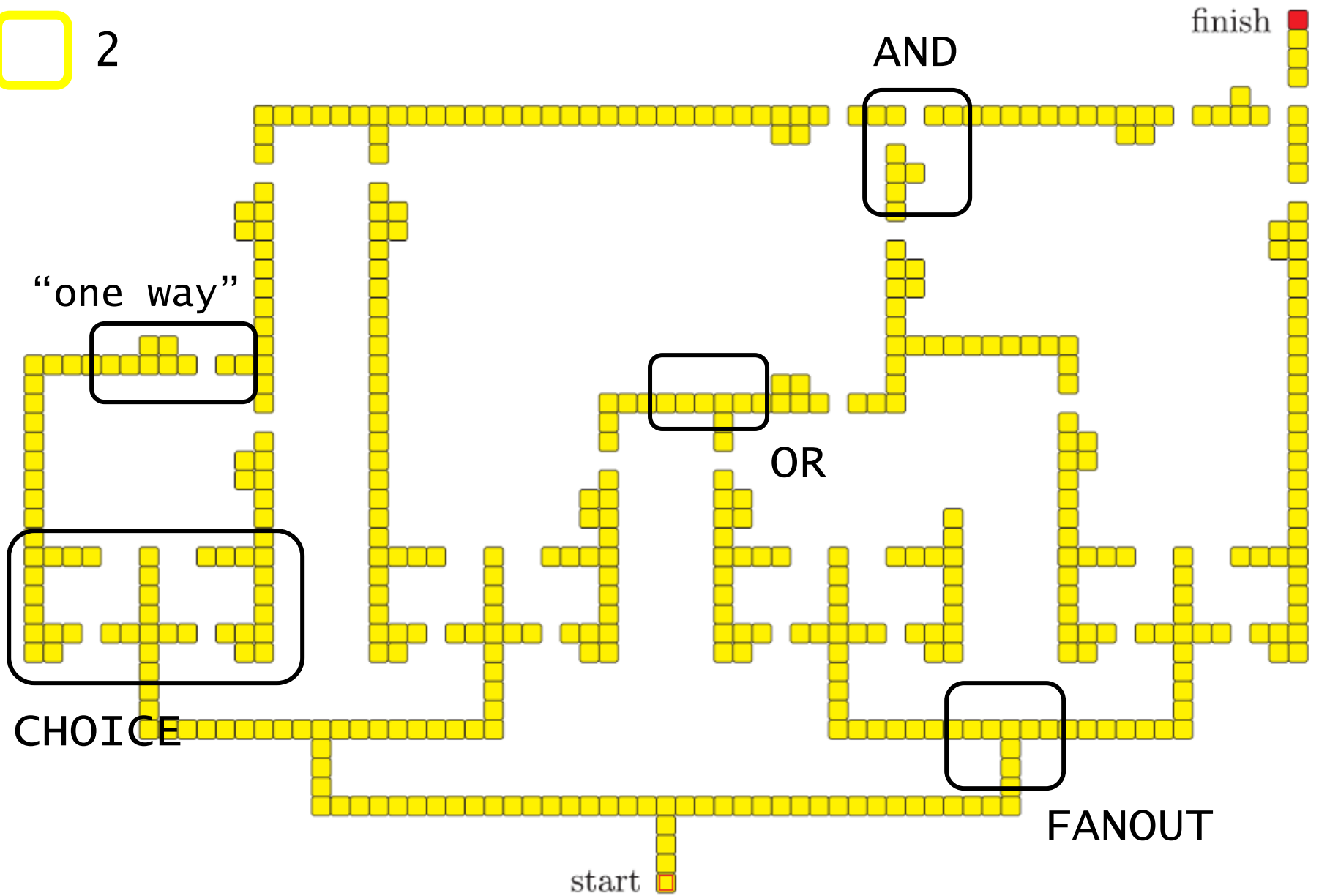


Figure 9-7: TipOver puzzle for a simple constraint graph.

gadgets: “one way”, OR

invariant:

- can be reached \Leftrightarrow can be inverted
- all visited positions remain connected

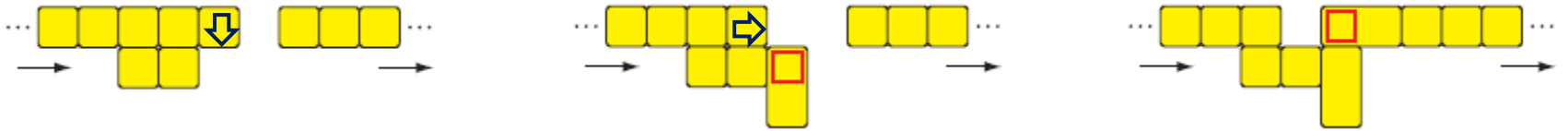
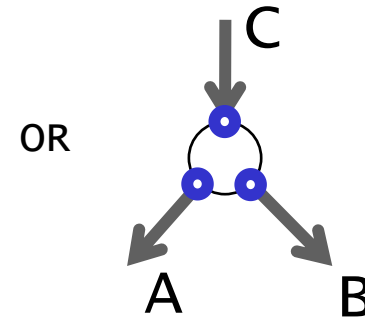
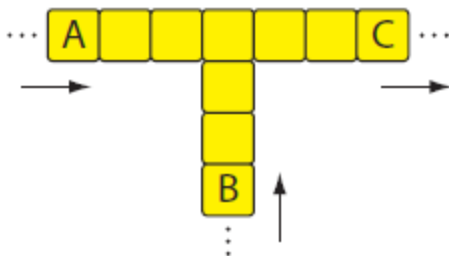
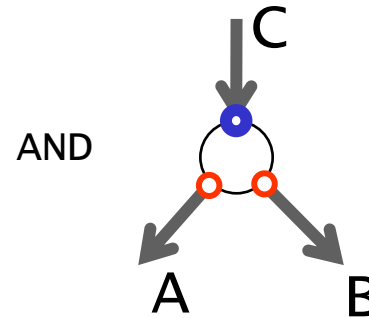
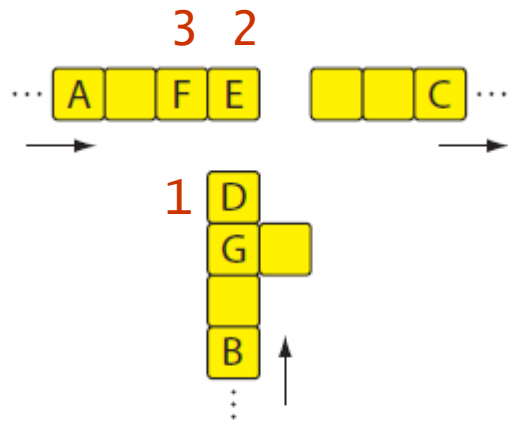


Figure 9-3: A wire that must be initially traversed from left to right. All crates are height two.



(a) OR gadget. If the tipper can reach either A or B, then it can reach C.

gadgets: AND



(b) AND gadget. If the tipper can reach both A and B, then it can reach C.

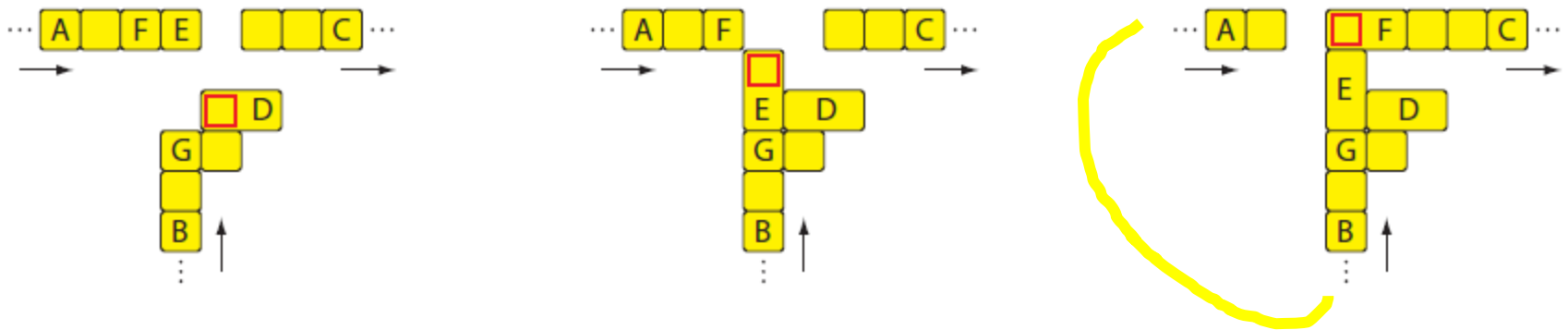


Figure 9-5: How to use the AND gadget.

remains connected

gadgets: CHOICE, FANOUT

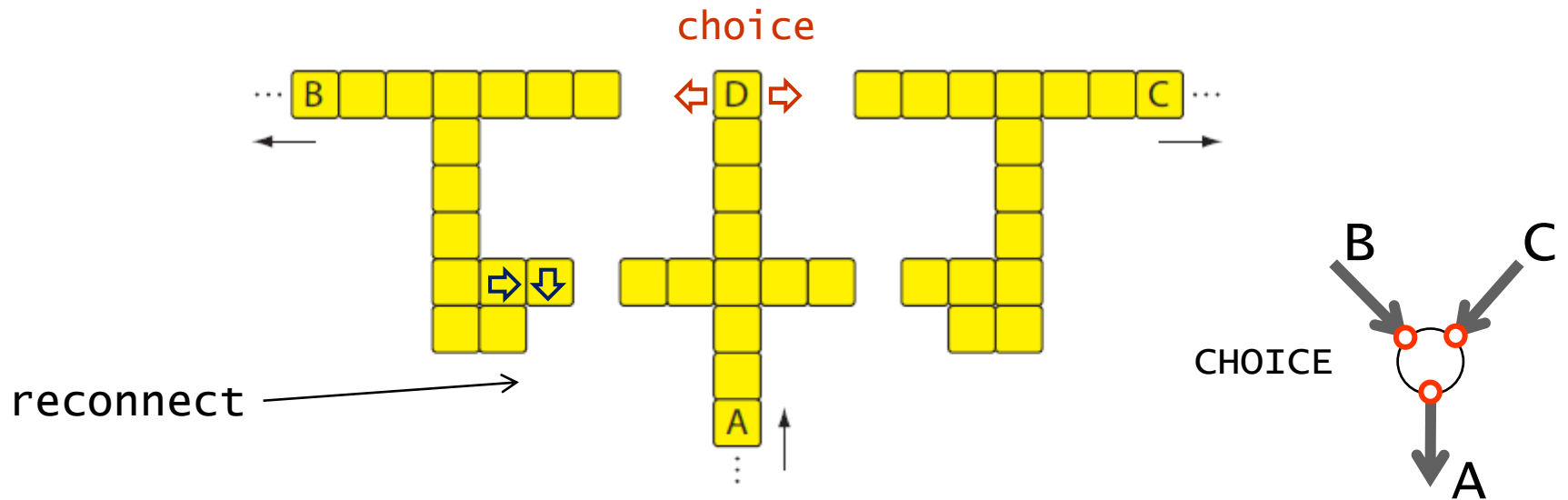
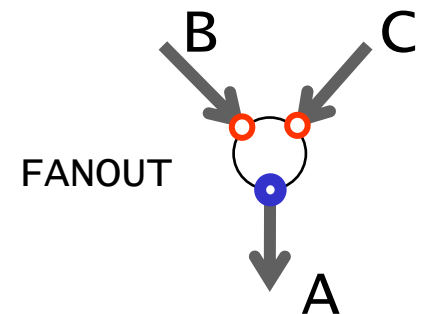
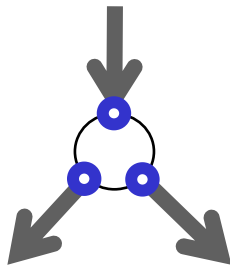


Figure 9-6: TipOver CHOICE gadget. If the tipper can reach A, then it can reach B or C, but not both.

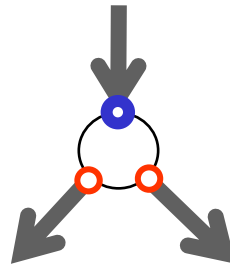
use one-way gadgets at B and C
(control information flow)



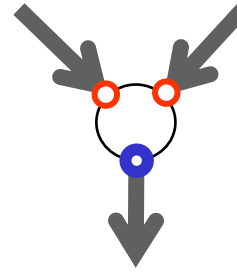
conclusion



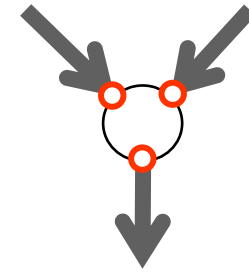
OR



AND

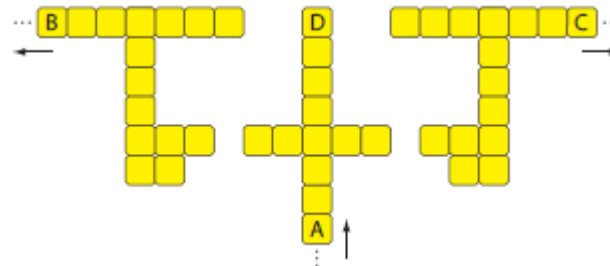


FANOUT



CHOICE

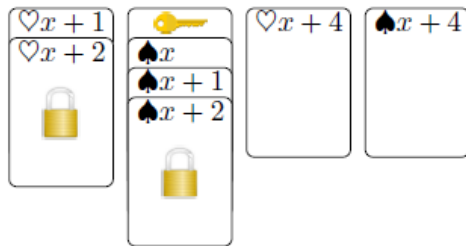
Bounded NCL is NP-complete,
even for planar graphs,
with above restricted vertices



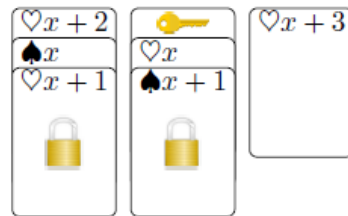
thm. TipOver is NP-complete

NP complete bounded games

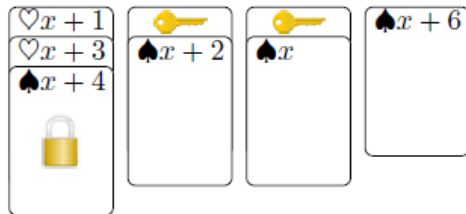
Jan van Rijn: Playing Games:
 The complexity of **klondike**, **Mahjong**, **Nonograms**
 and **Animal Chess**
 (Master Thesis, 2013, Leiden)



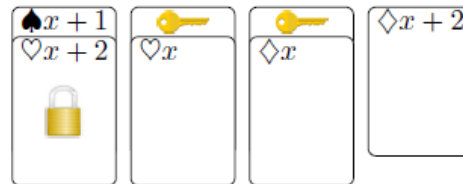
(a) AND gadget



(b) OR gadget



(c) FANOUT gadget



(d) CHOICE gadget



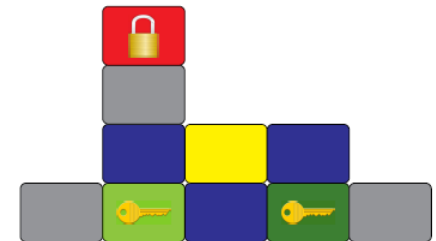
(a) AND gadget



(b) OR gadget



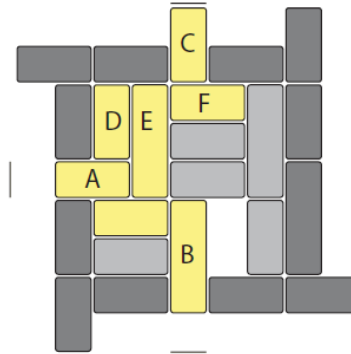
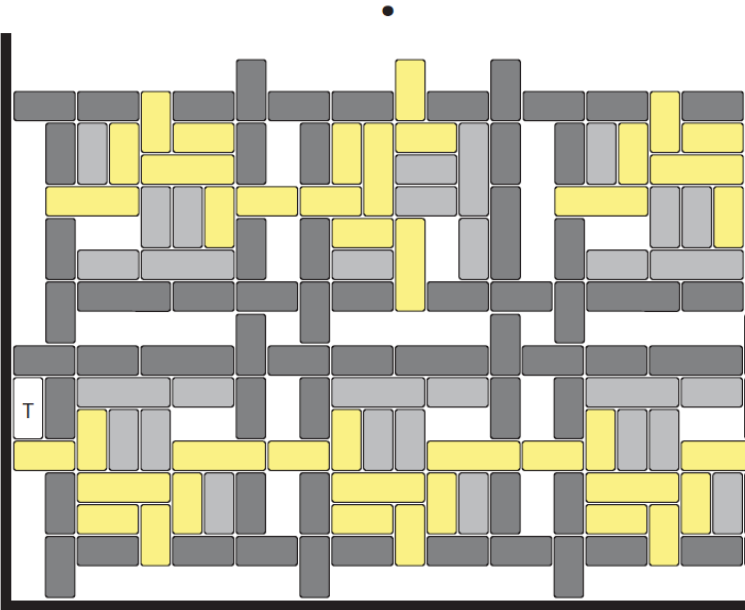
(c) FANOUT gadget



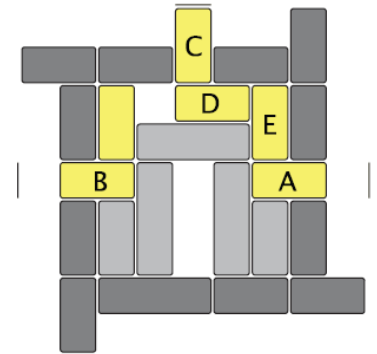
(d) CHOICE gadget

Rush Hour and Plank puzzle are
PSPACE-complete

rush hour

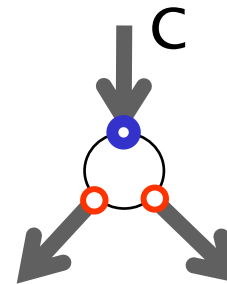


(b) AND

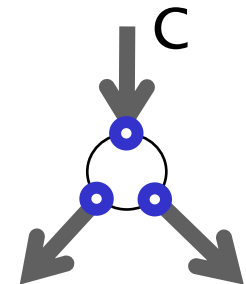


(c) Protected OR

car in \Leftrightarrow edge out

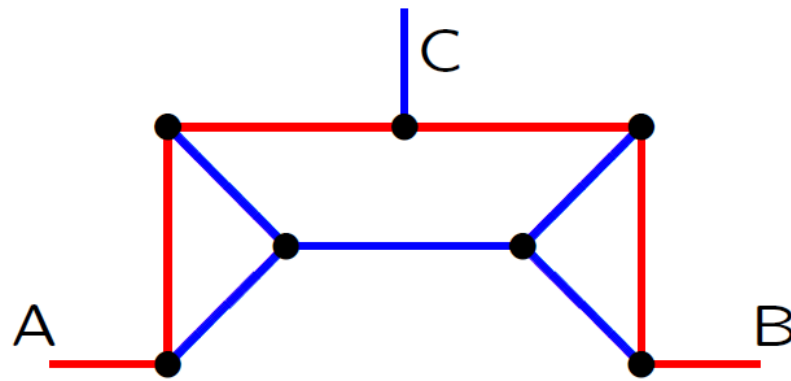
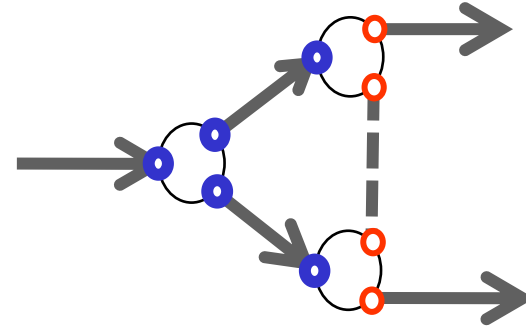
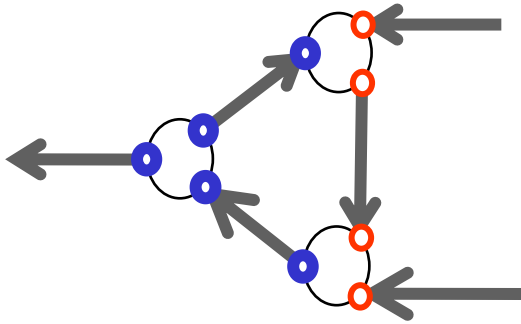


AND

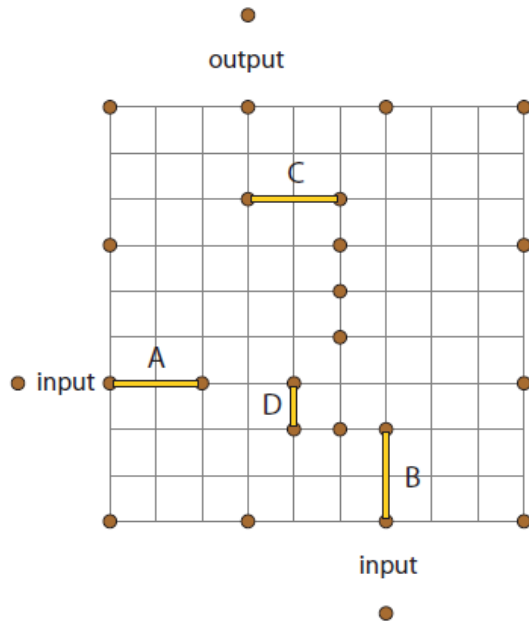
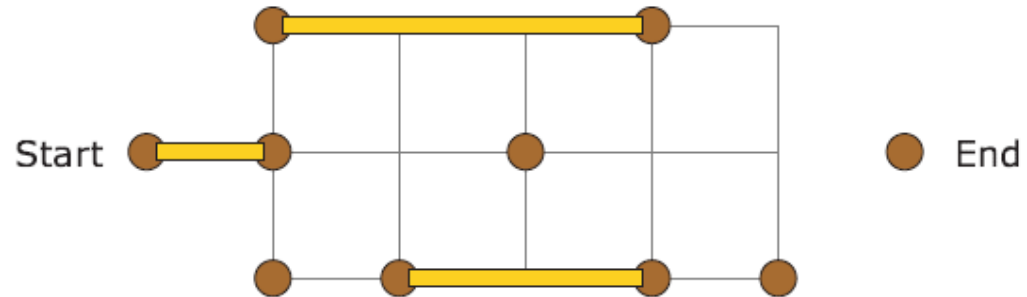


OR

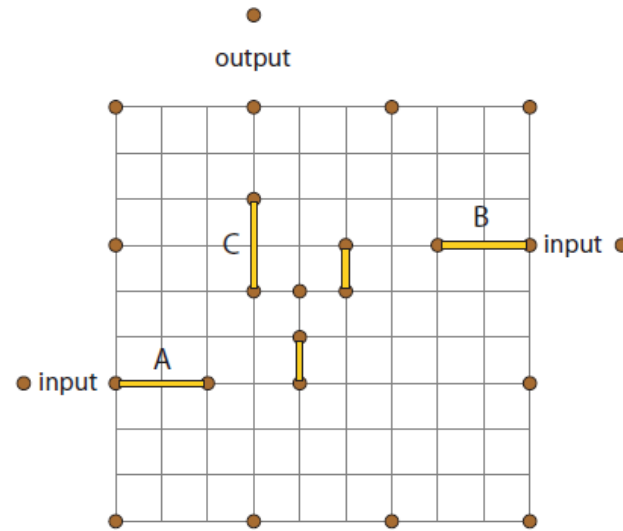
Latch / protected OR



plank puzzle

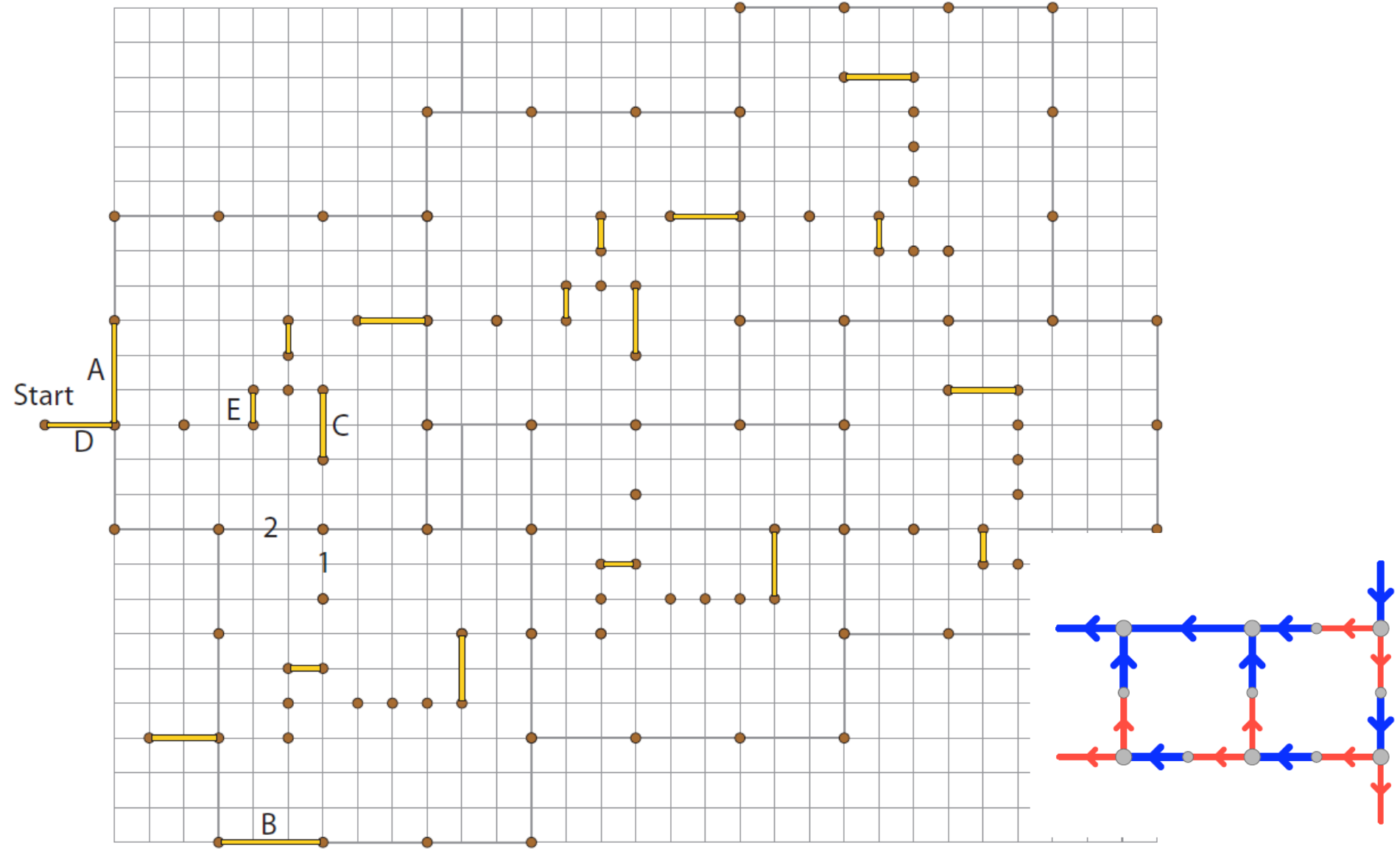


(a) AND



(b) OR

• End



Wrap Up

conclusion

conclusion: nice uniform family of graph games, suitable for the various game classes

not in this presentation:

deterministic classes are hard to prove complete: timing constraints

bounded det. ncl

has no known planar normal form

2pers. games need two types of edges (apart from colours), for each of the players

for teams one needs hidden info, otherwise equivalent to 2p games

roots can be found in the literature
(see [Geography](#))

take care: game of life (what is the 'goal'?)
is PSPACE, it also is undecidable 😊
(on infinite grid)

example of P-complete:
the domino toppling simulation

geography

[Schäfer, J.CSS, 1978]

THM. Geography is PSPACE-complete

two players on directed graph
alternately pick next vertex,
without repetition

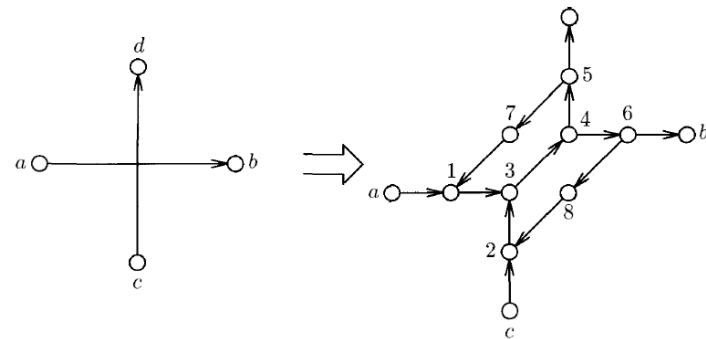
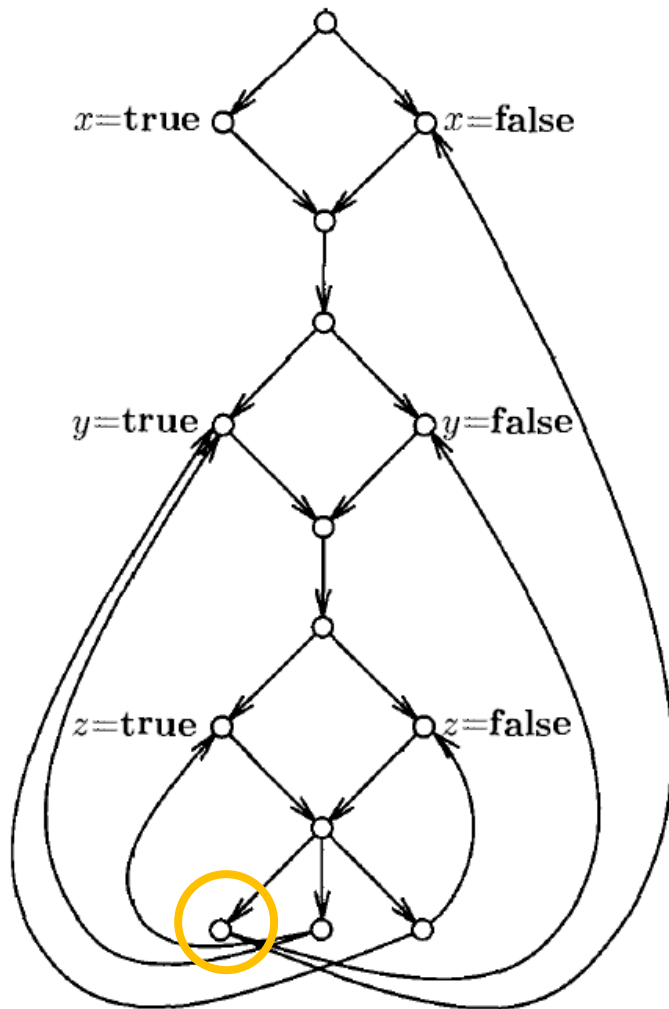


Figure 19-4. Crossing edges in GEOGRAPHY.

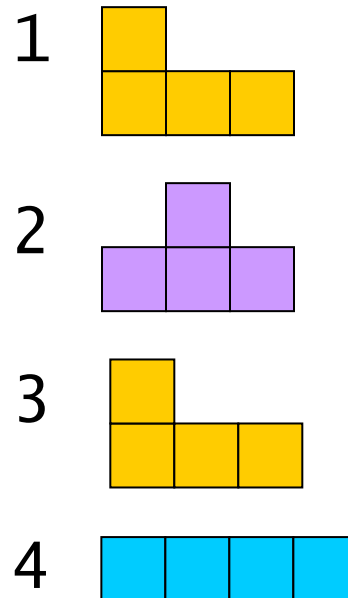
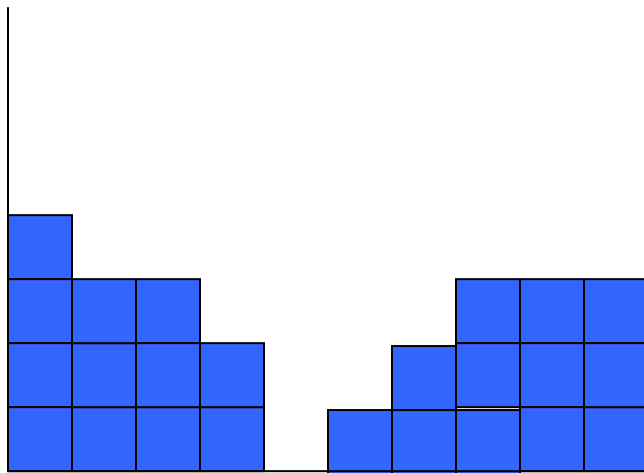
application to GO

[Lichtenstein&Sipser, J.ACM, 1980]

$$\exists x \forall y \exists z [(\neg x \vee \neg y) \wedge (y \vee z) \wedge (y \vee \neg z)].$$

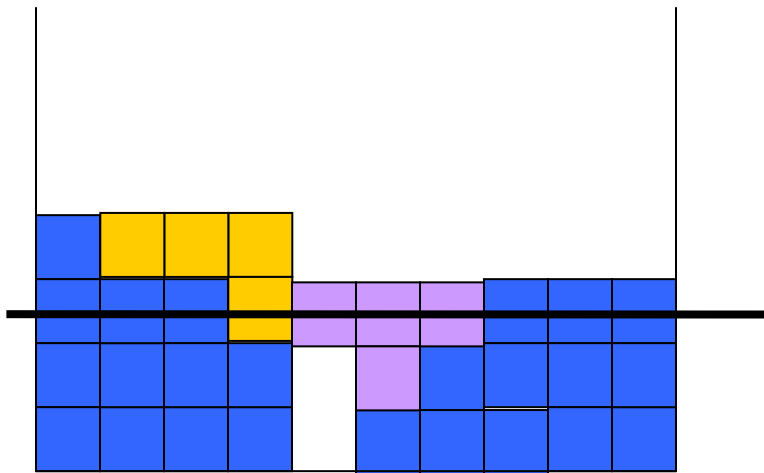
Tetris is NP complete

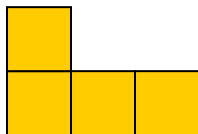
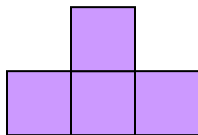
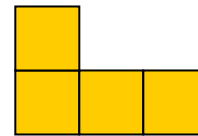

“Given an initial game board and a sequence of pieces, can the board be cleared?”



Tetris is NP complete

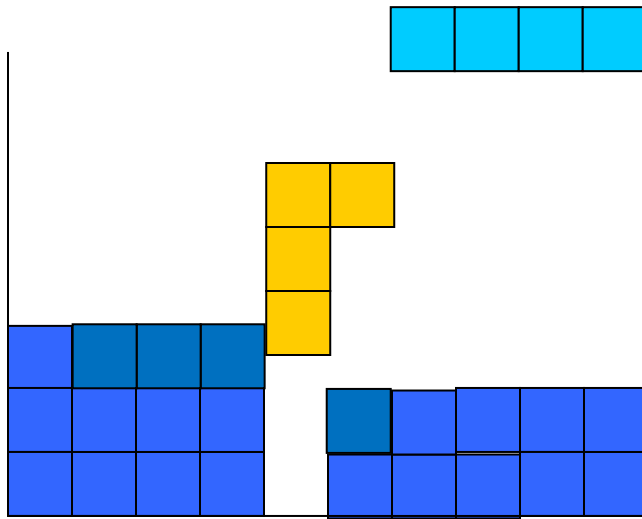
“Given an initial game board and a sequence of pieces, can the board be cleared?”

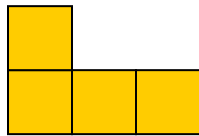
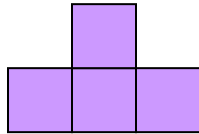
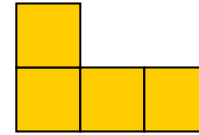



- 1  ✓
- 2  ✓
- 3 
- 4 

Tetris is NP complete

“Given an initial game board and a sequence of pieces, can the board be cleared?”



- 1  ✓
- 2  ✓
- 3  ✓
- 4  ✓

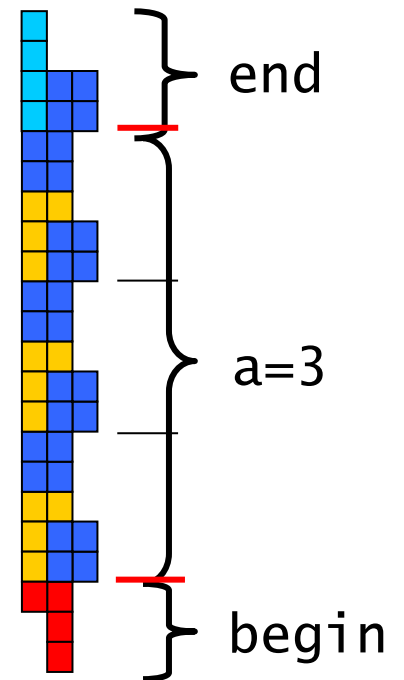
yes!

Tetris is NP complete

reduction from 3-partitioning problem
(can we divide set of numbers into triples?)

OPEN: directly with Bounded NCL ?

find OR, AND, FANOUT, CHOICE




Game Complexity

**IPA Advanced Course on
Algorithmics and Complexity**

Eindhoven, 25 Jan 2019

Walter Kusters
Hendrik Jan Hoogeboom

LIACS, Universiteit Leiden



Cook, Stephen (1971). "The complexity of theorem proving procedures".
Proceedings of the Third Annual ACM Symposium on Theory of Computing.
pp. 151–158.

<http://portal.acm.org/citation.cfm?coll=GUIDE&dl=GUIDE&id=805047>.

Provably difficult combinatorial games, L. J. Stockmeyer and A. K. Chandra,
SIAM J. Computing 8 (1979), pp. 151-174.

N.D. Jones, W.T. Laaser, Complete Problems for Deterministic Polynomial Time,
TCS 3: 105-117, 1977.

Chandra, Ashok K.; Kozen, Dexter C.; Stockmeyer, Larry J. (1981).
"Alternation". *Journal of the ACM*. 28 (1): 114-133